

# PARALLEL TRI-DIAGONAL MATRIX SOLVER USING MPI

Final Presentation –  
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# Introduction

Many technical and scientific problems involve the solution of linear systems of equations:

$$QX = Y,$$

where  $Q$  is structured as a block tri-diagonal matrix of order  $n$ :

$$Q = \begin{bmatrix} a_1 & b_1 & 0 & \dots & 0 & 0 & 0 \\ c_2 & a_2 & b_2 & \dots & 0 & 0 & 0 \\ & & & \ddots & & & \\ 0 & 0 & 0 & \dots & c_{n-1} & a_{n-1} & b_{n-1} \\ 0 & 0 & 0 & \dots & 0 & c_n & a_n \end{bmatrix}, \quad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}, \quad y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{bmatrix}.$$

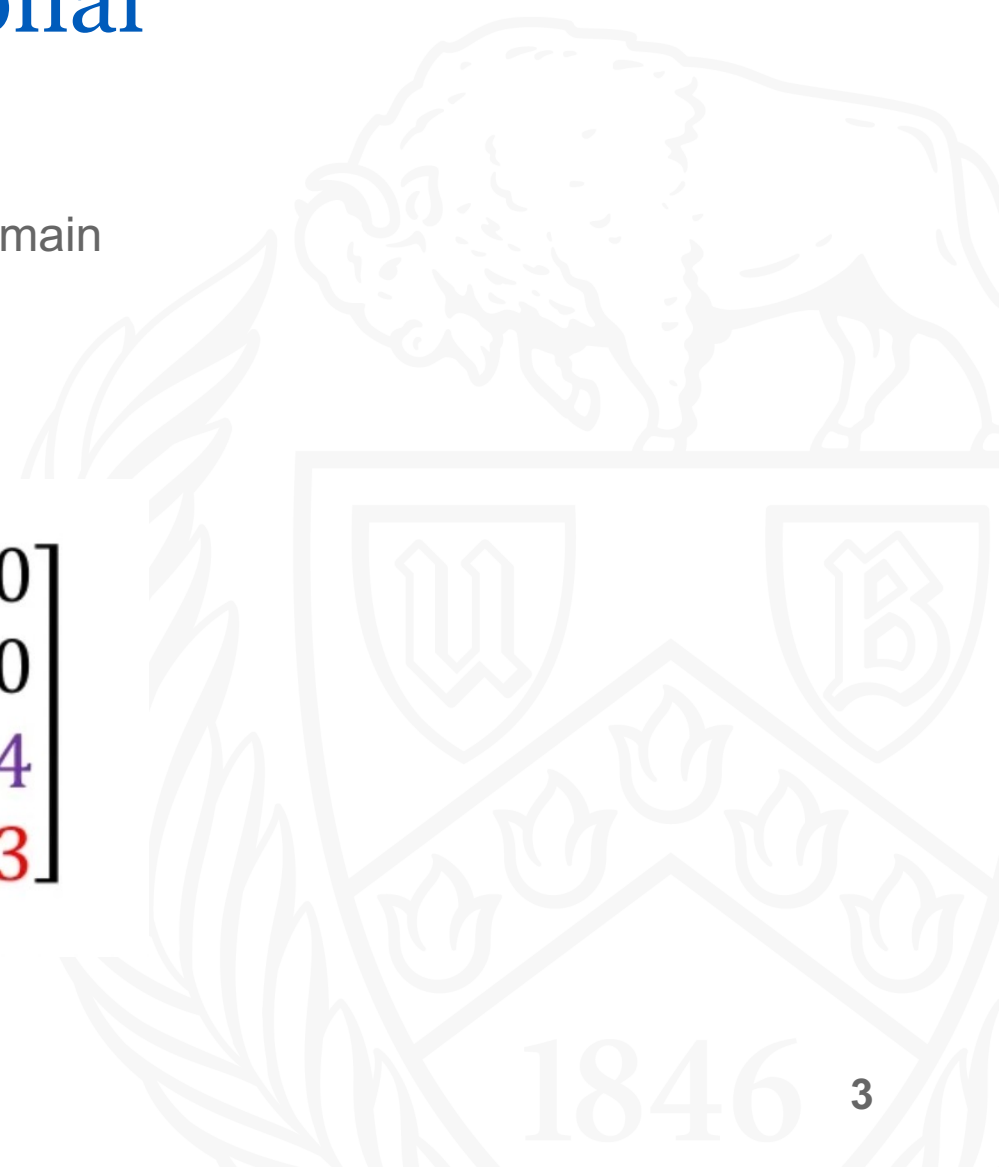
# Introduction – What is a tri-diagonal Matrix ??

A Tri-diagonal matrix is a matrix that has non zero elements on the main diagonal, the sub-diagonal and super-diagonal.

Considering a 4 X 4 Matrix

$$\begin{bmatrix}
 a_1 & b_1 & 0 & 0 \\
 c_2 & a_2 & b_2 & 0 \\
 0 & c_3 & a_3 & b_3 \\
 0 & 0 & c_4 & a_4
 \end{bmatrix}
 \rightarrow
 \begin{bmatrix}
 1 & 4 & 0 & 0 \\
 3 & 4 & 1 & 0 \\
 0 & 2 & 3 & 4 \\
 0 & 0 & 1 & 3
 \end{bmatrix}$$

Source:Wikipedia



# Sequential Method

The Thomas algorithm is an efficient way of solving tridiagonal matrix systems.

It involves following steps :-

- 1) Forward Elimination
- 2) Backward Substitution



# Sequential Method

## 1) Forward Elimination

Iterate through each row in a forward elimination phase, eliminating  $x_1, x_2, \dots, x_{n-1}$ . The last equation will just involve one unknown  $x_n$ . The coefficients at each iteration are calculated as :-

$$\begin{aligned}
 a'_i &= 0 & b'_i &= 1 & c'_1 &= \frac{c_1}{b_1} \\
 c'_i &= \frac{c_i}{(b_i - c'_{i-1}a_i)} & y'_1 &= \frac{y_1}{b_1} & y'_i &= \frac{y_i - y'_{i-1}a_i}{(b_i - c'_{i-1}a_i)}
 \end{aligned}$$

$$\begin{bmatrix} b_1 & c_1 & 0 & 0 & 0 \\ a_1 & b_2 & c_2 & 0 & 0 \\ 0 & a_2 & b_3 & c_3 & 0 \\ 0 & 0 & a_3 & b_4 & c_4 \\ 0 & 0 & 0 & a_4 & b_5 \end{bmatrix}
 \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}
 =
 \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix}$$

# Sequential Method

## 2) Backward Substitution

Iterate back through the matrix solving for x at each row

$$x_i + c_i x_{i+1} = y_i \quad i = 1 \dots n - 1$$

$$x_n = y_n \quad i = n$$

The complexity of is  $O(n)$

$$\begin{bmatrix} b_1 & c_1 & 0 & 0 & 0 \\ a_1 & b_2 & c_2 & 0 & 0 \\ 0 & a_2 & b_3 & c_3 & 0 \\ 0 & 0 & a_3 & b_4 & c_4 \\ 0 & 0 & 0 & a_4 & b_5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix}$$

# Simple Example

Let us consider the system of equations

$$\begin{aligned}
 3x_1 - x_2 + 0x_3 &= -1 \\
 -x_1 + 3x_2 - x_3 &= 7 \\
 0x_1 - x_2 + 3x_3 &= 7
 \end{aligned}$$

Matrix form is

$$\begin{bmatrix} 3 & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 7 \\ 7 \end{bmatrix}$$

- Row 1

$$3x_1 - x_2 = -1$$

Divide the Equation by  $a_1$ , in this case  $a_1 = 3$

$$\Rightarrow x_1 - \frac{1}{3}x_2 = \frac{-1}{3}$$

Assuming the coefficient of  $x_2$  as  $\gamma_1$  and the remaining constants as  $\rho_1$ .  
Now the equations converts to,

$$\Rightarrow x_1 + \gamma_1 x_2 = \rho_1$$



# Simple Example

- Row 2

**Multiplying  $a_2$  (-1) in Row 1 and eliminating  $x_1$  Row 2**

Row 2	$-x_1 + 3x_2 - x_3 = 7$
$a_2$ x Row 1	$-x_1 - \gamma_1 x_2 - 0x_3 = -\rho_1$
Subtracting	$x_2(3 + \gamma_1) - x_3 = 7 + \rho_1$

$$x_2(3 + \gamma_1) - x_3 = 7 + \rho_1$$

Divide by  $(3 + \gamma_1)$ ,

Equation becomes  $x_2 + \gamma_2 x_3 = \rho_2$

$$\gamma_2 = \frac{-1}{3 + \gamma_1} = 0.375 \quad \rho_2 = \frac{7 + \rho_1}{3 + \gamma_1} = 2.5$$





## Simple Example

- Row 3

**Multiplying  $a_3$  (-1) in Row 1 and eliminating  $x_2$  Row 3**

Row 3	$-x_2 + 3x_3 = 7$
$a_3$ x Row 2	$-x_2 - \gamma_2 x_3 = -\rho_1$
Subtracting	$(3 + \gamma_2)x_3 = 7 + \rho_2$

$$x_3 = \frac{7 + \rho_2}{3 + \gamma_2} \Rightarrow \rho_3$$

$$\rho_3 = \frac{7 + \rho_2}{3 + \gamma_2} = 3.619 \Rightarrow x_3 = 3.619$$



# Simple Example

STAGE II -> Backward Substitution

$$\begin{bmatrix} 1 & \gamma_1 & 0 \\ 0 & 1 & \gamma_2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \rho_1 \\ \rho_2 \\ \rho_3 \end{bmatrix}$$

**Row 2:**

$$x_2 + \gamma_2 x_3 = \rho_2$$

$$x_2 = \rho_2 - \gamma_2 x_3$$

*Substituting*

$$\begin{aligned}
 \rho_2 &= 2.5 \\
 \gamma_2 &= -0.375
 \end{aligned}$$

$$x_2 = 3.857$$



# Simple Example

STAGE II -> Backward Substitution

$$\begin{bmatrix} 1 & \gamma_1 & 0 \\ 0 & 1 & \gamma_2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \rho_1 \\ \rho_2 \\ \rho_3 \end{bmatrix}$$

**Row 1:**

$$\begin{aligned}
 x_1 + \gamma_1 x_2 &= \rho_1 \\
 x_1 &= \rho_1 - \gamma_1 x_2
 \end{aligned}$$

*Substituting*

$$\begin{aligned}
 \rho_1 &= -0.333 \\
 \gamma_1 &= -0.333
 \end{aligned}$$

$$x_1 = 0.952$$



# Pseudo Code -

**Input** : matrix size:  $N$ , Vectors  $a[]$ ,  $b[]$ ,  $c[]$  representing the sub-diagonal, main-Diagonal and super-Diagonal of the matrix  $A$  and the forcing vector  $d[]$  here  $i = 0, 1, \dots, N - 1$

**Output:** row vector  $d[i]$  here  $i = 0, 1, 2, \dots, N - 1$

```

 $d_0^* \leftarrow d_0 / b_0$ 
 $c_0^* \leftarrow c_0 / b_0$ 
for  $i = 1, 2 \dots N - 1$  do
    |  $r \leftarrow 1 / (b_i - a_i c_{i-1})$ 
    |  $d_i^* \leftarrow r(d_i - a_i d_{i-1})$ 
    |  $c_i^* \leftarrow r c_i$ 
end
for  $i = (N - 2) \dots 1$  do
    |  $d_i \leftarrow d_i^* - c_i^* d_{i+1}$ 
end
    
```

$$\begin{bmatrix} b_1 & c_1 & 0 & 0 & 0 \\ a_1 & b_2 & c_2 & 0 & 0 \\ 0 & a_2 & b_3 & c_3 & 0 \\ 0 & 0 & a_3 & b_4 & c_4 \\ 0 & 0 & 0 & a_4 & b_5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix}$$

[source: wikipedia](https://en.wikipedia.org/wiki/Tridiagonal_matrix_algorithm)







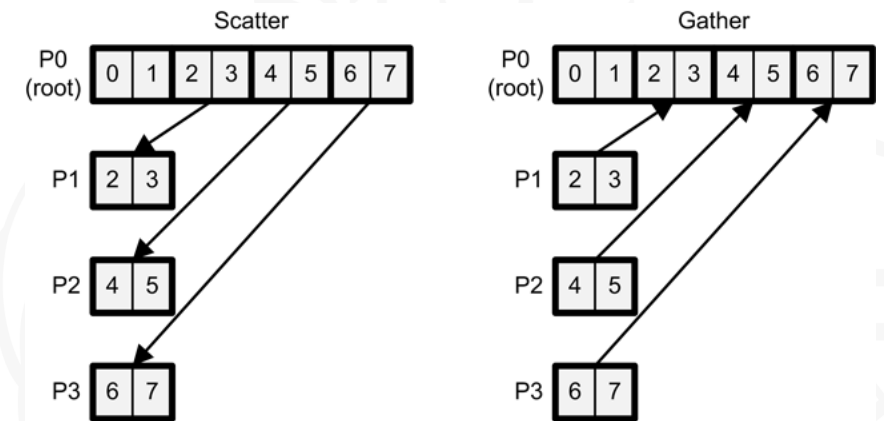




# Parallel Method

Summary:-

1. Every core transforms the partitioned sub-matrices in the tridiagonal systems of equations into the modified forms.
2. Construct a reduced tridiagonal system of equations by collecting the first and last row of every modified sub-matrix, using MPI\_Gather
3. The reduced tridiagonal system constructed in step 2 is solved using the Thomas Algorithm.
4. The solutions of reduced tridiagonal systems in Step 3 are distributed to each core, using MPI\_Scatter
5. Finally, we solve for the remaining unknowns of the modified sub-matrices (Step 1) by using the solutions obtained in Steps 3 and 4.



[source- codeproject.com](http://source-codeproject.com)

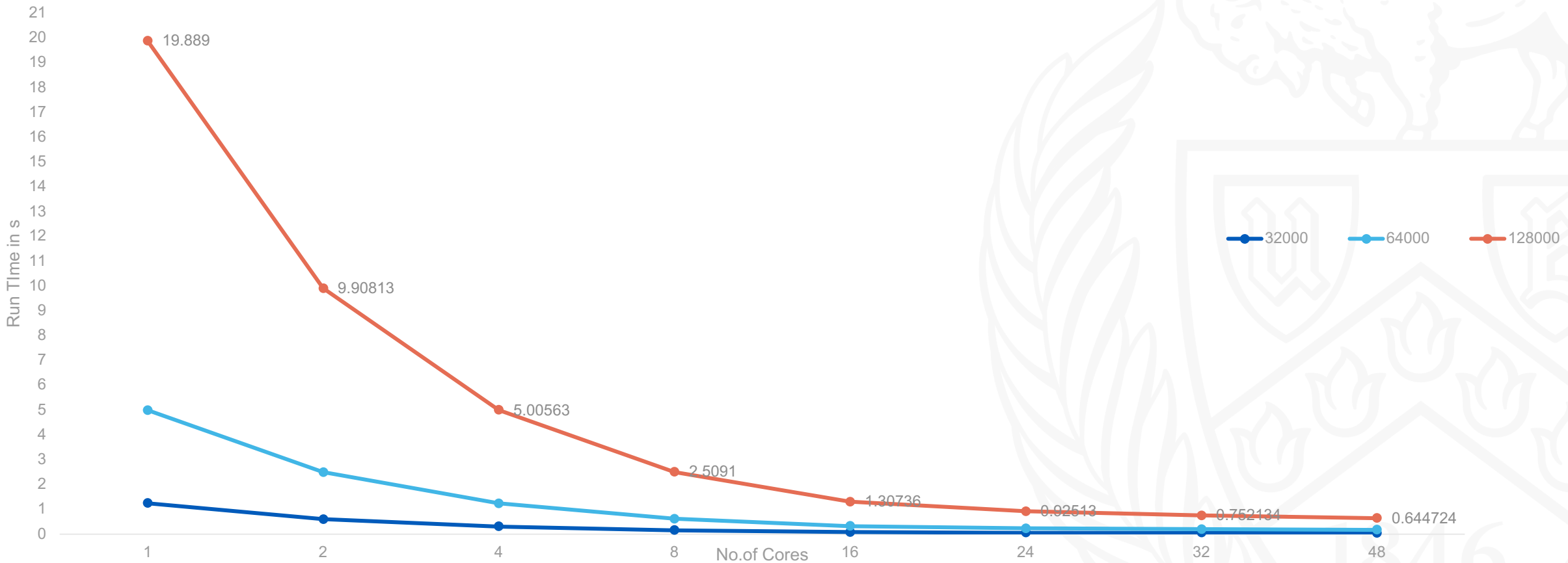
# Results:

The average of time(in seconds) recorded for four runs

N*N(size)	Serial	Procs=2	Procs==4	Procs=8	Procs=16	Procs=24	Procs=32	Procs=48
500	0.00242	0.000204	0.000129	0.000113	0.000137	0.000169	0.000551	0.000315
1000	0.003194	0.000602	0.00034	0.000208	0.000191	0.000229	0.000304	0.000411
2000	0.005477	0.002355	0.001223	0.000703	0.000525	0.001181	0.000602	0.000838
4000	0.0186	0.009305	0.004789	0.00255	0.001605	0.001484	0.001471	0.001763
8000	0.075866	0.037791	0.019273	0.010203	0.006001	0.004951	0.004636	0.004818
16000	0.303937	0.152449	0.077777	0.039812	0.022207	0.017308	0.015984	0.015659
32000	1.24737	0.608305	0.30757	0.156505	0.08398	0.062848	0.054981	0.050052
64000	5.00169	2.49914	1.2428	0.621809	0.325638	0.235615	0.197465	0.173918
128000	19.889	9.90813	5.00563	2.5091	1.30736	0.92513	0.752134	0.644724

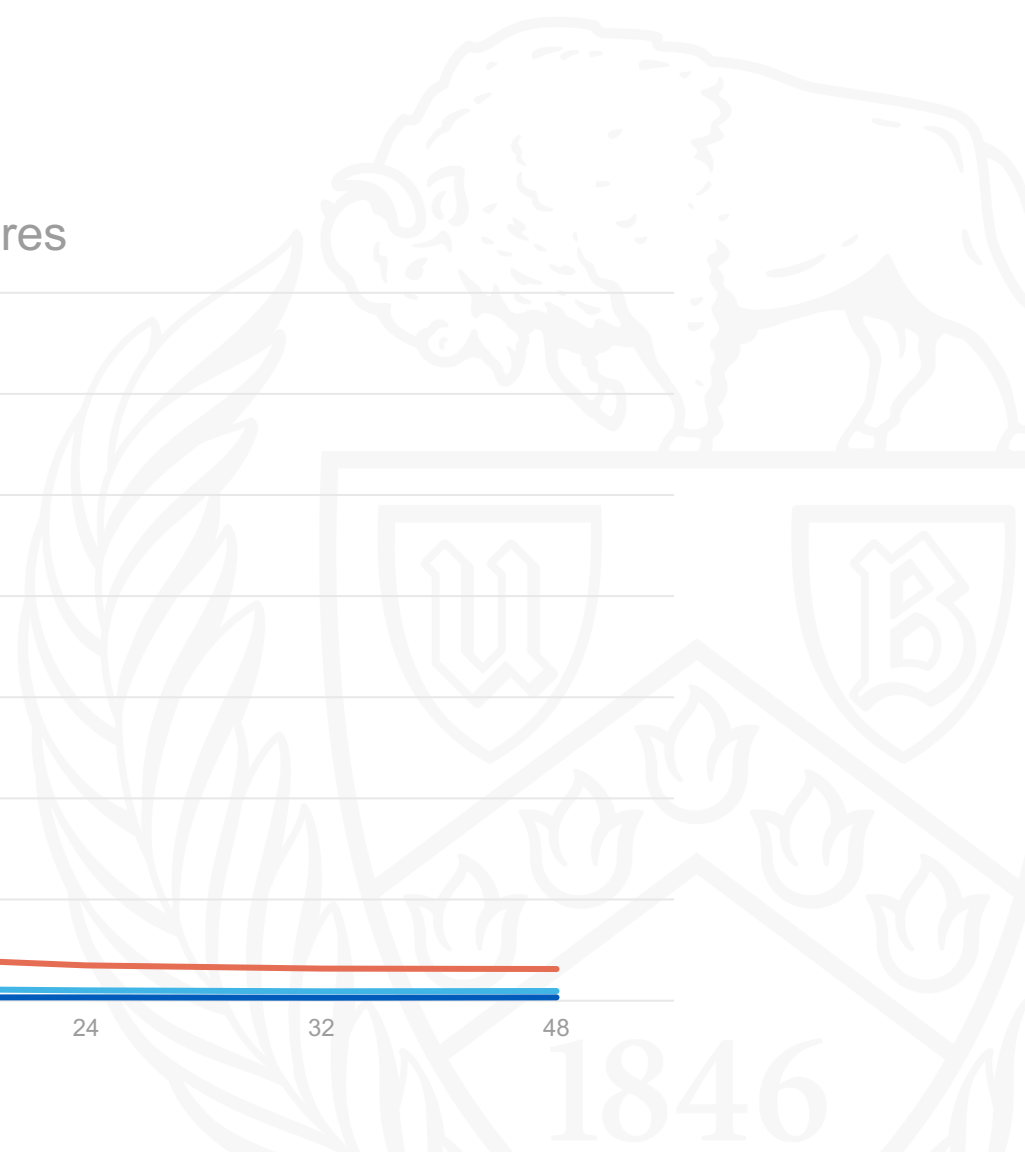
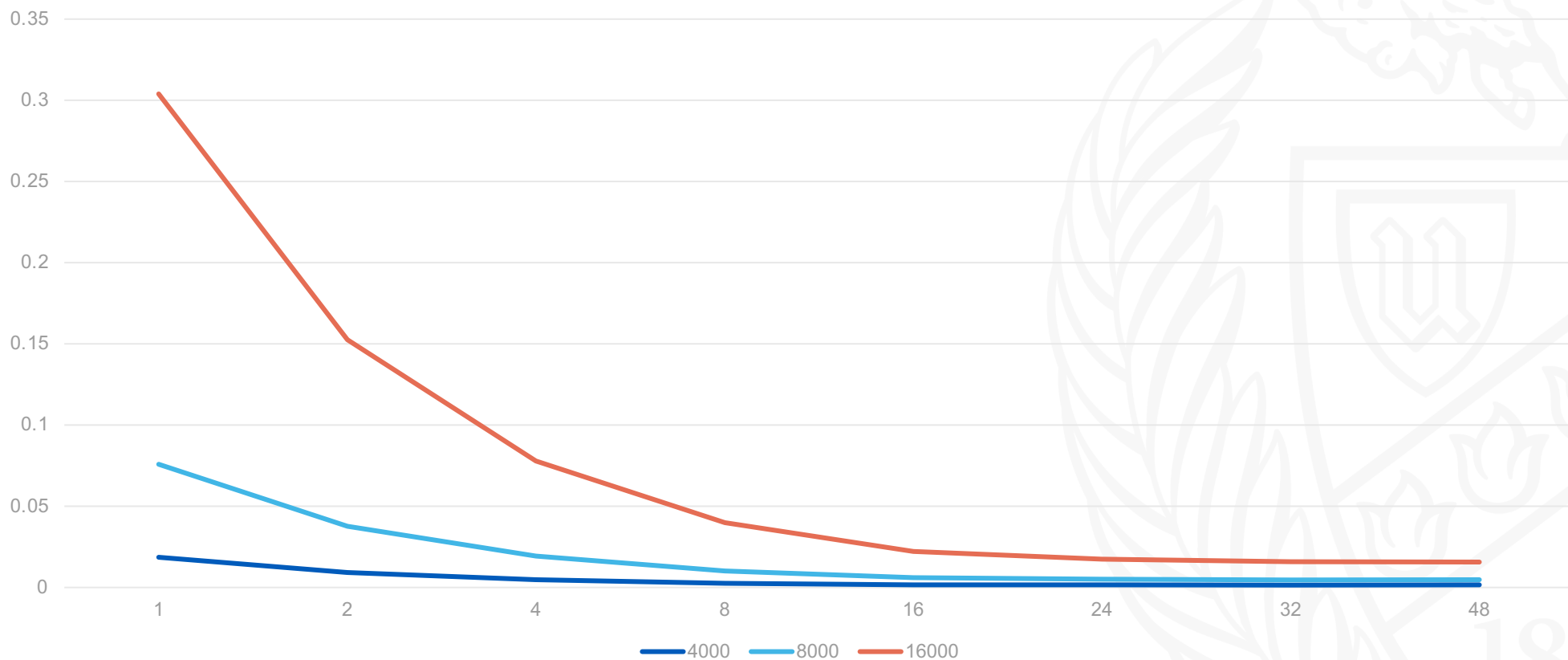
# Graph

## Parallel Run Time vs Number of Cores



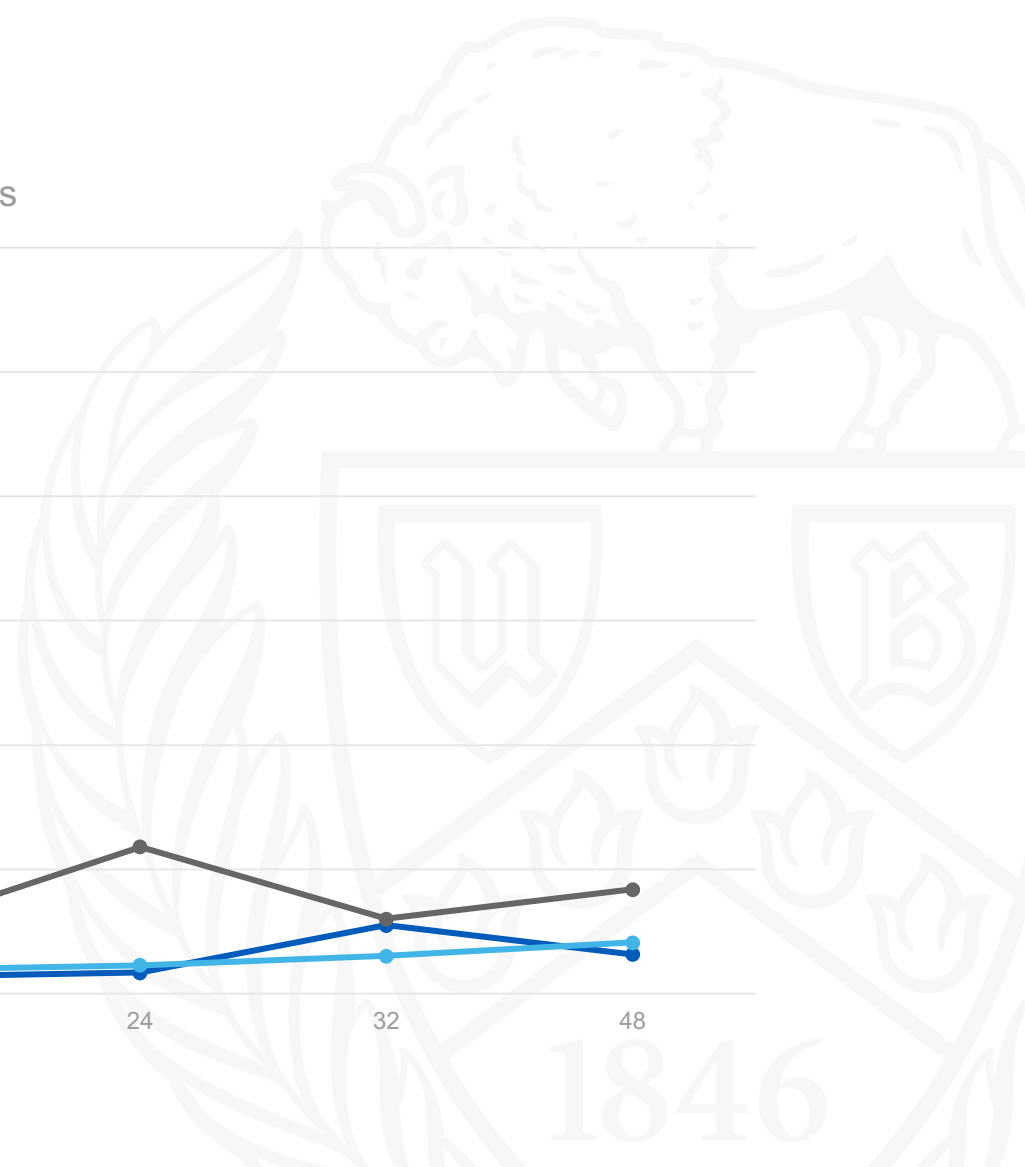
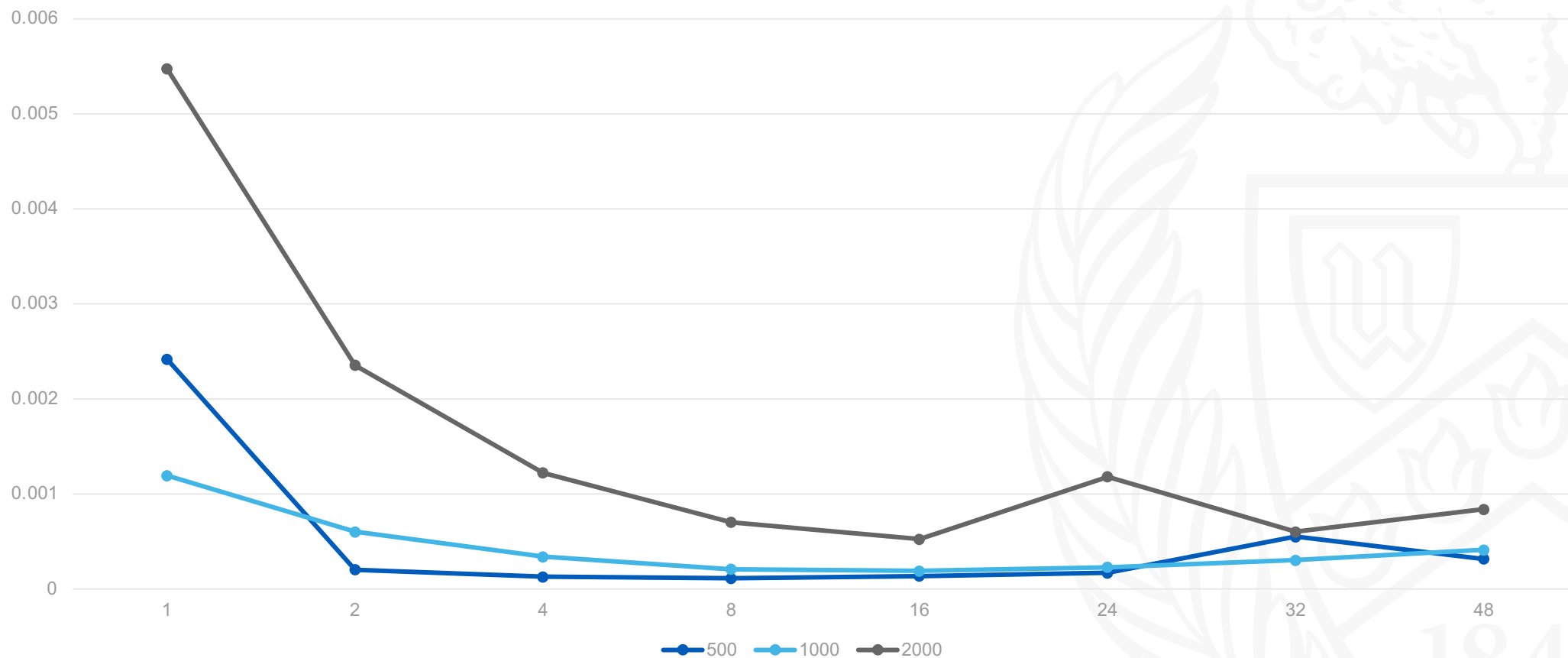
# Graph

Parallel Run Time vs No. of Cores



# Graph

Parallel Run Time vs No. of Cores



## Future Work -

- Calculate Efficiency and Speedup
- Explore more ways to solve Tri-diagonal System



## Reference -

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Thank You !!!

