

Three Dimensional Representations

Quadric Surfaces

Superquadrics

Sweep Representations

Constructive Solid Geometry

Octrees

Quadric Surfaces

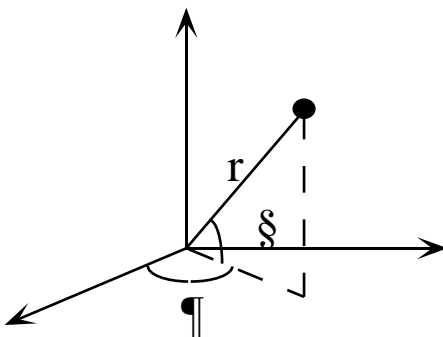
Second degree equations - quadratics

Sphere

$$\text{nonparametric: } x^2 + y^2 + z^2 = r^2$$

parametric: use latitude (ξ) and longitude (η)

$$\begin{aligned} x &= r \cos \xi \cos \eta & -1/2 \leq \xi \leq 1/2 \\ y &= r \cos \xi \sin \eta & -1 \leq \eta \leq 1 \\ z &= r \sin \xi \end{aligned}$$

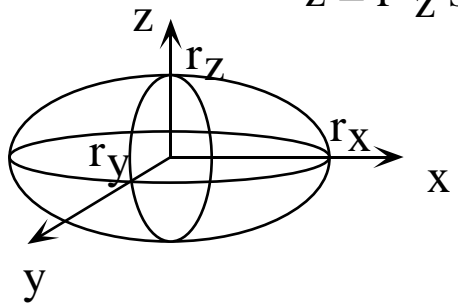


$$\begin{aligned} \text{use } 0 \leq u, v \leq 1 \\ \xi &= 2u - 1 \\ \eta &= 2v \end{aligned}$$

Ellipsoid

nonparametric: $(x/r_x)^2 + (y/r_y)^2 + (z/r_z)^2 = 1$

parametric: $x = r_x \cos \xi \cos \eta$ $-1/2 \leq \xi \leq 1/2$
 $y = r_y \cos \xi \sin \eta$ $-1/2 \leq \eta \leq 1/2$
 $z = r_z \sin \xi$

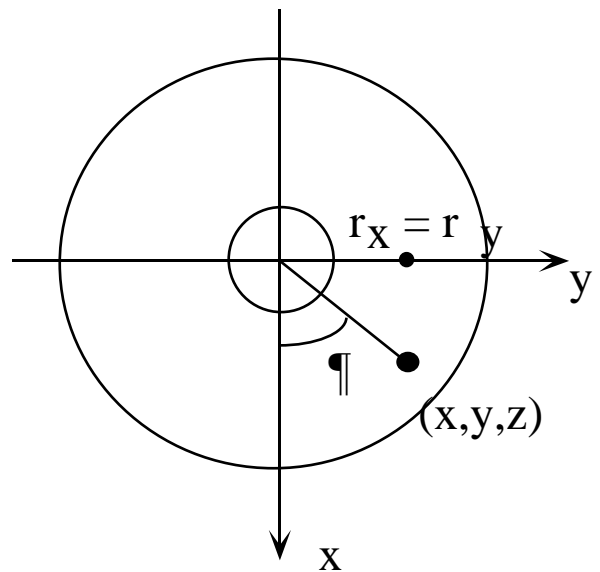
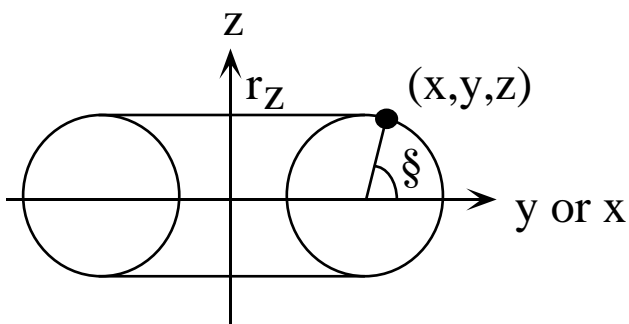


Torus

Rotate circle (or other conic) in yz plane about z axis

Parametric:

$x = r_x (r + \cos \xi) \cos \eta$ $-1 \leq \xi \leq 1$
 $y = r_y (r + \cos \xi) \sin \eta$ $-1 \leq \eta \leq 1$
 $z = r_z \sin \xi$



Superquadrics

Generalize quadrics by adding extra parameters

Number of extra parameters equals dimension of object

one extra for curves

two extra for surfaces

Superellipse

$$\begin{aligned} \text{parametric: } x &= r_x \cos^s \phi & -1 \leq \phi \leq 1 \\ y &= r_y \sin^s \phi \end{aligned}$$

(see figure)

Superellipsoid

$$\begin{aligned} \text{parametric: } x &= r_x \cos^{s_1} \xi \cos^{s_2} \eta & -1/2 \leq \xi \leq 1/2 \\ y &= r_y \cos^{s_1} \xi \sin^{s_2} \eta & -1 \leq \eta \leq 1 \\ z &= r_z \sin^{s_1} \xi \end{aligned}$$

(see figure)

How to define shapes for manufacture?

Consider the process used to form the shape

Surfaces of revolution

wood turned on a lathe

pot formed on potters wheel

Extrusion

spaghetti

plastic siding and gutters

Rolling, forming, molding

clay finger pots

pie crusts

Sawing, flat grinding

construction 2x4's

Develop representation appropriate for the process

Examples:

sawing and flat grinding yields polygons

surface of revolution yields surfaces represented
by sweep representations

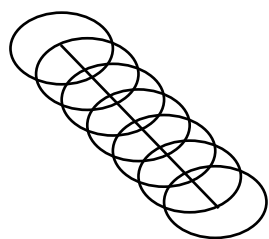
Computer graphics systems for design should allow user to easily
create appropriate surfaces

Sweep Representations

Define by: two-dimensional shape
sweep that moves the shape through a region of space

Translational sweep

example:

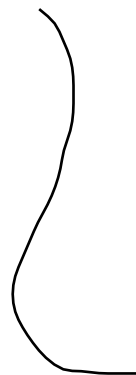


Sweep an ellipse along a line

Rotational Sweep

example:

How get a torus?

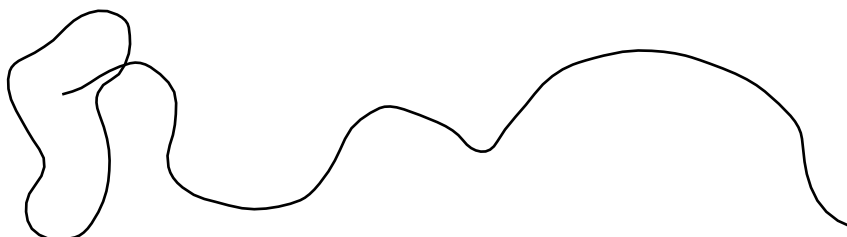


Arbitrary Sweep

example:

Define cross section as a closed curve represented
as a B-spline

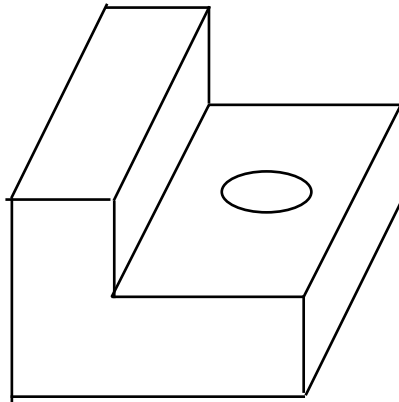
Define path as a curve represented as a B-spline



Constructive Solid Geometry

Intersection, union and difference of specified volumes

Volumetric rather than surface representation



Form by union of a block lying flat and a block lying on edge

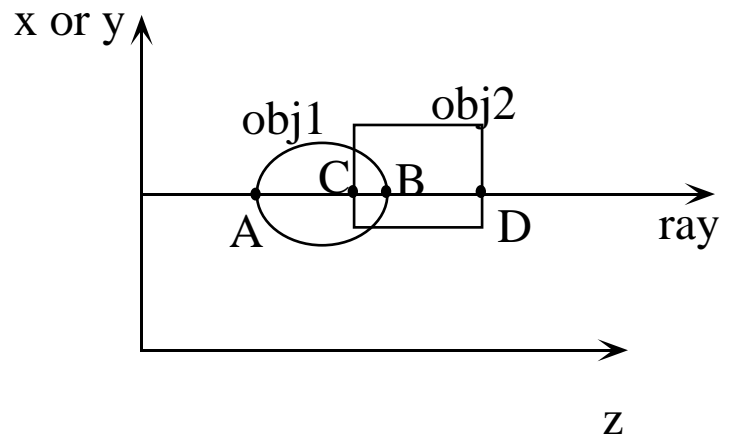
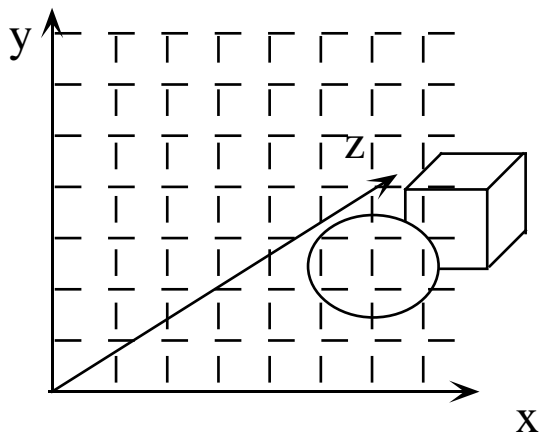
Subtract a cylinder from the union to get the hole

How get a quarter cylinder of height H
from a rectangular block of height H
and a cylinder of height J ?

How implement constructive solid geometry in computer graphics system?

If use boundary representation of objects
use Ray-casting

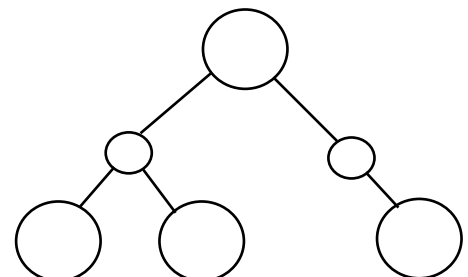
- Represent scene in world coordinates
- Represent firing plane with x-y plane
- Fire rays from each pixel in firing plane
- Note intersection of rays with surfaces of objects
- Apply operations to intersections to get new boundaries



Operation	Surface Limits
Union	A, D
Intersection	C, B
Difference	
obj2-obj1	B, D
obj1-obj2	A, C

Easy to represent finished objects as a tree

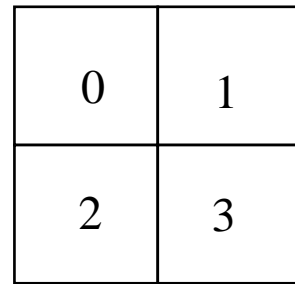
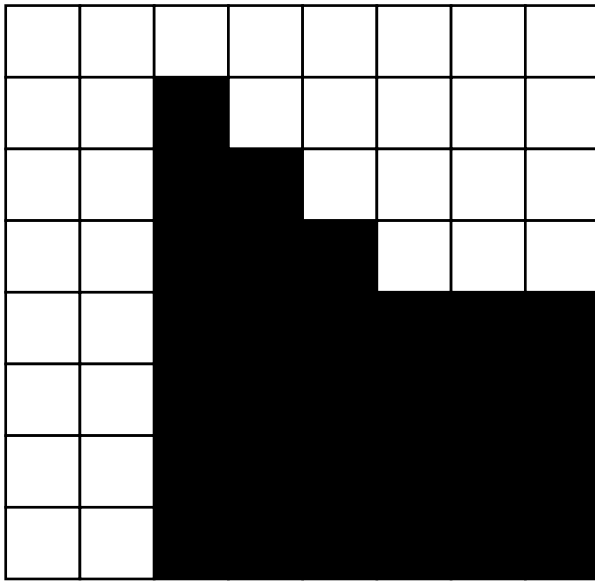
large circles - objects
small circles - operations



Octrees

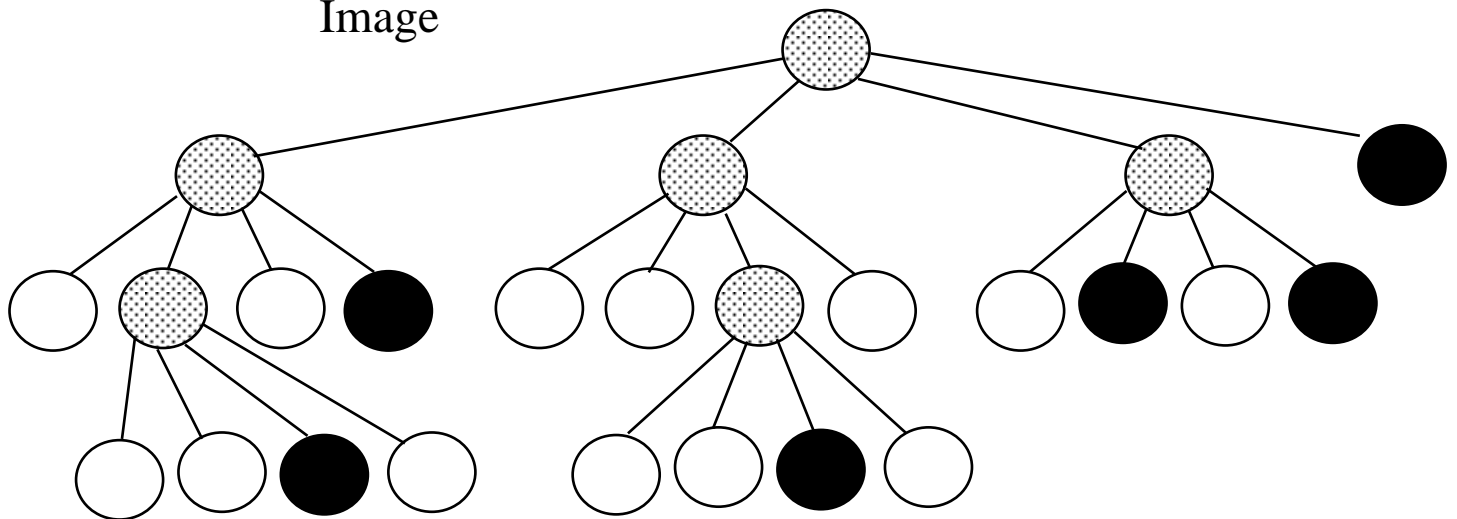
Spatial occupancy array

2-D - quadtrees



Quadrant labels

Image



Three types of nodes - white, black, grey

What color are leaf nodes?

What colors can root nodes be?

BSP Trees

Binary space partitioning

Instead of dividing space into 8 regions at each step
divide into just two regions using a plane

What additional info must be stored?

the definition of the partitioning plane

Can be much more efficient

What happens to the octree representation of an object

if the object is translated?

For a BSP tree?

For image = $2^n \times 2^n$ pixels

What is the minimum height of it's quad-tree?

What is it's maximum height?

Are there always fewer nodes than pixels?

What would be a worst case image?

a checkerboard with square size of one pixel

What number of nodes in a worst case quadtree?

Octrees

Do same thing with voxels versus pixels

Max possible children / node?