CSE 421/521 - Operating Systems Fall 2011

# OS STRUCTURES

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# Roadmap

- · OS Design and Implementation
  - Different Design Approaches
- · Major OS Components
  - Processes
  - Memory management
  - CPU Scheduling
  - I/O Management



2

# OS DESIGN APPROACHES

3

5

# Operating System Design and Implementation

- · Start by defining goals and specifications
- · Affected by choice of hardware, type of system
  - Batch, time shared, single user, multi user, distributed
- User goals and System goals
  - User goals operating system should be convenient to use, easy to learn, reliable, safe, and fast
  - System goals operating system should be easy to design, implement, and maintain, as well as flexible, reliable, errorfree, and efficient
- No unique solution for defining the requirements of an OS
  - $\rightarrow$  Large variety of solutions
  - $\rightarrow$  Large variety of OS

4

#### Operating System Design and Implementation (Cont.)

Important principle: to separate policies and mechanisms

Policy: What will be done?

Mechanism: How to do something?

- Eg. to ensure CPU protection
  - Use Timer construct (mechanism)
  - How long to set the timer (policy)
- The separation of policy from mechanism allows maximum flexibility if policy decisions are to be changed later

# **OS Design Approaches**

- Simple Structure (Monolithic)
- · Layered Approach
- Microkernels
- Modules

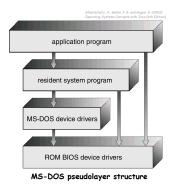
# Simple Structure

- Monolithic
- No well defined structure
- · Start as small, simple, limited systems, and then grow
- · No Layers, not divided into modules

# Simple Structure

# Example: MS-DOS

- initially written to provide the most functionality in the least space
- started small and grew beyond its original scope
- levels not well separated: programs could access I/O devices directly
- excuse: the hardware of that time was limited (no dual user/kernel mode)



# Layered Approach

# Monolithic operating systems

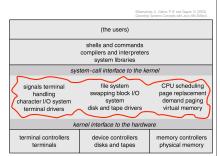
- no one had experience in building truly large software systems
- the problems caused by mutual dependence and interaction were grossly underestimated
- such lack of structure became unsustainable as O/S grew

#### Enter hierarchical layers and information abstraction

- each layer is implemented exclusively using operations provided by lower layers
- it does not need to know how they are implemented
- hence, lower layers hide the existence of certain data structures, private operations and hardware from upper layers

# Simple Layered Approach The original UNIX

- enormous amount of functionality crammed into the kernel everything below system call interface
- "The Big Mess": a collection of procedures that can call any of the other procedures whenever they need to
- no encapsulation, total visibility across the system
- very minimal layering made of thick monolithic layers

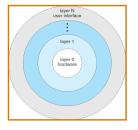


**UNIX** system structure

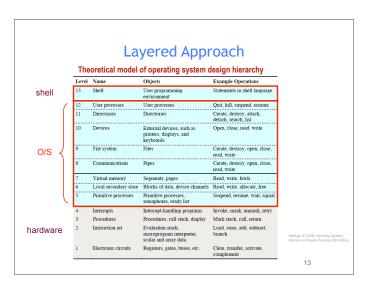
10

# Layered Approach

- · The operating system is divided into a number of layers (levels), each built on top of lower layers.
  - The bottom layer (layer 0), is the hardware;
  - The highest (layer N) is the user interface.
- · With modularity, layers are selected such that each uses functions (operations) and services of only lower-level layers
  - GLUnix, Multics, VAX/VMS



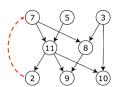
Layered Approach Layers can be debugged and replaced independently without bothering the other layers above and below famous example of strictly layered architecture: the TCP/IP networking stack N uses services *N*–1 12



# Layered Approach

# Major difficulty with layering

- ... appropriately <u>defining</u> the various layers!
- layering is only possible if all function dependencies can be sorted out into a Directed Acyclic Graph (DAG)
- however there might be conflicts in the form of circular dependencies ("cycles")



Circular dependency on top of a DAG

# Layered Approach

# Circular dependencies in an O/S organization

- example: disk driver routines vs. CPU scheduler routines
  - the device driver for the backing store (disk space used by virtual memory) may need to wait for I/O, thus invoke the CPU-scheduling layer
  - the CPU scheduler may need the backing store driver for swapping in and out parts of the table of active processes

#### > Other difficulty: efficiency

- the more layers, the more indirections from function to function and the bigger the overhead in function calls
- backlash against strict layering: return to fewer layers with more functionality

17

# Microkernel System Structure

### ➤ The microkernel approach

- ✓ a microkernel is a reduced operating system core that contains only essential O/S functions
- the idea is to minimize the kernel by moving up as much functionality as possible from the kernel into user space
- many services traditionally included in the O/S are now external subsystems running as user processes
  - device drivers
  - file systems
  - virtual memory manager
  - windowing system
  - security services, etc.
- Examples: QNX, Tru64 UNIX, Mach (CMU), Windows NT 16

# Layered OS vs Microkernel User A Users Kernel Mode I/O and Device Management HARDWARE (a) Lavered kernel (b) Microkernel

# Microkernel System Structure

#### > Benefits of the microkernel approach

- extensibility it is easier to extend a microkernel-based O/S as new services are added in user space, not in the kernel
- portability it is easier to port to a new CPU, as changes are needed only in the microkernel, not in the other services
- reliability & security much less code is running in kernel mode; failures in user-space services don't affect kernel space

#### Detriments of the microkernel approach

- again, performance overhead due to communication from user space to kernel space
- not always realistic: some functions (I/O) must remain in kernel space, forcing a separation between "policy" and "mechanism"

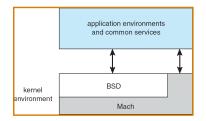
# Modular Approach

- > The modular approach
  - ✓ many modern operating systems implement kernel modules
  - ✓ this is similar to the object-oriented approach:
    - each core component is separate
    - each talks to the others over known interfaces
    - each is loadable as needed within the kernel
  - ✓ overall, modules are similar to layers but with more flexibility
  - modules are also similar to the microkernel approach, except they are inside the kernel and don't need message passing

19

# Modules are used in Solaris, Linux and Mac OS X Scheduling classes file systems wiscellaneous core solaris kernel system calls STREAMS Executable formats The Solaris loadable modules The Solaris loadable modules

# Mac OS X Structure - Hybrid



- BSD: provides support for command line interface, networking, file system, POSIX API and threads
- Mach: memory management, RPC, IPC, message passing

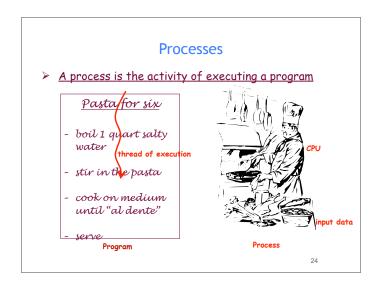
21

# MAJOR OS COMPONENTS

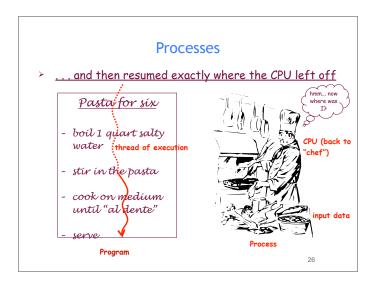
22

# Major OS Components

- Processes
- Memory management
- CPU Scheduling
- I/O Management



# **Processes** It can be interrupted to let the CPU execute a higher-priority process Pa CPU (changes hat to "doctor" First aid boil - Get the first aid kit wat Check pulse - stir - Clean wound with alcohol coo Apply band aid unt Program



# 

# **Processes**

- **Timesharing** is logical extension in which CPU switches jobs so frequently that users can interact with each job while it is running, creating **interactive** computing
  - **Response time** should be < 1 second
  - Each user has at least one program loaded in memory and executing ⇒ process

28

#### **Processes**

Operating System Responsibilities:

#### The O/S is responsible for managing processes

- ✓ the O/S creates & deletes processes
- √ the O/S suspends & resumes processes
- √ the O/S schedules processes
- √ the O/S provides mechanisms for process synchronization
- the O/S provides mechanisms for interprocess communication
- ✓ the O/S provides mechanisms for deadlock handling

# Memory Management

Operating System Responsibilities:

# The O/S is responsible for an efficient and orderly control of storage allocation

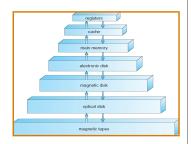
- ensures process isolation: it keeps track of which parts of memory are currently being used and by whom
- allocates and deallocates memory space as needed: it decides which processes to load or swap out
- regulates how different processes and users can sometimes share the same portions of memory
- transfers data between main memory and disk and ensures long-term storage

29

# Memory Management

# Main memory

- ✓ large array of words or bytes, each with its own address
- ✓ repository of quickly accessible data shared by the CPU and I/O devices
- √ volatile storage that loses its contents in case of system failure



The storage hierarchy

31

# Performance of Various Levels of Storage

• Movement between levels of storage hierarchy can be explicit or implicit

Level	1	2	3	4
Name	registers	cache	main memory	disk storage
Typical size	< 1 KB	> 16 MB	> 16 GB	> 100 GB
Implementation technology	custom memory with multiple ports, CMOS	on-chip or off-chip CMOS SRAM	CMOS DRAM	magnetic disk
Access time (ns)	0.25 - 0.5	0.5 – 25	80 – 250	5,000.000
Bandwidth (MB/sec)	20,000 - 100,000	5000 - 10,000	1000 - 5000	20 - 150
Managed by	compiler	hardware	operating system	operating system
Backed by	cache	main memory	disk	CD or tape

32

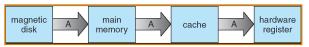
# Caching

- Important principle, performed at many levels in a computer (in hardware, operating system, software)
- Information in use copied from slower to faster storage temporarily
- Faster storage (cache) checked first to determine if information is there
  - If it is, information used directly from the cache (fast)
  - If not, data copied to cache and used there
- If cache is smaller than storage being cached
  - Cache management important design problem
  - Cache size and replacement policy

33

# Migration of Integer A from Disk to Register

 Multitasking environments must be careful to use most recent value, not matter where it is stored in the storage hierarchy



- Multiprocessor environment must provide cache coherency in hardware such that all CPUs have the most recent value in their cache
- Distributed environment situation even more complex
  - Several copies of a datum can exist

34

# **CPU Scheduling**

Operating System Responsibilities:

The O/S is responsible for efficiently using the CPU and providing the user with short response times

- ✓ decides which available processes in memory are to be executed by the processor
- decides what process is executed when and for how long, also reacting to external events such as I/O interrupts
- relies on a scheduling algorithm that attempts to optimize CPU utilization, throughput, latency, and/or response time, depending on the system requirements

# OS Scheduling

#### > Long-term scheduling

the decision to add a program to the pool of processes to be executed (job scheduling)

# > Medium-term scheduling

the decision to add to the number of processes that are partially or fully in main memory ("swapping")

# Short-term scheduling = CPU scheduling

the decision as to which available processes in memory are to be executed by the processor ("dispatching")

#### > I/O scheduling

the decision to handle a process's pending I/O request

fine- to coarse-grain level frequency of intervention

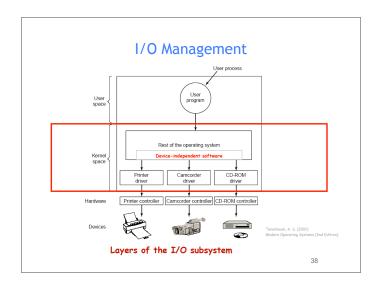
# I/O Management

Operating System Responsibilities:

# The O/S is responsible for controlling access to all the I/O devices

- hides the peculiarities of specific hardware devices from the user
- ✓ issues the low-level commands to the devices, catches interrupts and handles errors
- ✓ relies on software modules called "device drivers"
- provides a device-independent API to the user programs, which includes buffering

37



#### Two I/O Methods

- After I/O starts, control returns to user program only upon I/O completion → synchronous
  - Wait instruction idles the CPU until the next interrupt
  - Wait loop (contention for memory access).
  - At most one I/O request is outstanding at a time, no simultaneous I/O processing.
- After I/O starts, control returns to user program without waiting for I/O completion →asynchronous
  - System call request to the operating system to allow user to wait for I/O completion.
  - Device-status table contains entry for each I/O device

Synchronous

Asynchronous

requesting process device driver

device driver

device driver

hardware

data transfer

time

time

time

time

time

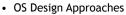
time

40

Two I/O Methods

39

# **Summary**



- Monolithic Systems,
- Layered Approach, Microkernels, Modules
- · Major OS Components
  - Processes
  - Memory management
  - CPU Scheduling
  - I/O Management



**Ouestions?** 

• Reading Assignment: Chapter 2 from Silberschatz.

# Acknowledgements

- "Operating Systems Concepts" book and supplementary material by A. Silberschatz, P. Galvin and G. Gagne
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42