

# Process Scheduling

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## Introduction

- An important aspect of multiprogramming is scheduling. The resources that are scheduled are IO and processors.
- The goal is to achieve
  - High processor utilization
  - High throughput
    - number of processes completed per unit time
  - Low response time
    - time elapse from the submission of a request to the beginning of the response

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## Topics for discussion

- Motivation
- Types of scheduling
- Short-term scheduling
- Various scheduling criteria
- Various algorithms
  - Priority queues
  - First-come, first-served
  - Round-robin
  - Shortest process first
  - Shortest remaining time and others

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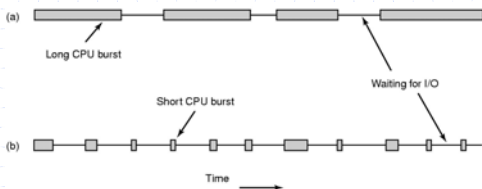
## The CPU-I/O Cycle

- We observe that processes require alternate use of processor and I/O in a repetitive fashion
- Each cycle consist of a CPU burst (typically of 5 ms) followed by a (usually longer) I/O burst
- A process terminates on a CPU burst
- CPU-bound processes have longer CPU bursts than I/O-bound processes

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## CPU/IO Bursts



- Bursts of CPU usage alternate with periods of I/O wait
  - a CPU-bound process
  - an I/O bound process

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## Motivation

- Consider these programs with processing-component and IO-component indicated by upper-case and lower-case letters respectively.

```
A1 a1 A2 a2 A3
0 30 50 80 120 130 ==> JOB A
B1 b1 B2
0 20 40 60 ==> JOB B
C1 c1 C2 c2 C3 c3 C4 c4 C5
0 10 20 60 80 100 110 130 140 150
2/16/2004 ==> JOB C
```

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## Motivation

- The starting and ending time of each component are indicated beneath the symbolic references (A1, b1 etc.)
- Now lets consider three different ways for scheduling: no overlap, round-robin, simple overlap.
- Compare utilization  $U = \text{Time CPU busy} / \text{Total run time}$

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## Scheduling Criteria

- CPU utilization – keep the CPU as busy as possible
- Throughput – # of processes that complete their execution per time unit
- Turnaround time – amount of time to execute a particular process
- Waiting time – amount of time a process has been waiting in the ready queue
- Response time – amount of time it takes from when a request was submitted until the first response is produced, **not** output (for time-sharing environment)

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## Optimization Criteria

- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time

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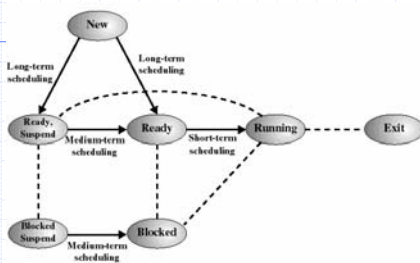
## Types of scheduling

- Long-term : To add to the pool of processes to be executed.
- Medium-term : To add to the number of processes that are in the main memory.
- **Short-term** : Which of the available processes will be executed by a processor?
- IO scheduling: To decide which process's pending IO request shall be handled by an available IO device.

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## Classification of Scheduling Activity



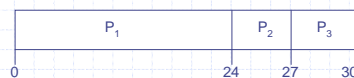
- Long-term: which process to admit
- Medium-term: which process to swap in or out
- Short-term: which ready process to execute next

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## First-Come, First-Served (FCFS) Scheduling

Process	Burst Time
$P_1$	24
$P_2$	3
$P_3$	3

- Suppose that the processes arrive in the order:  $P_1, P_2, P_3$   
The Gantt Chart for the schedule is:



Waiting time for  $P_1 = 0$ ;  $P_2 = 24$ ;  $P_3 = 27$

Average waiting time:  $(0 + 24 + 27)/3 = 17$

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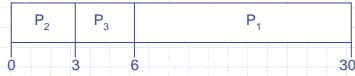
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## FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order

$$P_2, P_3, P_1.$$

The Gantt chart for the schedule is:



- Waiting time for  $P_1 = 6$ ;  $P_2 = 0$ ;  $P_3 = 3$
- Average waiting time:  $(6 + 0 + 3)/3 = 3$
- Much better than previous case.
- Convoy effect short process behind long process

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## Shortest-Job-First (SJR) Scheduling

- Associate with each process the length of its next CPU burst. Use these lengths to schedule the process with the shortest time.
- Two schemes:
  - nonpreemptive – once CPU given to the process it cannot be preempted until completes its CPU burst.
  - preemptive – if a new process arrives with CPU burst length less than remaining time of current executing process, preempt. This scheme is known as the Shortest-Remaining-Time-First (SRTF).
- SJF is optimal – gives minimum average waiting time for a given set of processes.

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## Example of Non-Preemptive SJF

Process Arrival Time Burst Time

$P_1$	0.0	7
$P_2$	2.0	4
$P_3$	4.0	1
$P_4$	5.0	4



- Average waiting time =  $(0 + 6 + 3 + 7)/4 = 4$

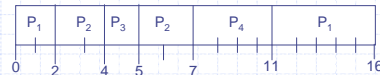
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## Example of Preemptive SJF

Process Arrival Time Burst Time

$P_1$	0.0	7
$P_2$	2.0	4
$P_3$	4.0	1
$P_4$	5.0	4



- Average waiting time =  $(9 + 1 + 0 + 2)/4 = 3$

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## Determining Length of Next CPU Burst

- Can only estimate the length.
- Can be done by using the length of previous CPU bursts, using exponential averaging.

- $t_n$  = actual length of  $n^{\text{th}}$  CPU burst
- $r_{n+1}$  = predicted value for the next CPU burst
- $\alpha, 0 \leq \alpha \leq 1$
- Define:  $r_{n+1} = \alpha t_n + (1 - \alpha)r_n$ .

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## Examples of Exponential Averaging

- $\alpha = 0$ 
  - $r_{n+1} = r_n$
  - Recent history does not count.
- $\alpha = 1$ 
  - $r_{n+1} = t_n$
  - Only the actual last CPU burst counts.
- If we expand the formula, we get:
 
$$r_{n+1} = \alpha t_n + (1 - \alpha) \alpha t_{n-1} + \dots + (1 - \alpha)^j \alpha t_{n-j} + \dots + (1 - \alpha)^{n+1} r_1$$
- Since both  $\alpha$  and  $(1 - \alpha)$  are less than or equal to 1, each successive term has less weight than its predecessor.

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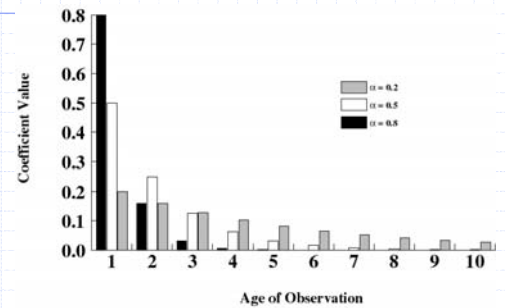
## More on Exponential Averaging

- $S[n+1]$  next burst,  $s[n]$  current burst
  - $S[n+1] = \alpha T[n] + (1-\alpha) S[n]$  ;  $0 < \alpha < 1$
  - more weight is put on recent instances whenever  $\alpha > 1/n$
- By expanding this eqn, we see that weights of past instances are decreasing exponentially
  - $S[n+1] = \alpha T[n] + (1-\alpha)\alpha T[n-1] + \dots (1-\alpha)^i \alpha T[n-i]$   
+  
... +  $(1-\alpha)^n S[1]$
  - predicted value of 1st instance  $S[1]$  is not calculated; usually set to 0 to give priority to new processes

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## Exponentially Decreasing Coefficients



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## Shortest Process Next: critique

- Possibility of starvation for longer processes as long as there is a steady supply of shorter processes
- Lack of preemption is not suited in a time sharing environment
  - CPU bound process gets lower priority (as it should) but a process doing no I/O could still monopolize the CPU if he is the first one to enter the system
- SPN implicitly incorporates priorities: shortest jobs are given preferences
- The next (preemptive) algorithm penalizes directly longer jobs

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## Priority Scheduling

- A priority number (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer = highest priority).
  - Preemptive
  - nonpreemptive
- SJF is a priority scheduling where priority is the predicted next CPU burst time.
- Problem = Starvation – low priority processes may never execute.
- Solution = Aging – as time progresses increase the priority of the process.

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## Round Robin (RR)

- Each process gets a small unit of CPU time (*time quantum*), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are  $n$  processes in the ready queue and the time quantum is  $q$ , then each process gets  $1/n$  of the CPU time in chunks of at most  $q$  time units at once. No process waits more than  $(n-1)q$  time units.
- Performance
  - $q$  large  $\Rightarrow$  FIFO
  - $q$  small  $\Rightarrow$   $q$  must be large with respect to context switch, otherwise overhead is too high.

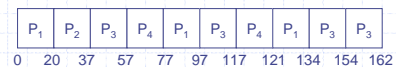
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## Example of RR with Time Quantum = 20

Process	Burst Time
$P_1$	53
$P_2$	17
$P_3$	68
$P_4$	24

- The Gantt chart is:



- Typically, higher average turnaround than SJF, but better *response*.

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## Various Metrics

- ◆ Turnaround time = Finish time - Arrival time
- ◆ Normalized turnaround time = Turnaround time / service time
- ◆ Response time = arrival time - start time
- ◆ Overall wait time = response time + wait times in the ready queue (ready to run, but CPU not avail)

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## Scheduling in Real-Time Systems

Schedulable real-time system

◆ Rate Monotonic Scheduling:

◆ Given

- $m$  periodic events
- event  $i$  occurs within period  $P_i$  and requires  $C_i$  seconds

◆ Then the load can only be handled if

$$\sum_{i=1}^m \frac{C_i}{P_i} \leq 1$$

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## Summary

- ◆ Scheduling is important for improving the system performance.
- ◆ Methods of prediction play an important role in Operating system and network functions.
- ◆ Simulation is a way of experimentally evaluating the performance of a technique.

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