HEIGHT MAP GENERATION WITH GPU’s

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FRACTALS

- Self-Similarity
- Fine structure at arbitrarily small scales
- Simple and recursive definition
- Everywhere in nature – snowflakes, clouds, mountain ranges, lightning bolts and even in vegetables!
SELF SIMILARITY

The “simple” part is exaggerated!

Recursion perfectly captures the self-similarity of fractals

Usually generated in a complex plane

Escape-time; Iterated functions; Random fractals; Strange attractors; L-systems

Julia set, Mandelbrot set, Nova fractal, Sierpinski carpet, Koch snowflake, Brownian Tree
APPLICATION OF FRACTALS

- Lossy compression (sounds and images)
- Seismology
- Fractal antennas
- Computer network design
- Fractal landscape generation
- Financial analysis
- Computer graphics
- Art
MANDELBROT SET

- A visualization of an iterative function in a complex plane
- \( y(z) = z^2 + c \)
- \( c \) is used as a bounding constant to ensure that \( y(z) \) does not exceed that value as we perform an increasing number of iterations
- Fine detail even on infinite magnification
TERRAIN MAPPING

- Used to generate mountainous or futuristic terrain
- Practical use in the entertainment/graphics sector
- Far Cry 2, Left4Dead, .kkrieger, Borderlands, Diablo

MID POINT DISPLACEMENT ALGORITHM

- Take a line segment on the X-axis
- Calculate the mid-point of the segment
- Add some random noise to generate the y co-ordinate
- Reduce the range of the random noise
- Recursively call the above steps for all the line segments
DIAMOND SQUARE ALGORITHM

Source: http://gameprogrammer.com/fractal.html#diamond
PROBLEMS

- The number of squares increases exponentially after every round
- $2^{X+2}$ squares after $X$ iterations
- Large terrains require a huge number of calculations
GOALS

- Write a Mandelbrot set visualization program using CUDA/C
  - Generate the elements of a Mandelbrot set
  - Visualize them using OpenGL

- Create a random terrain map generation program using CUDA/C
  - Generate random height maps using fractals
  - Visualize them using OpenGL/pass height maps as inputs to existing 3D renderers
APPROACH

- Divide and Conquer!
- Assign a thread/block/processor to each individual pixel value that needs to be calculated
- Run the fractal generation/diamond square algorithm
- Because the number of pixels to be calculated differs in each step for DS, dynamically allocate
- CUDA did not support recursive device calls for < CUDA 3.1 (roughly compute capability 2.0)
CUDA ABSTRACTION FOR DEVELOPERS

Figure 2-1. Grid of Thread Blocks

Source: CUDA C Programming Guide
Though GPU’s inherently support multi-threading, there are several hardware constraints

Eg: CCR

- Name: Tesla M2050
- CUDA Version: 2.0
- Shared memory per block: 49152
- Total constant memory: 65536
- Regs per block: 32768
- Max threads per block: 1024
- Max threads per dim: 1024,1024,64
- Max grid size: 65535,65535,65535
- Multi processor count: 14
MANDELBROT SET

- Straight-forward implementation
- Challenge was in writing the program in CUDA
- Use varying number of threads and blocks
- Number of blocks dependent on the number of threads
- I learnt the hard way about the hardware limitation on the number of threads
  - \( \text{numBlocks} \times \text{numThreadsPerBlock} \leq \text{maxThreadsPerDim} \)
  - \( \text{numThreadsPerBlock} \leq \text{maxThreadsPerBlock} \)
- Based on input number of threads, dynamically allocating number of blocks to be created by the GPU
- Communication time => Time taken to transfer initial array to GPU or to allocate memory on GPU
- Computation time => Time taken by the GPU to finish computation
HEIGHT MAPS WITH GPU’s

- Sample height map available on the internet
Sample height map from my code
- Flatten the array and pass it to the GPU
- Communication time – Time take to initialize GPU with initial height map with seeded values
- Computation time – Time taken by the GPU to calculate height values for ALL the points in the given 2D array
- Runs
  - Sequential run on CPU
  - Single thread with multiple blocks
  - Single block with multiple threads
  - Multiple blocks with multiple threads
SEQUENTIAL CPU RUN
- The previous image did not use random values in the diamond square algorithm
- Grid size: 1025*1025
- Average running time (with random value generation) was 64.9 ms (100 runs)
- Difference in running on integrated graphics memory vs. dedicated GPU (CCR machine)
- For the parallel runs, number of blocks/threads = dimension of image
- If hardware limit is smaller, assign multiple pixel values to each block/thread
SINGLE THREAD WITH MULTIPLE BLOCKS
(INTEGRATED GRAPHICS MEMORY)
SINGLE THREAD WITH MULTIPLE BLOCKS (CCR)
SINGLE BLOCK WITH MULTIPLE THREADS
(INTEGRATED GRAPHICS MEMORY)
SINGLE BLOCK WITH MULTIPLE THREADS (CCR)
MULTIPLE BLOCKS WITH 4 OR LESS THREADS -
(INTEGRATED GRAPHICS MEMORY)
MULTIPLE BLOCKS WITH 4 OR LESS THREADS - (CCR)
When we have multiple blocks, assign each square step to a single thread

Can’t always launch 4 threads (hardware limitation!)

Based on the maxThreadsPerDim property of the CUDA enabled device

Dynamic creation of threads and blocks maybe creating considerable overhead

Computation time involves some communication (random numbers) to the GPU

Using more advanced features of the GPU – streams, DMA, Shaders, maybe even multiple CUDA enabled devices – might considerably lower the running time
FUTURE WORK

- Make use of 2D CUDA functions like cudaMemcpy2D, cudaMallocPitch etc.
- Utilize advanced features – streams, DMA, Shaders
- Divide into smaller problems of constant size and solve each problem on a separate device in parallel – will help in static assignment of number of threads/blocks
- Use better terrain generation algorithms
- Add rendering code – mesh and full color
QUESTIONS?
SAMPLE HEIGHT MAPS GENERATED
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