## 2D Graphics Primitives IV

Clipping polygons
Antialiasing

Clipping Polygons


Original Scene and Clipbox

If just clip lines


Want to clip polygons


## Sutherland-Hodgeman Polygon Clipper

## Divide and conquer algorithm

Clipping against clip-region
Clip against each region edge
Parallel implementation
Pipeline implementation
\(\left.\left.$$
\begin{array}{|l|}\hline \begin{array}{l}\text { Clip } \\
\text { Right } \\
\text { Boundary }\end{array} \\
\hline\end{array}
$$ \rightarrow \right\rvert\, \begin{array}{l}Clip <br>
Bottom <br>

Boundary\end{array}\right) \rightarrow\)| Clip |
| :--- |
| Left <br> Boundary |
| $\longrightarrow$Clip <br> Top <br> Boundary |

## Input a list of points (vertices)

Each stage of pipeline outputs an updated list of vertices


Can generalize to any convex polygon clip region

How Clip Polygon by a Boundary?


## Need concept of inside and outside of boundary

Consider a polygon described by a sequence of vertices

$$
\mathrm{V}=\left(\mathrm{v}_{1}, \mathrm{v}_{2}, \mathrm{v}_{3}, \ldots, \mathrm{v}_{\mathrm{n}}\right)
$$

Want to clip against clip-region to get clipped polygon

$$
\mathrm{C}=\left(\mathrm{c}_{1}, \mathrm{c}_{2}, \mathrm{c}_{3}, \ldots, \mathrm{c}_{\mathrm{m}}\right)
$$

In general will $\mathrm{m}=\mathrm{n}$ ?
Let E be the edge list of V

$$
E=\left\{s p \mid s=v_{i}, p=v_{i+1}\right\}+\left\{v_{n} v_{1}\right\}
$$

note we need to include last edge

For each edge sp in E
if $s$ and $p$ are both inside boundary, then output $p$
if $s$ is inside and $p$ is outside then output intersection, i
if $s$ and $p$ both outside, then output nothing
if $s$ is outside and $p$ is inside, then output $i$ and $p$


The output list from one boundary is the input list for the next

## CDQ: Hand Simulation of Sutherland-Hodgman Polygon Clipping



$$
\begin{aligned}
& V=(a, b, c, d, e, f, g) \\
& E=?
\end{aligned}
$$

Find the updated E after clipping by: right boundary

$$
\mathrm{E}=
$$

bottom boundary

$$
\begin{gathered}
E= \\
\text { left boundary }
\end{gathered}
$$

$$
\mathrm{E}=
$$

top boundary

$$
\mathrm{E}=
$$

Is this the desired output for this polygon?

## Weiler-Atherton Polygon Clipping

Solves problem just encountered
Very general
Can clip convex polygon by a convex polygon Can clip a concave polygon by a convex polygon

Clip region is called the clip polygon
Polygon to be clipped is called the subject polygon
Traces clockwise around the polygons

## Algorithm

```
position = start
save = off
trace subject (position)
    if hit clip
            if (entering clip and subject not saved)
                save = on
                trace subject(current)
            else if (leaving clip and clip right not saved))
            save = on
            push current onto stack
            trace clip(current)
            else
            save = off
            if stack empty
                end
            else
                popstack (current)
                    trace subject (current)
end
trace clip (position)
    if hit subject
            if subject right not saved
                                    turn on save
                                    trace subject (current)
            else
                turn off save
                        if stack empty
                end
            else

\section*{Antialiasing}

Or: "How to overcome the Jaggies"
When scan converting lines (or filled polygons) get jaggies - small step edges


By product of digitization
Can we improve things by increasing the resolution of the display?

Not exactly
Does increase the number of distinct orientations we can display
But still a problem

Can we overcome this problem with binary displays?

How to overcome the problem with grey-scale displays

\section*{Method 1: Prefiltering}

When scan converting an object, compute the value for each pixel that will diminish the perceived aliasing

Pitteway and Watkinson came up with a modification to Bresenham's line drawing algorithm which does the calculations whilst scan converting

Difficult to compute this for nonstraight lines.
Two main approaches:
Unweighted Area Sampling
Weighted Area Sampling

Unweighted Area Sampling:
Determine what percentage of a pixel's area is covered by the object

Value of pixel is linear function of this percentage Totally covered - max value (foreground color) Totally uncovered - min value (background color) \(50 \%\) covered - half way between max amd min


Triangle color: 10 Background: 0

What value for each pixel?

\section*{Weighted Area Sampling}

If line passes through middle of pixel, may want to weight it more than if it passes by pixel edge
(Assume now that pixels are square tiles tesselating (tiling) a surface)


Use weighted filter function


Box Filter
Convolve scene with filter for each pixel
filter \(=f(x, y)\)
scene \(=g(x, y)\)
filtered output \(=\) area under \(f(x, y)\) times \(\mathrm{g}(\mathrm{x}, \mathrm{y})\)
for box filter at pixel i,j
\[
\begin{aligned}
\mathrm{f}(\mathrm{x}, \mathrm{y}) & =1, \text { if } \mathrm{i}<=\mathrm{x}<=\mathrm{i}+1, \text { and } \mathrm{j}<=\mathrm{y}<=\mathrm{j}+1 \\
& =0, \text { otherwise }
\end{aligned}
\]

Box filter is just the Unweighted Prefiltering
To give more weight at center of pixel
Could use cone shaped filter
May want the base of the cone to be greater than one pixel in diameter


If diameter of cone base (support) = one pixel width for square pixels, then is all of the scene sampled?

If make support too small, then not all scene is sampled If make support too large, then may blur scene too much

Support diameter \(=2\) pixel widths is good compromise

Method 2: Supersampling
Scan convert a grid that has more pixels than actual display
For each display pixel, compute the average value of the corresponding set of supersampled pixels


Here dashed line intersections are the displayed pixels solid and solid-dashed intersections are supersampled pixels

With this double sampling, average display pixel and it's eight-connected neighbors
(See example)
What is relation between prefiltering and supersampling?

Method 3: Postfiltering
Just as could use weighted sampling filter in prefiltering, can use weighted sampling filter in postfiltering

Supersample the scene
Instead of using straight average, use a weighted average of supersample pixels to compute value of display pixel

If double sample, could use \(3 \times 3\) filter or even \(5 \times 5,7 \times 7\) or greater.

Example filters:

If quadruple sample, what would be smallest reasonable filter size?


How many extra pixels?

What is effect of using larger filter?```

