

# Solving 0-1 KNAPSACK PROBLEM USING CUDA Platform

CSE 708 Seminar: Programming Massively  
Parallel Systems

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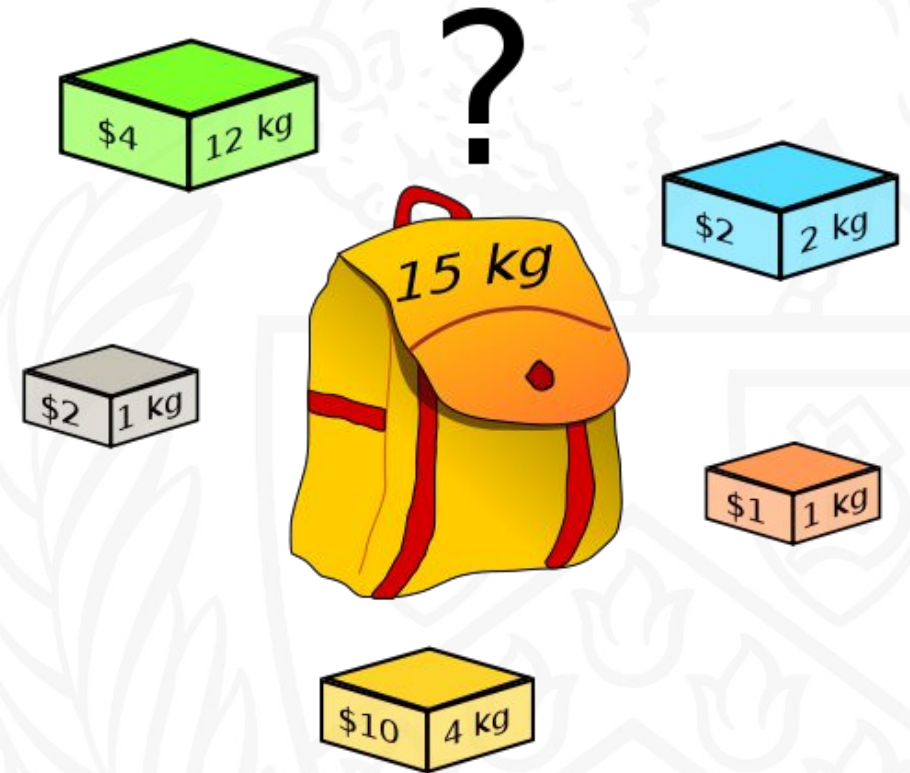
References



## Introduction to 0-1 Knapsack Problem

- Problem of combinatorial optimization
- A set of items with a weight and a value given a knapsack with a maximum weight it can carry

Find which items to take to get the best value but not exceed the knapsack capacity



# Example of Knapsack Problem

## 0-1 Knapsack Problem

value[] = {60, 100, 120};

weight[] = {10, 20, 30};

W = 50;

Solution: 220

Weight = 10; Value = 60;

Weight = 20; Value = 100;

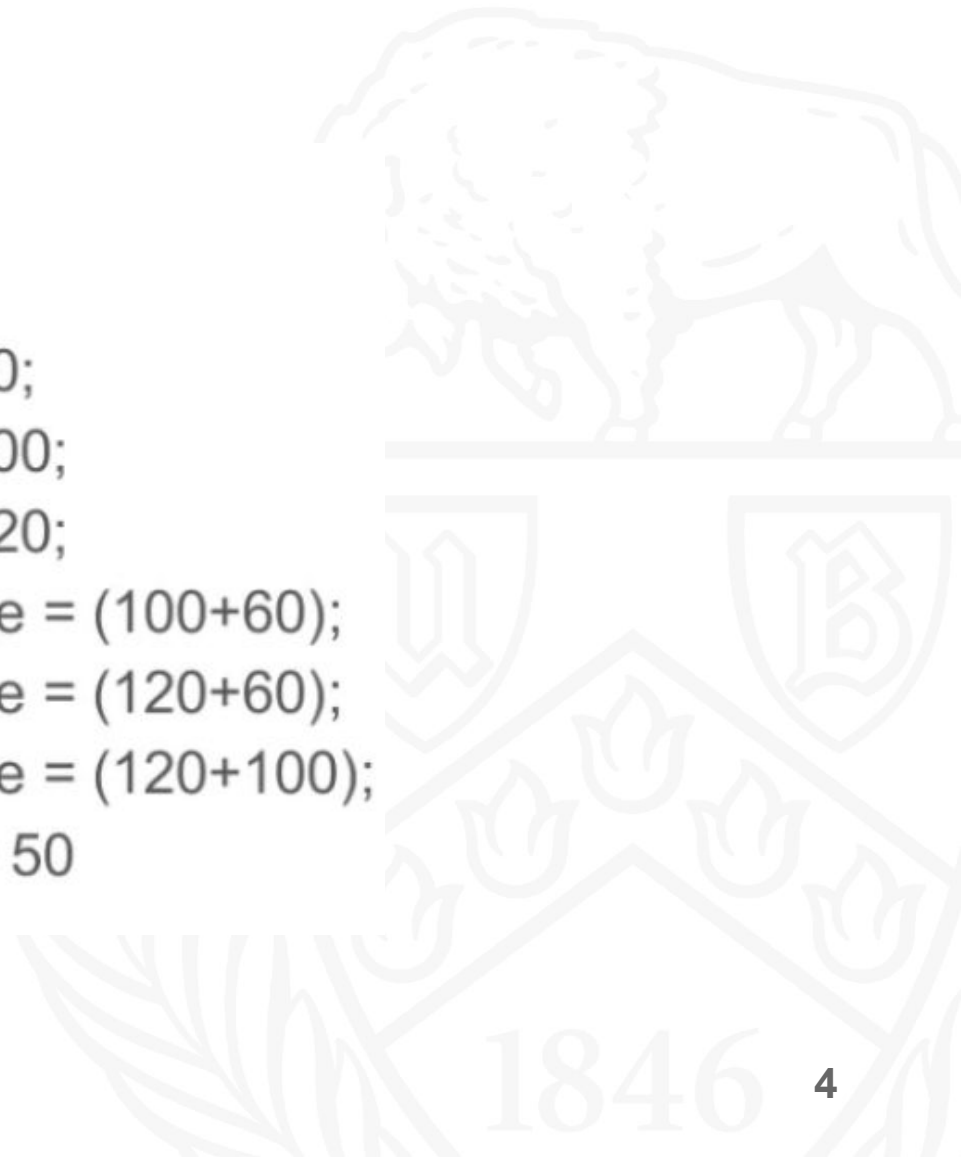
Weight = 30; Value = 120;

Weight = (20+10); Value = (100+60);

Weight = (30+10); Value = (120+60);

Weight = (30+20); Value = (120+100);

Weight = (30+20+10) > 50



# Sequential Implementation

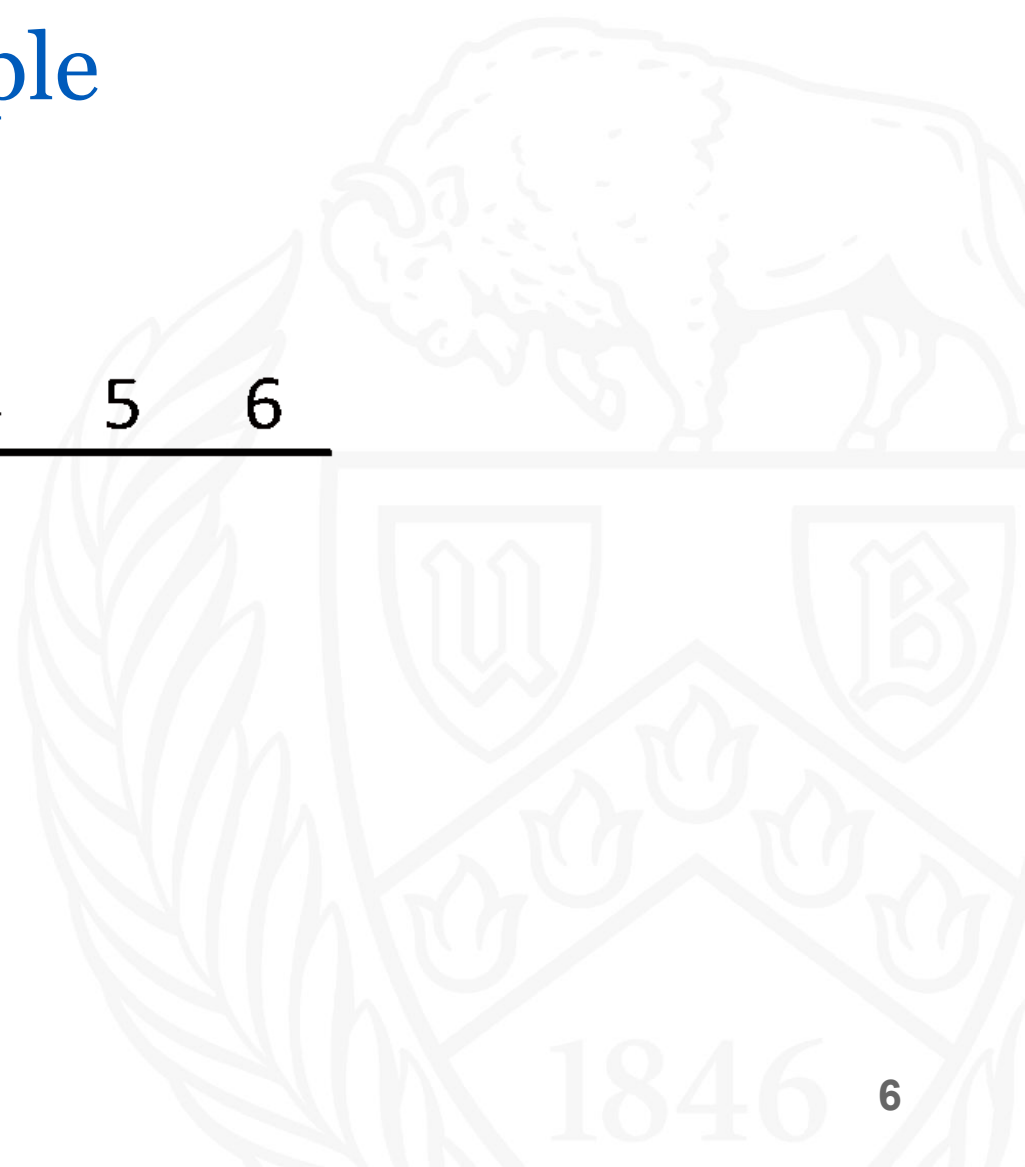
```
1 // Input:
2 // Values (stored in array v)
3 // Weights (stored in array w)
4 // Number of distinct items (n)
5 // Knapsack capacity (W)
6 // NOTE: The array "v" and array "w" are assumed to store all relevant values starting at index 1.
7
8 array m[0..n, 0..W];
9 for j from 0 to W do:
10     m[0, j] := 0
11 for i from 1 to n do:
12     m[i, 0] := 0
13
14 for i from 1 to n do:
15     for j from 0 to W do:
16         if w[i] > j then:
17             m[i, j] := m[i-1, j]
18         else:
19             m[i, j] := max(m[i-1, j], m[i-1, j-w[i]] + v[i])
```

# Sequential Implementation Example

$i$	$v$	$w$
1	5	4
2	4	3
3	3	2
4	2	1

*Capacity=6*

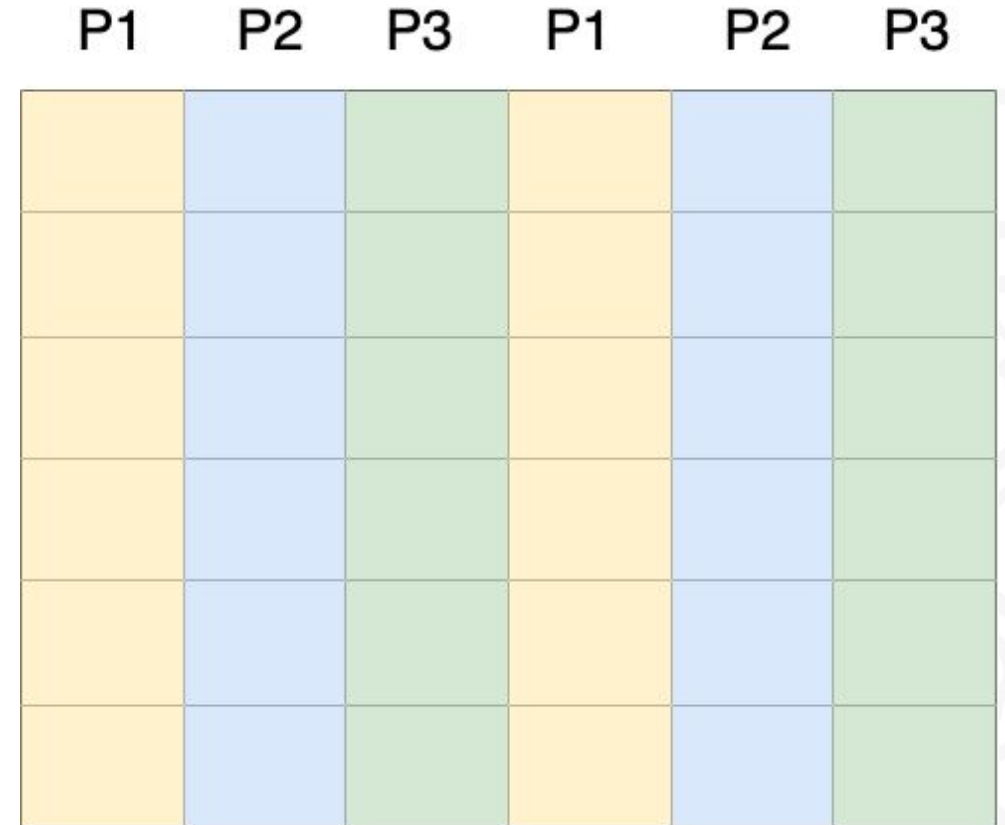
		$w$						
		0	1	2	3	4	5	6
$i$	0							
	1							
	2							
	3							
	4							



# MPI Parallel Implementation

We do column parallelization

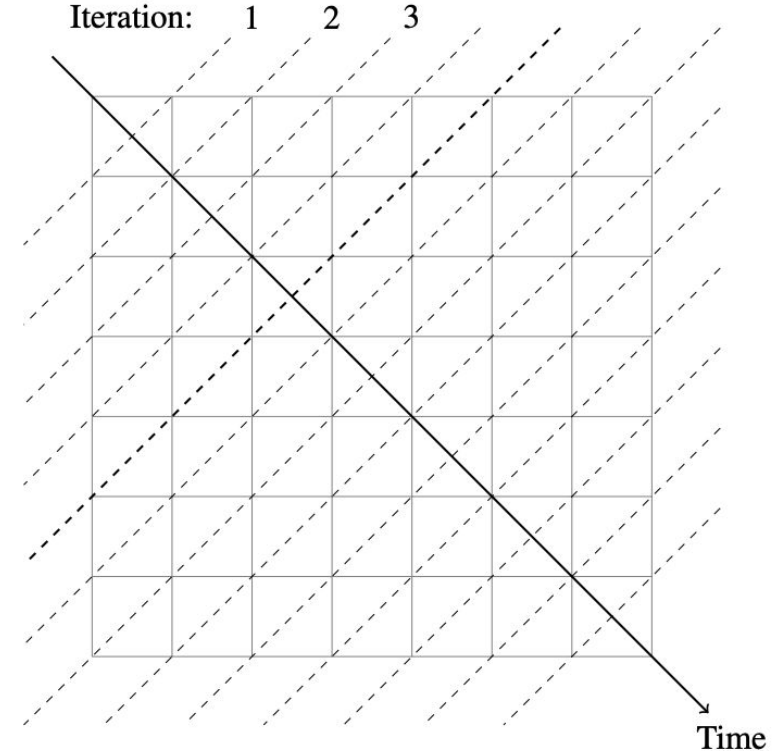
- Compute the maximum value achievable using the item of the row
- Compute the value without the new item. This value is the value just above in the matrix or 0 if it is the first item.
- Save in the cell the maximum value achievable using or not the new item
- Send to all the processors that could need it in future iteration the new value.



# CUDA Parallel Implementation

## Anti-Diagonal Approach

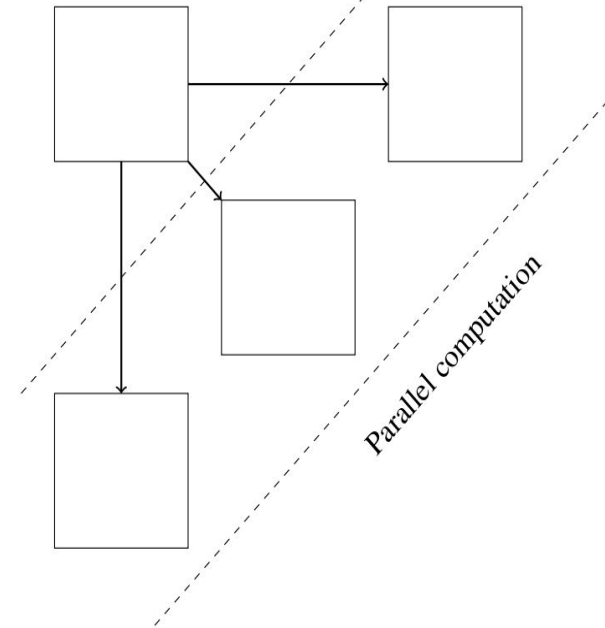
- We iterating through the dynamic programming scoring grid in an anti diagonal process.
- Each dotted line represents an iteration that is processed in parallel.





# CUDA Parallel Implementation

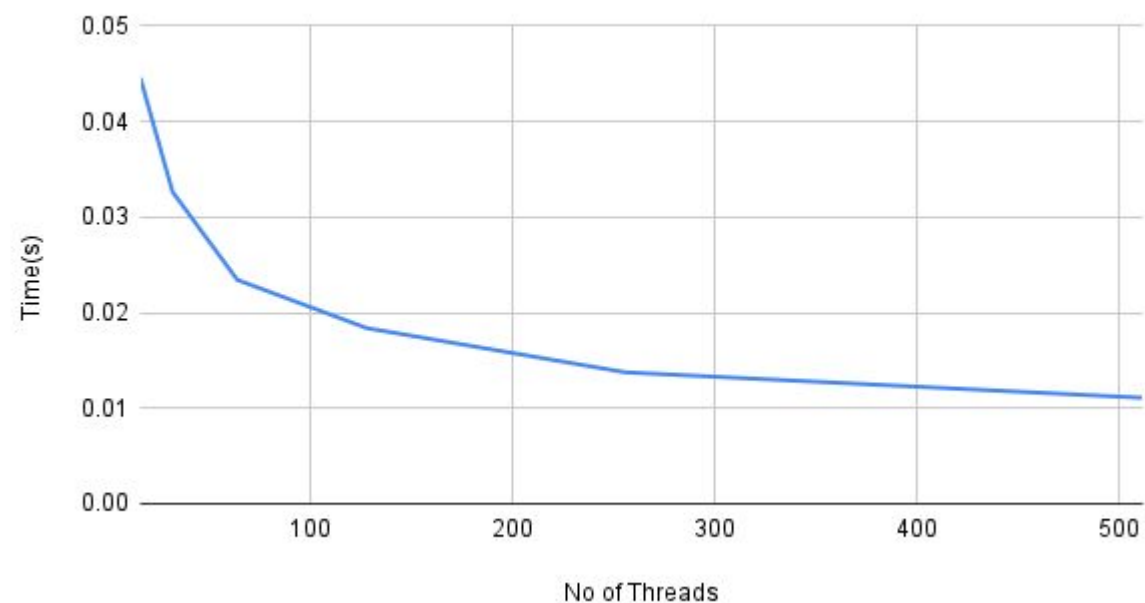
- As a cell being filled satisfies the dependencies of future cells, it allows the elements of a diagonal iteration of the current grid, to be calculated and filled in parallel.
- An example of a cell in the current grid only having data dependencies to the previous iterations.



# Output Analysis for W(100000/10000)

No of Threads	Time(s)
<b>16</b>	0.04461
<b>32</b>	0.03264
<b>64</b>	0.02343
<b>128</b>	0.01838
<b>256</b>	0.01375
<b>512</b>	0.01108

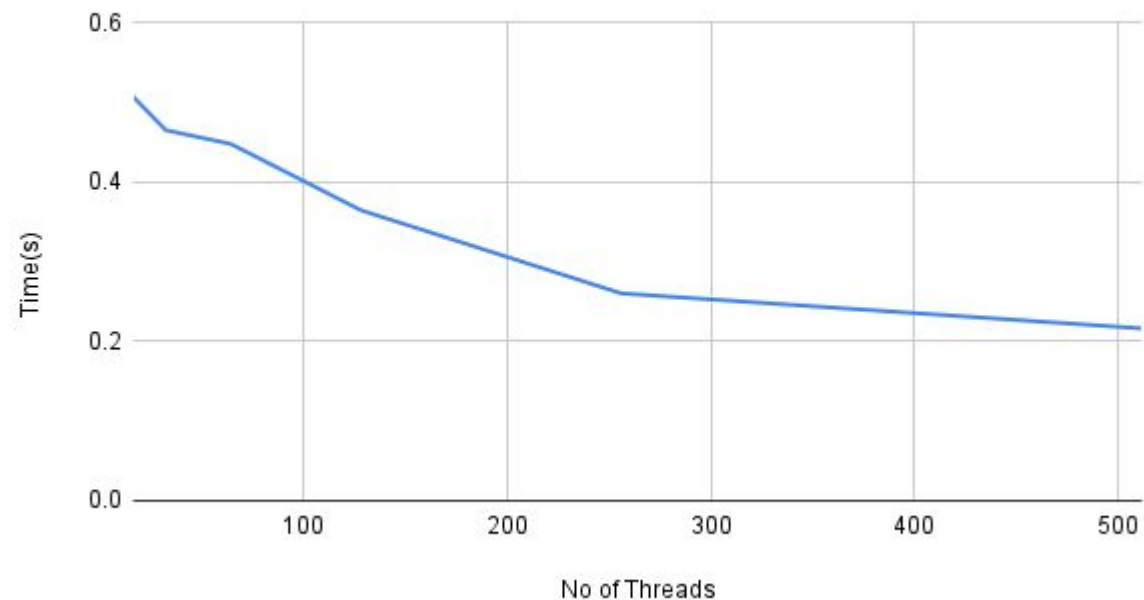
Time(s) vs. No of Threads



# Output Analysis for $W(500000/10000)$

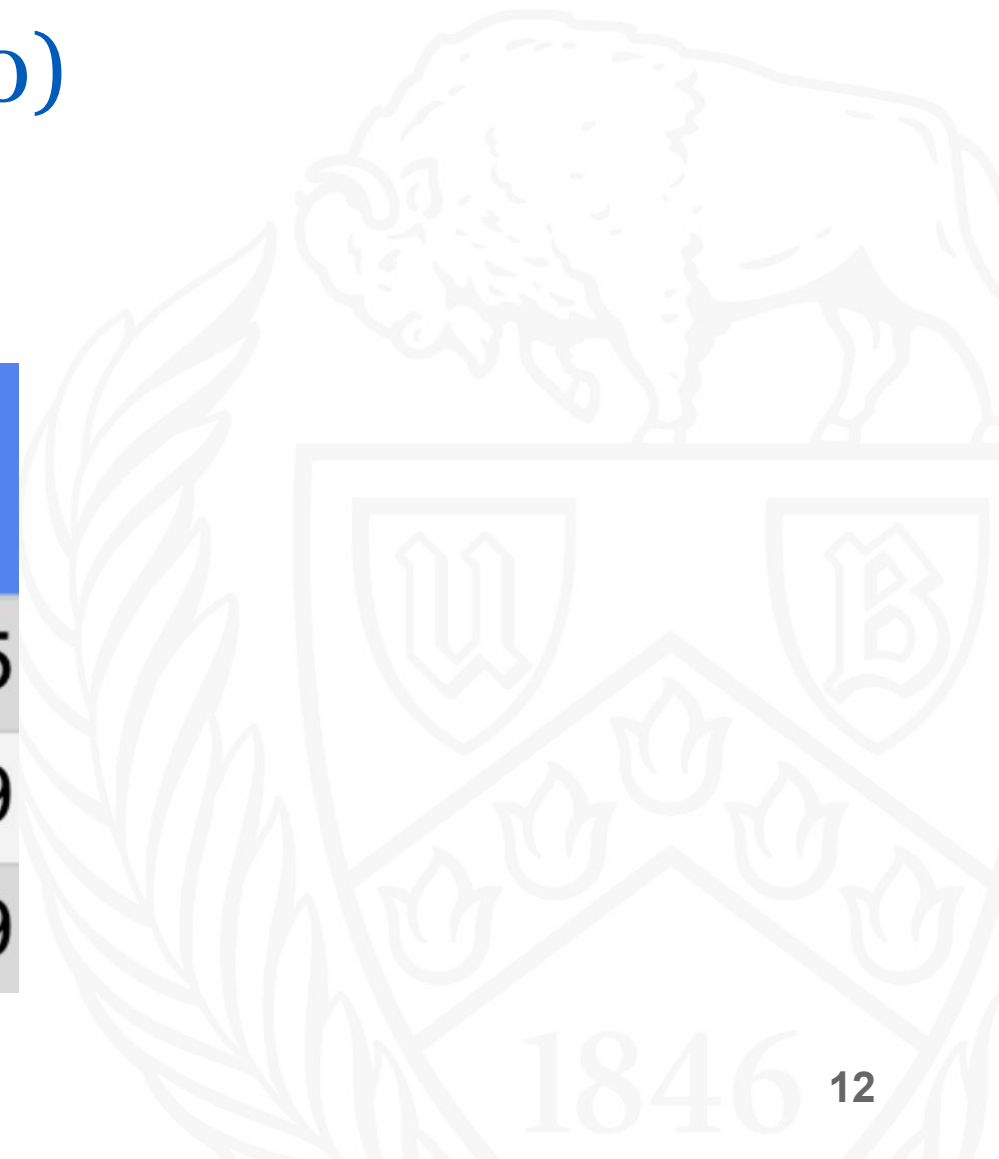
No of Threads	Time(s)
<b>16</b>	0.5073
<b>32</b>	0.4654
<b>64</b>	0.4481
<b>128</b>	0.3648
<b>256</b>	0.2604
<b>512</b>	0.2164

Time(s) vs. No of Threads



## MPI vs Cuda for W(500000/10000)

No of Threads/Nodes	Time(s)	Time(s)
<b>16</b>	0.5073	101.475
<b>32</b>	0.4654	64.479
<b>64</b>	0.4481	43.489



## Conclusion

- As the thread count increases per block the code executing becomes faster.
- Cuda is a shared memory paradigm, which makes the algorithm easy and faster. MPI is a distributed memory and all synchronization and communication are explicit.

## References:

- [https://en.wikipedia.org/wiki/Knapsack\\_problem](https://en.wikipedia.org/wiki/Knapsack_problem)
- <https://developer.nvidia.com/cuda-toolkit>
- <https://docs.nvidia.com/cuda/cuda-c-programming-guide/index.html>
- <https://www.geeksforgeeks.org/0-1-knapsack-problem-dp-10/>



Thanks You

