

Limitations of SQL

<code>flight</code>	from	to
	SD	LA
	SD	ORD
	LA	NY
	

“Is there a way to get from City1 to City2” ?

Easier:

“Is there a way to get from City1 to City2 **by a direct flight?**”

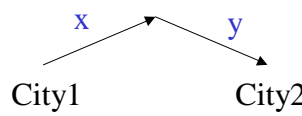
City1 \longrightarrow City2

```
Select * from flight  
where from = 'City1' and to = 'City2'
```

Easier:

“Is there a way to get from City1 to City2 **with at most one stopover?**”

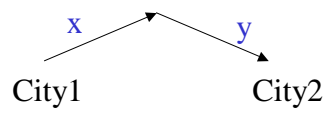
City1 \longrightarrow City2 `select * from flight
where from = 'City1' and to = 'City2'`
OR

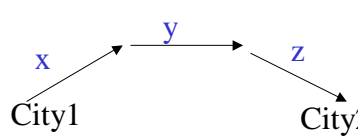
 `select x.from, y.to
from flight x, flight y
where x.from = 'City1' and
x.to = y.from and y.to = 'City2'`

Easier:

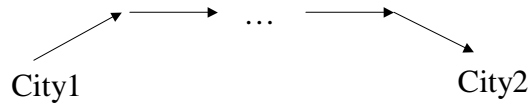
“Is there a way to get from City1 to City2 **with at most two stopovers?**”

City1 \longrightarrow City2 `select * from flight
where from = 'City1' and to = 'City2'`
OR

 `select x.from, y.to
from flight x, flight y
where x.from = 'City1' and
x.to = y.from and y.to = 'City2'`
OR

 `select x.from, z.to
from flight x, flight y, flight z
where x.from = 'City1' and x.to = y.from
and y.to = z.from and z.to = 'City2'`

“Is there a way to get from City1 to City2 with at most k stopovers?”



Need k+1 tuple variables!

“Is there a way to get from City1 to City2
with any number of stopovers?”

Cannot do in SQL!

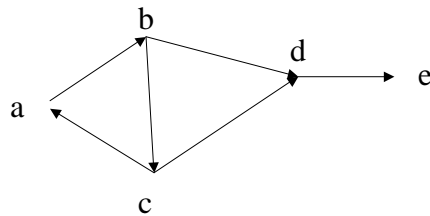
Similar examples

- Parts-components relation:
“find all subparts of some given part A”
- Parent/child relation
“find all of John’s descendants”

More general: transitive closure of a graph

G	A	B
	a	b
	c	a
	b	c
	

Find the pairs of nodes $\langle x,y \rangle$ that are connected by some directed path



a	b
a	d
a	e
b	d
b	e
.....	

Computing transitive closure T of G

“Find the pairs of nodes $\langle a,b \rangle$ that are connected in G”

Same as

“find pairs of nodes $\langle a,b \rangle$ at distance 1” UNION

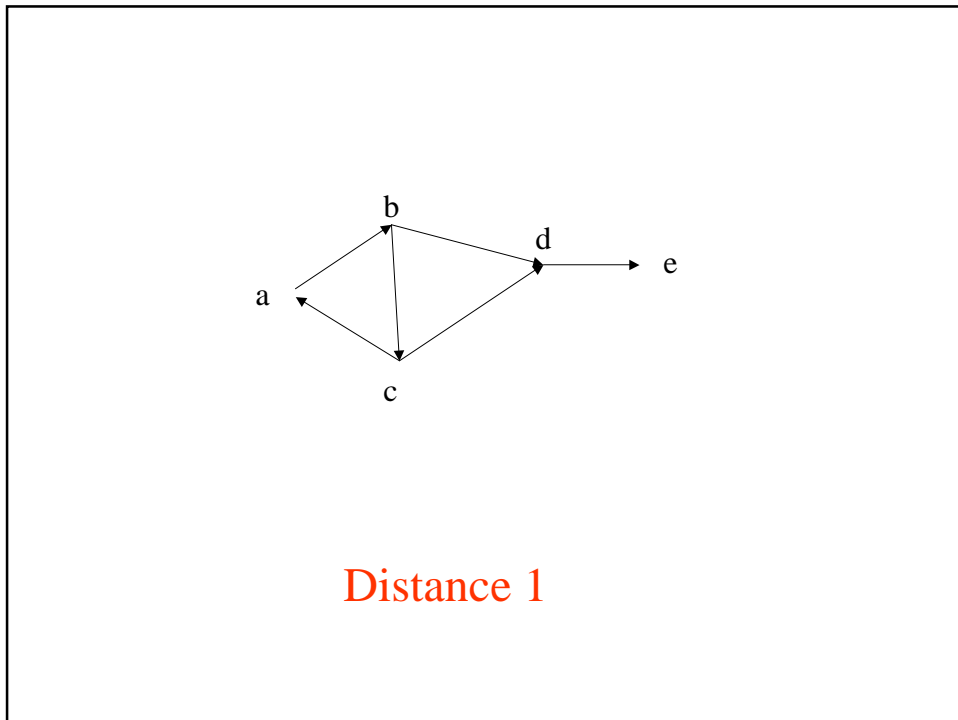
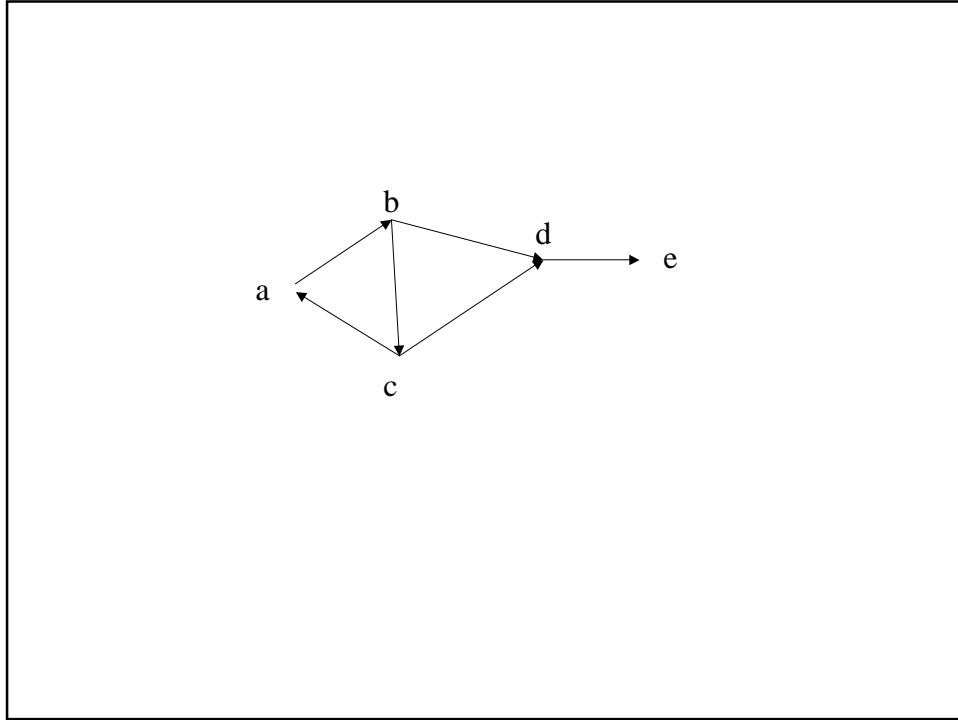
“find pairs of nodes $\langle a,b \rangle$ at distance at most 2” UNION

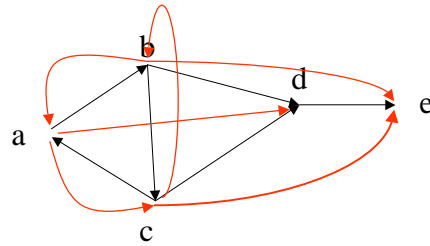
.....

“find pairs of nodes $\langle a,b \rangle$ at distance at most k” UNION

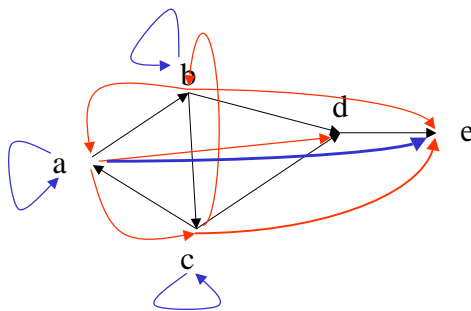
.....

When to stop? At some point, no new nodes are added.
Distance cannot be larger than total number of nodes in G.





Distance ≤ 2



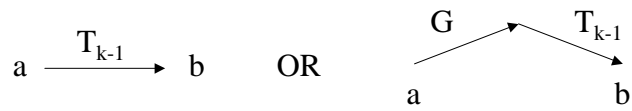
Distance ≤ 3

Denote by T_k the pairs of nodes at distance at most k

T_1 : “find pairs of nodes $\langle a,b \rangle$ at distance 1”

select * from G

T_k : “find the pairs of nodes $\langle a,b \rangle$ at distance at most k ”

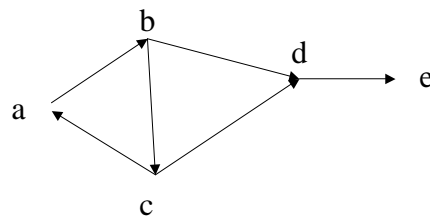


(select * from T_{k-1})

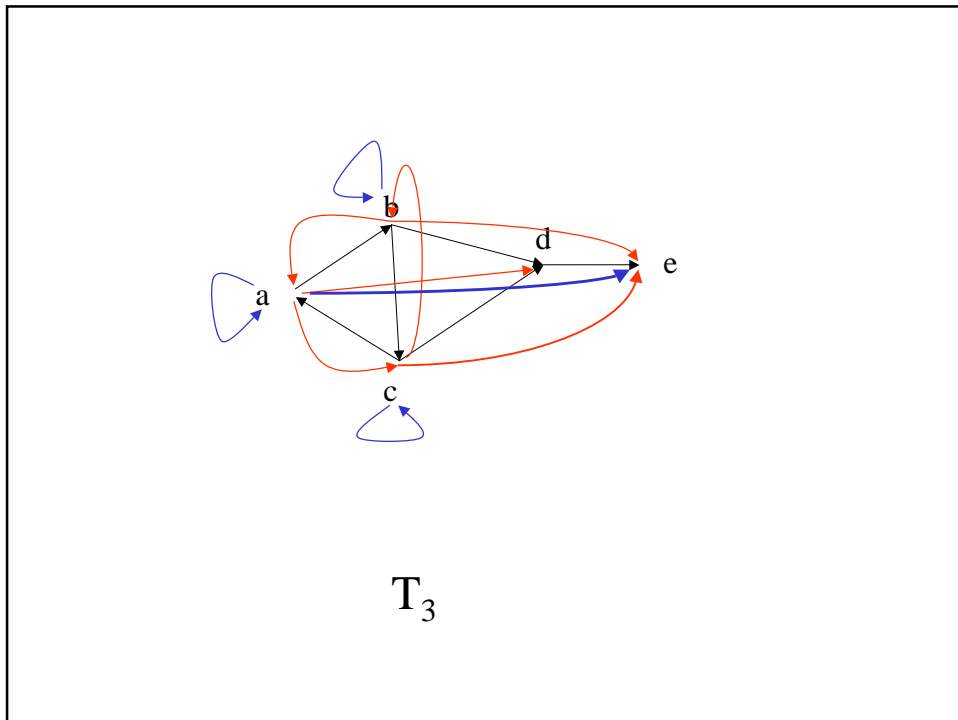
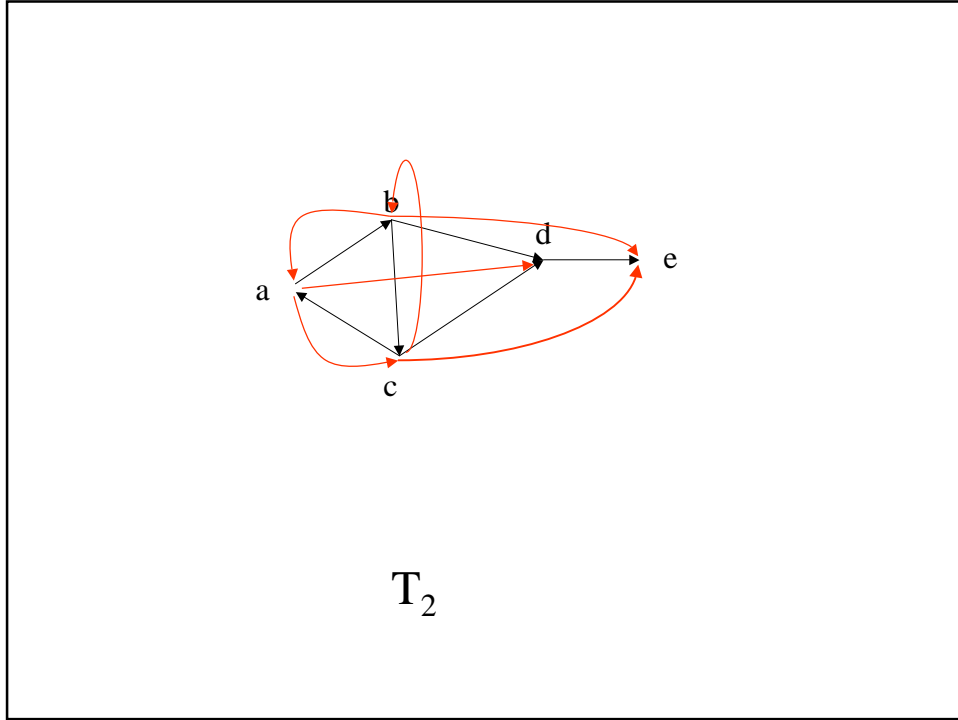
union

(select $x.A, y.B$ from G x, T_{k-1} y

where $x.B = y.A$)



T_1



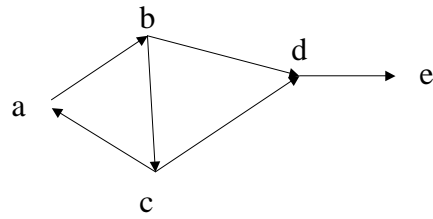
One solution: extend SQL with recursion

```
create view T as
(select * from G)
union
(select x.A, y.B
from G x, T y
where x.B = y.A)
```

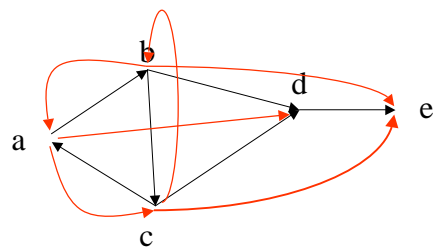
Another way: Embedded SQL

<pseudo-code>

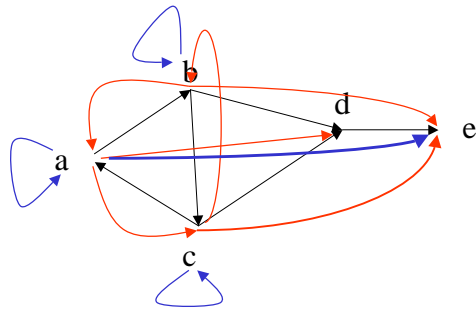
```
T := G
Δ := G
while Δ ≠ Φ do
  { Told = T
    T := (select * from T)
      union
      (select x.A, y.B from G x, T y
       where x.B = y.A)
    Δ := T - Told }
Output T
```



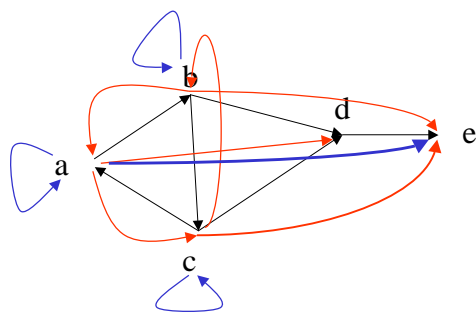
T_1 and Δ_1



T_2 and Δ_2



T_3 and Δ_3



$T_4 = T_3$ and $\Delta_4 = \Phi$
 stop!

Another way: Embedded SQL

<pseudo-code>

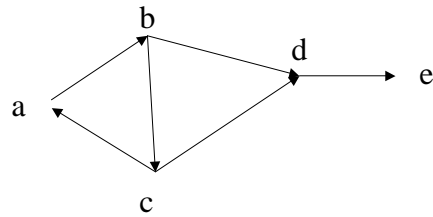
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    T := (select * from T)
      union
      (select x.A, y.B from G x, T y
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    Δ := T - Told }
Output T
```

Converges in **diameter(G)** iterations
(maximum distance between two nodes in G)

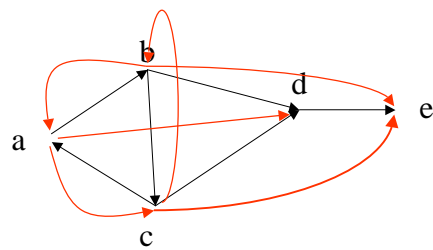
Optimization (“semi-naïve” evaluation):
use at least one new tuple (from Δ) every time

<pseudo-code>

```
T := G
Δ := G
while Δ ≠ Φ do
  { Told = T
    T := (select * from T)
      union
      (select x.A, y.B from G x, Δ y
        where x.B = y.A)
    Δ := T - Told }
Output T
```

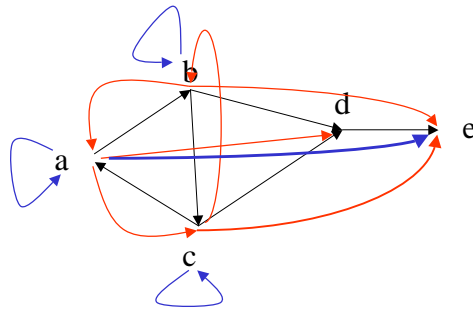


T_1 and Δ_1



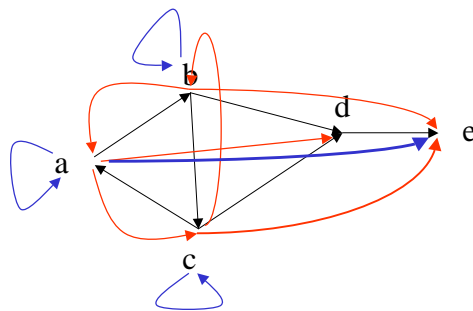
T_2 and Δ_2

No longer recompute $\langle c, b \rangle$ but recompute $\langle c, d \rangle$



T_3 and Δ_3

No longer recompute $\langle a,c \rangle$ but recompute $\langle c,e \rangle$



$T_4 = T_3$ and $\Delta_4 = \Phi$
stop!

Faster convergence (double recursion):

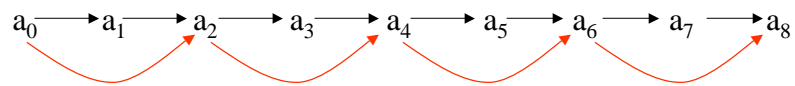
```
T := G
Δ := G
while Δ ≠ Φ do
  { Told = T
    T := (select * from T)
      union
      (select x.A, y.B from T x, T y
        where x.B = y.A)
    Δ := T - Told }
Output T
```

Converges in $\log(\text{diameter}(G))$ iterations

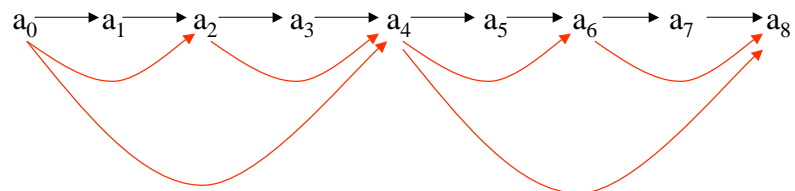
Example (focus on computing $\langle a_0, a_8 \rangle$)

$a_0 \longrightarrow a_1 \longrightarrow a_2 \longrightarrow a_3 \longrightarrow a_4 \longrightarrow a_5 \longrightarrow a_6 \longrightarrow a_7 \longrightarrow a_8$

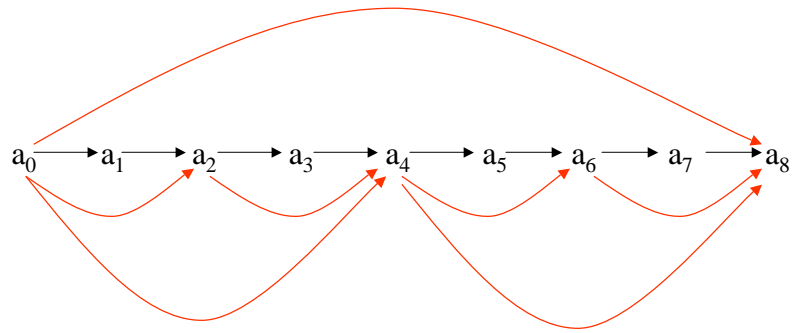
Example (focus on computing $\langle a_0, a_8 \rangle$)



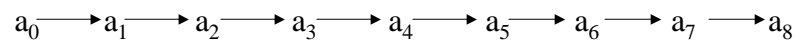
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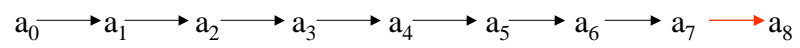
Example (focus on computing $\langle a_0, a_8 \rangle$)



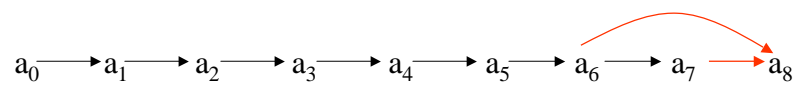
Compare to linear recursion (first program):



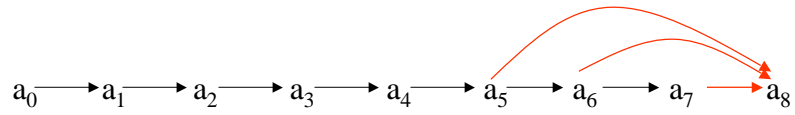
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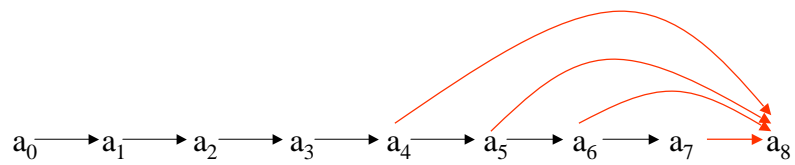
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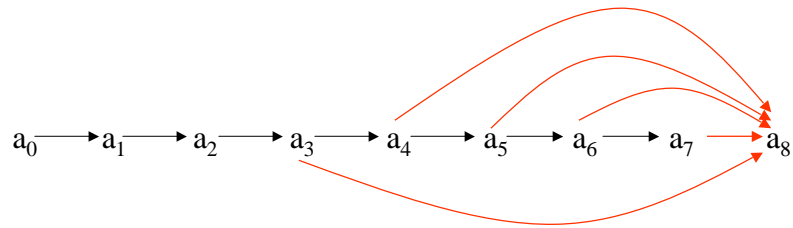
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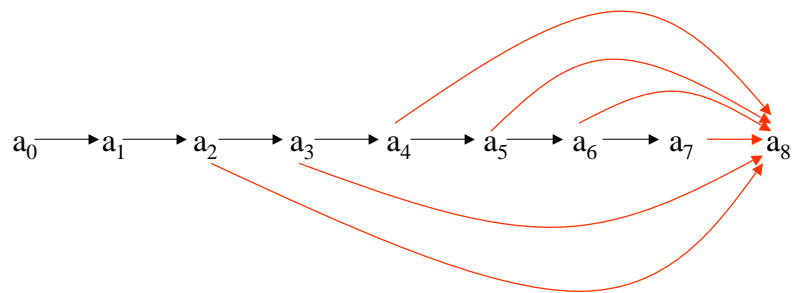
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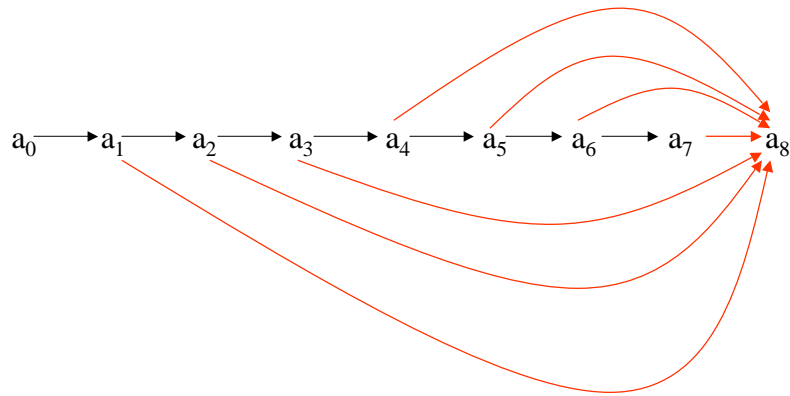
Compare to linear recursion (first program):



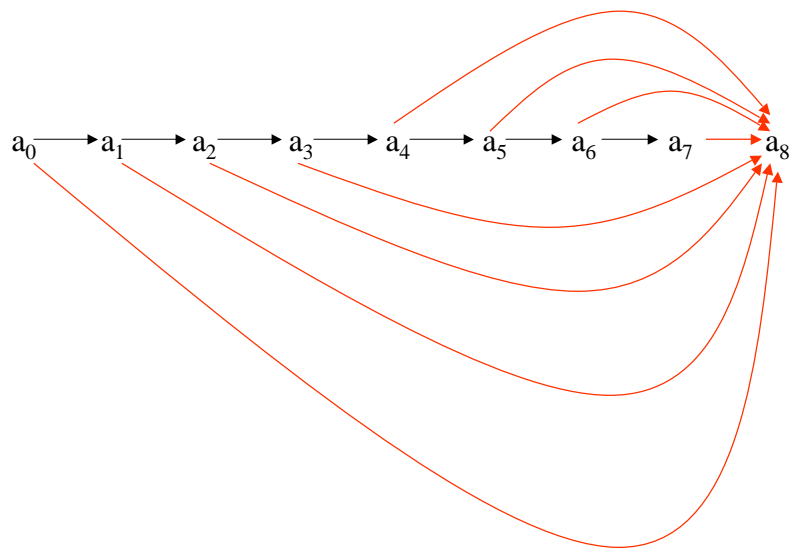
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Optimization (“semi-naïve” evaluation):
again, use at least one new tuple every time

```
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Δ := G
while Δ ≠ Φ do
  { Told = T
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        (select x.A, y.B from Δ x, T y
         where x.B = y.A)
        union
        (select x.A, y.B from T x, Δ y
         where x.B = y.A) }
  Δ := T - Told
Output T
```