#### CSE 250 Data Structures

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#### Lec 23: Heaps

#### Announcements

• PA2 autolab will be up tonight

# PriorityQueue ADT

PriorityQueue<T>

**void add(T value)** Insert **value** into the priority queue

T poll()

Remove the highest priority value in the priority queue

T peek()

Peek at the highest priority value in the priority queue

Two mentalities...

Lazy: Keep everything a mess ("Selection Sort")

**Proactive:** Keep everything organized ("Insertion Sort")

Operation	Lazy	Proactive
add	<i>O</i> (1)	<i>O</i> ( <i>n</i> )
poll	<i>O</i> ( <i>n</i> )	<i>O</i> (1)
peek	<i>O</i> ( <i>n</i> )	O(1)

Operation	Lazy	Proactive
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Can we do better?

Lazy - Fast add, Slow removal Proactive - Slow add, Fast removal

Lazy - Fast add, Slow removal
Proactive - Slow add, Fast removal
??? - Fast(-ish) add, Fast(-ish) removal

Idea: Keep the priority queue "kinda" sorted. Hopefully "kinda" sorted is cheaper to maintain than a full sort, but still gives us some of the benefits.

Idea: Keep the priority queue "kinda" sorted. Keep higher priority towards the front of the list, and keep the front of the list more sorted than the back...

# **Binary Heaps**

# **Challenge:** If we are only "kinda" sorting, how do we know which elements are actually sorted?

# **Binary Heaps**

**Idea:** Organize the priority queue as a *directed* tree! A directed edge from a to b means that  $a \ge b$ 

<u>Child</u> - An adjacent node connected by an out-edge

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Leaf - A node with no children

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**<u>Depth</u> (of a node)** - The number of edges from the root to the node

Depth (of a tree) - The maximum depth of any node in the tree

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**<u>Depth</u> (of a node)** - The number of edges from the root to the node

Depth (of a tree) - The maximum depth of any node in the tree

Level (of a node) - depth + 1

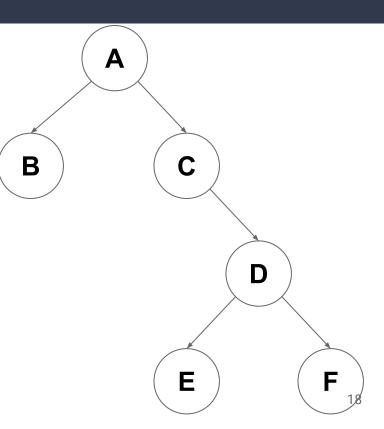
A is the root

B and C are children of AD is a child of CE and F are children of D

B, E and F are leaves

The depth of **A** is 0, **B** and **C**: 1, **D**: 2, **E** and **F**: 3

The depth of the tree is 3



Organize our priority queue as a directed tree **Directed:** A directed edge from a to b means that  $a \le b$ 

Organize our priority queue as a directed tree

**Directed:** A directed edge from *a* to *b* means that *a* ≤ *b* 

Binary: Max out-degree of 2 (easy to reason about)

Organize our priority queue as a directed tree

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**Complete:** Every "level" except the last is full (from left to right)

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Organize our priority queue as a directed tree

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This makes it easy to encode into an array (later today)

Organize our priority queue as a directed tree

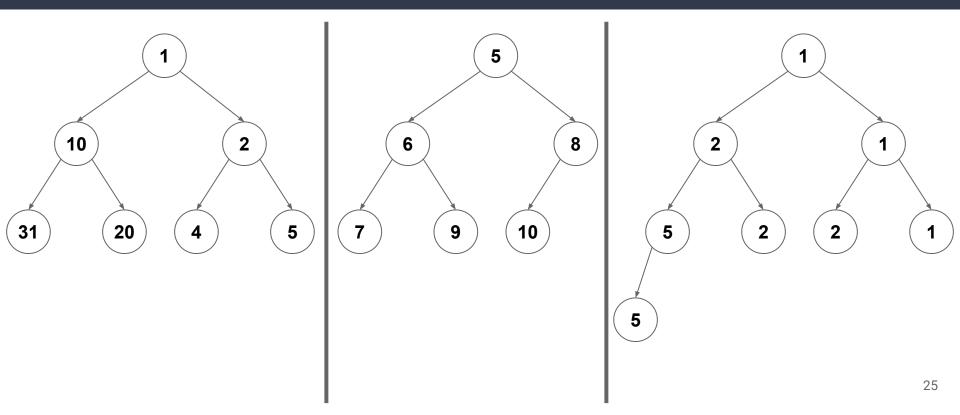
**Directed:** A directed edge from a to b means that  $a \le b$ **Binary:** Max out-degree of 2 (easy to reason about) A max heap would reverse this ordering

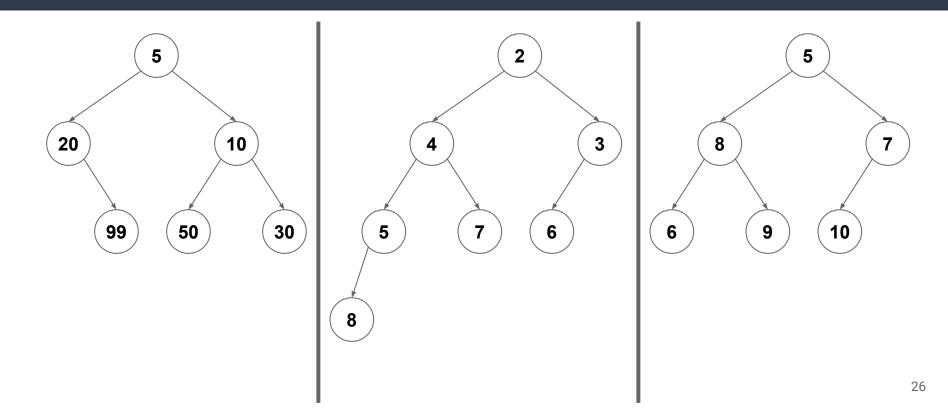
**Complete:** Every "level" except the last is full (from left to right)

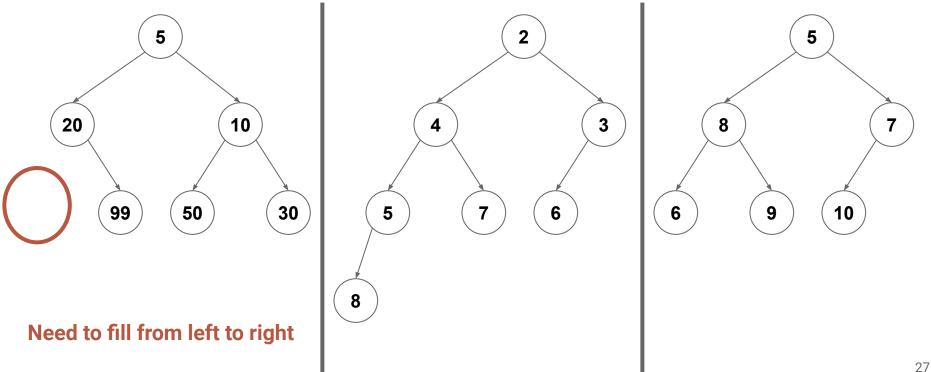
Balanced: TBD (basically, all leaves are roughly at the same level)

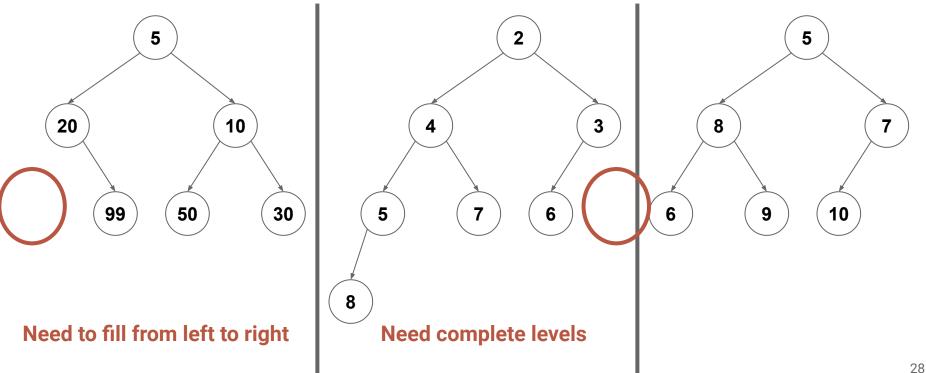
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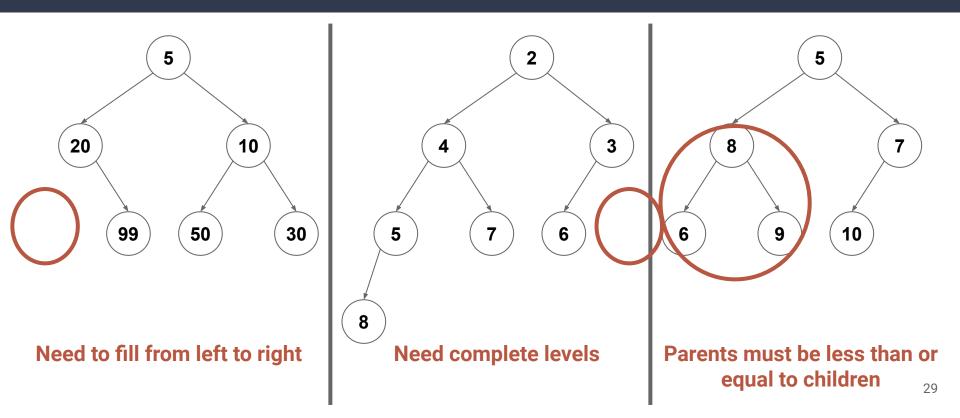
#### Valid Min Heaps











What is the depth of a binary heap containing **n** items? Level 1: holds up to 1 item

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**Level** *i*: holds up to  $2^{i-1}$  items

...

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$$n = O\left(\sum_{i=1}^{\ell_{max}} 2^i\right) = O\left(2^{\ell_{max}}\right)$$

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$$n = O\left(\sum_{i=1}^{\ell_{max}} 2^i\right) = O\left(2^{\ell_{max}}\right)$$

$$\ell_{max} = O\left(\log(n)\right)$$

## The MinHeap ADT

# void pushHeap(T value) Place an item into the heap

T popHeap() Remove and return the minimal element from the heap

T peek() Peek at the minimal element in the heap

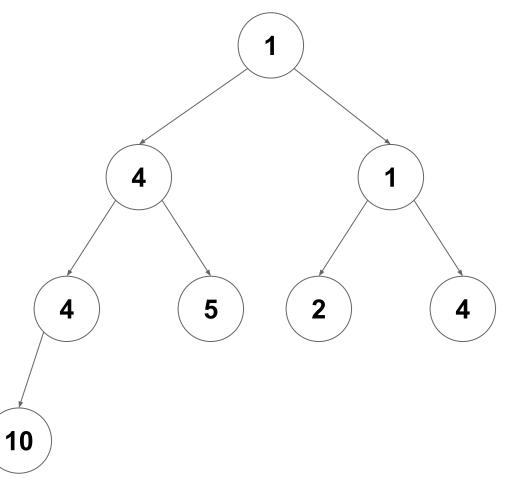
int size()
The number of elements in the heap

#### Idea: Insert the element at the next available spot, then fix the heap.

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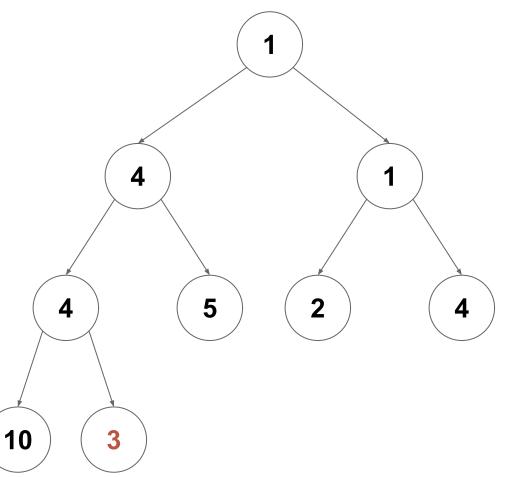
- 1. Call the insertion point current
- 2. While current != root and current < parent
  - a. Swap current with parent
  - b. Set current = parent

What if we add 3?



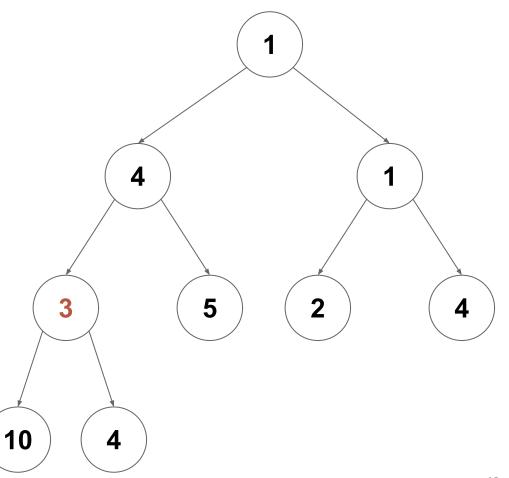
What if we add 3?

Place in the next available spot



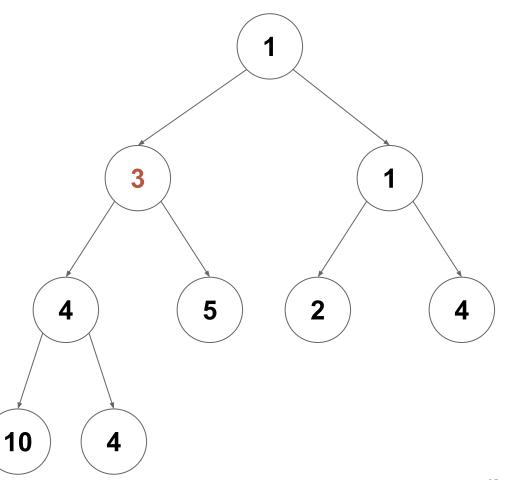
What if we enqueue 3?

Swap with parent if it is smaller than the parent



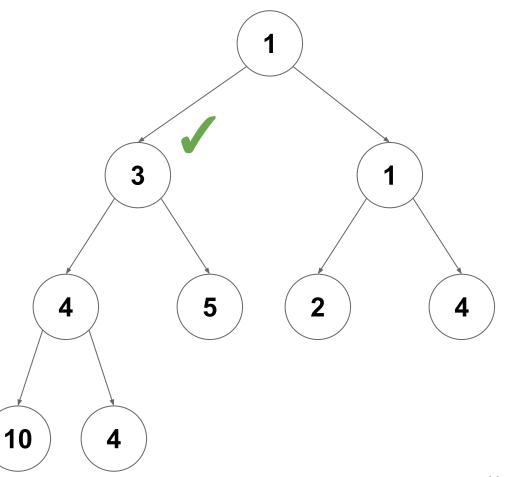
What if we enqueue 3?

Continue swapping upwards...



What if we enqueue 3?

Stop swapping when we are no longer smaller than our parent



Idea: Insert the element at the next available spot, then fix the heap.

- 1. Call the insertion point **current**
- 2. While current != root and current < parent
  - a. Swap current with parent
  - b. Set current = parent

What is the complexity (or how many swaps occur)?

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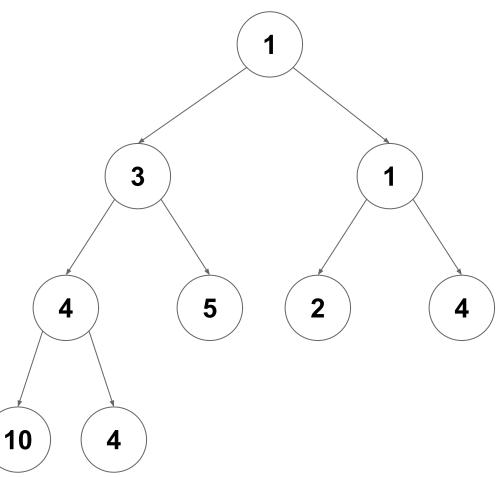
What is the complexity (or how many swaps occur)? **O(log(n))** 

#### Idea: Replace root with the last element then fix the heap

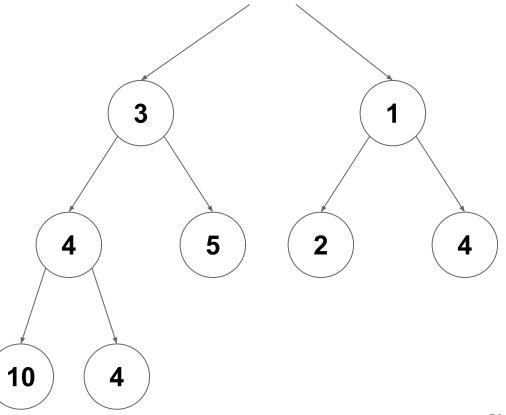
Idea: Replace root with the last element then fix the heap

- 1. Start with **current** = **root**
- 2. While current has a child < current
  - a. Swap current with its smallest child
  - b. Set current = child

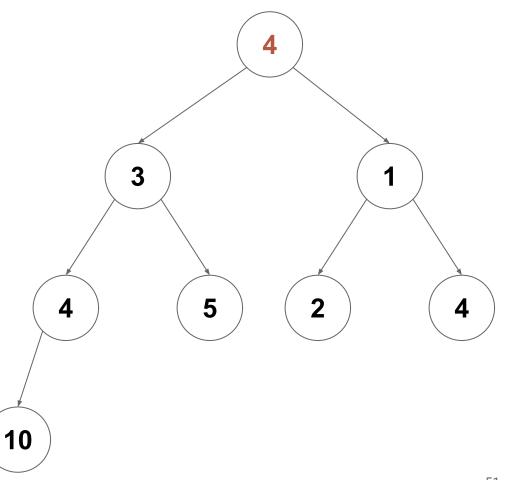
#### What if we call popHeap?



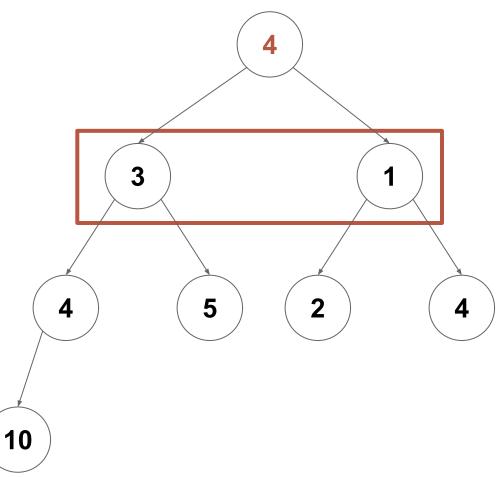
What if we call popHeap? Remove and return the root



What if we call popHeap? Make the last item the new root

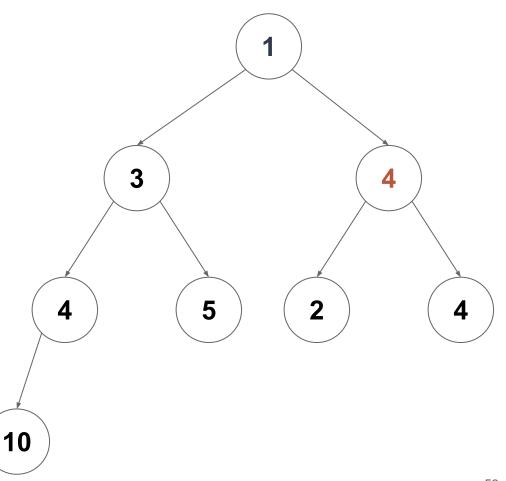


What if we call popHeap? Check for our smallest child



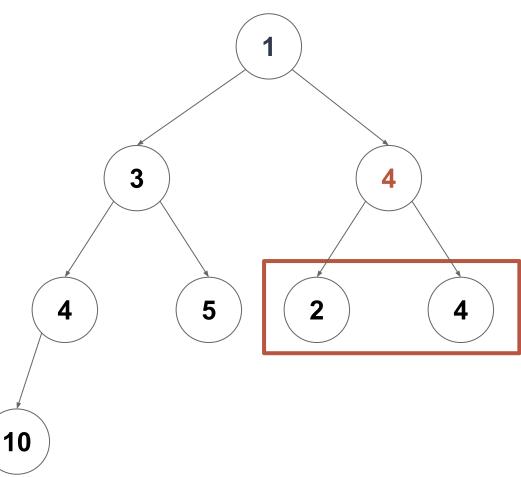
What if we call popHeap?

If the smallest child is smaller than us, swap



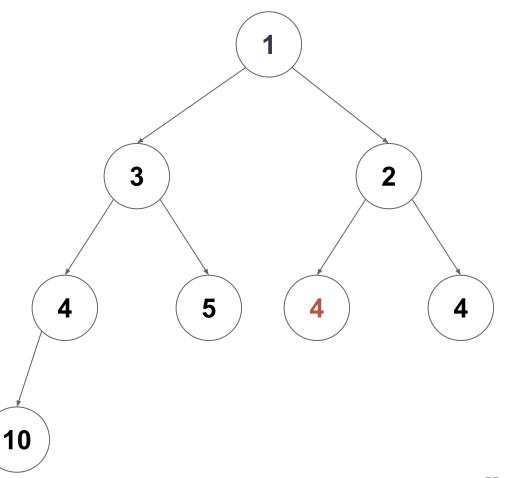
What if we call popHeap?

Continue swapping down the tree as necessary...



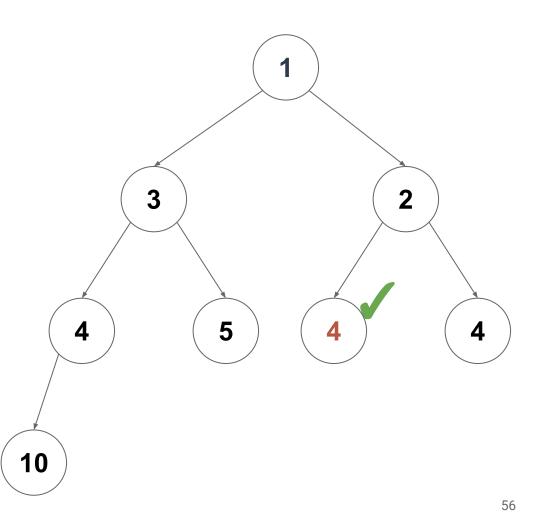
What if we call popHeap?

Continue swapping down the tree as necessary...



What if we call popHeap?

Stop swapping when our children are no longer bigger



Idea: Replace root with the last element then fix the heap

- 1. Start with **current = root**
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What is the complexity (or how many swaps occur)? **O(log(n))** 

## **Priority Queues**

Operation	Lazy	Proactive	Неар
add	<i>O</i> (1)	<i>O</i> ( <i>n</i> )	O(log( <i>n</i> ))
poll	<i>O</i> ( <i>n</i> )	O(1)	O(log( <i>n</i> ))
peek	<i>O</i> ( <i>n</i> )	O(1)	O(1)

#### Notice that:

- 1. Each level has a maximum size
- 2. Each level grows left-to-right
- 3. Only the last layer grows

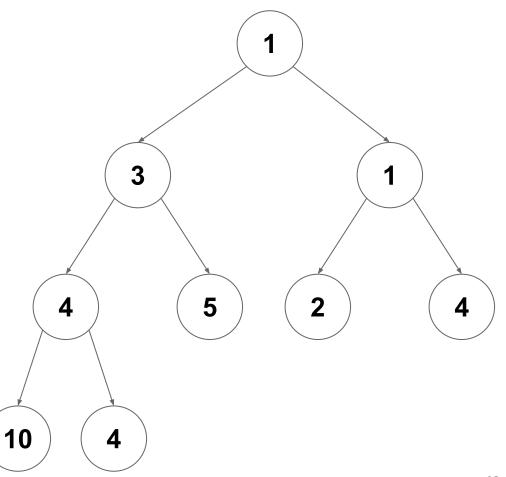
How can we compactly store a heap?

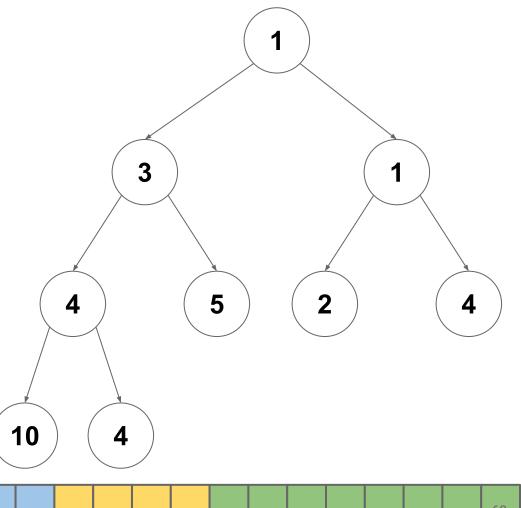
#### Notice that:

- 1. Each level has a maximum size
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How can we compactly store a heap?

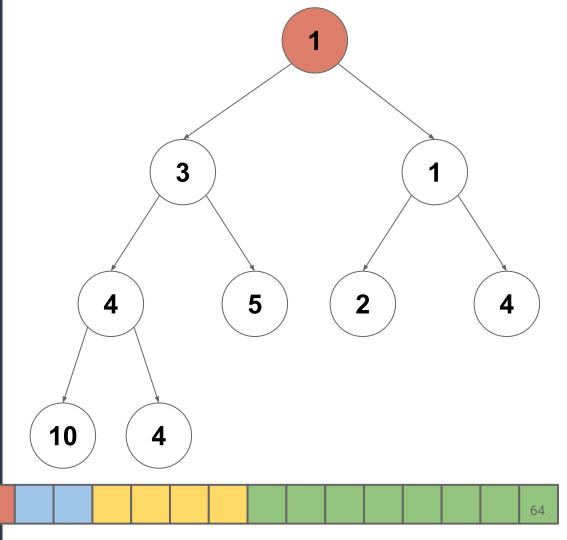
Idea: Use an ArrayList

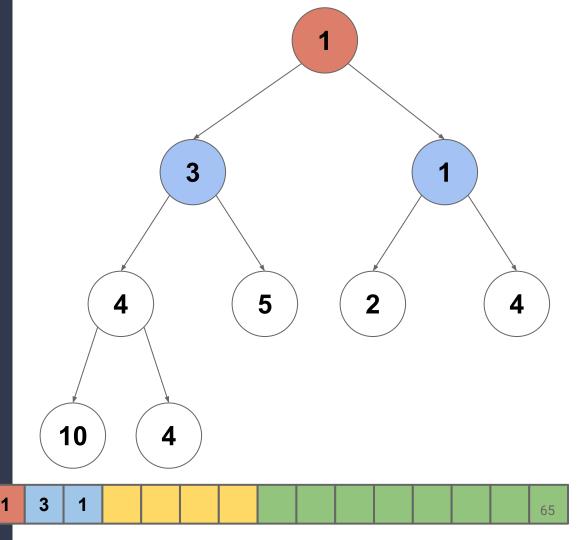




How can we store this heap in an array buffer?

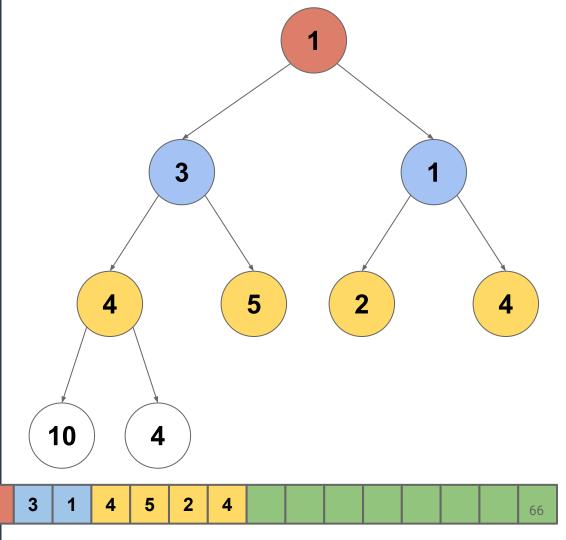
1

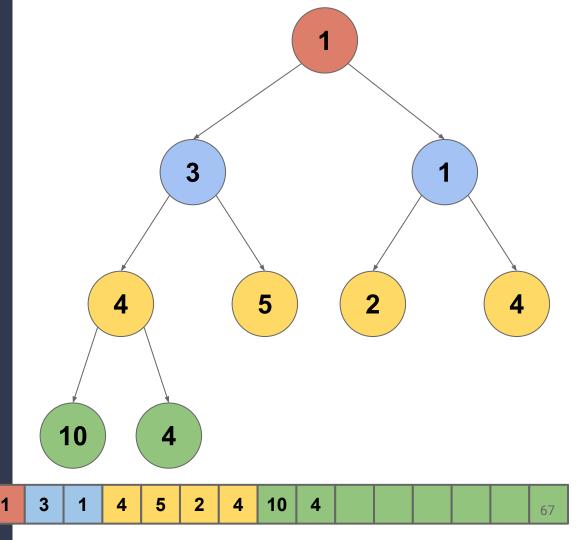


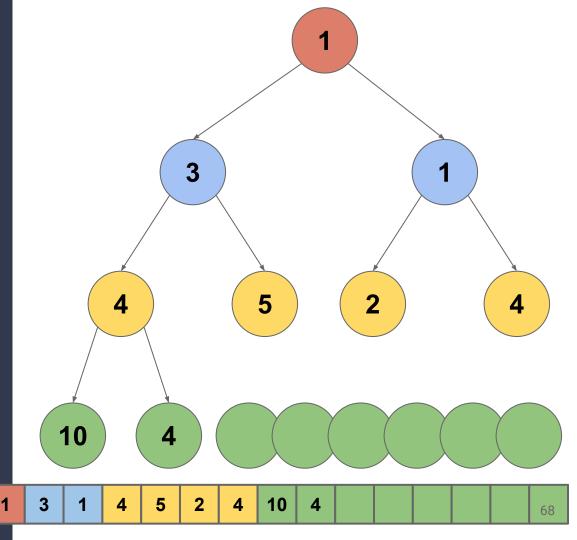


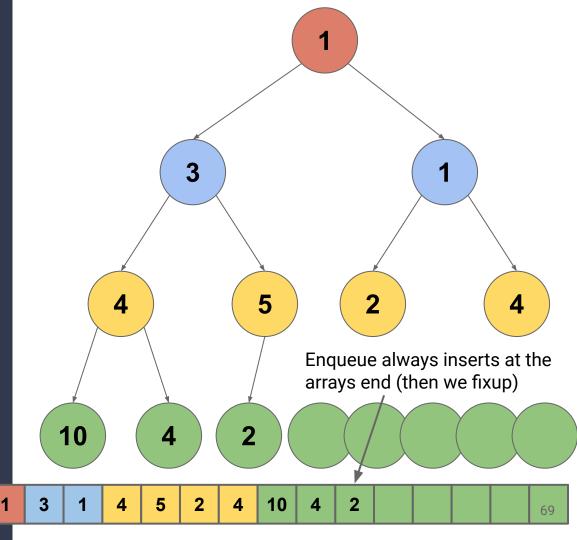
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1









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- **Total:** amortized O(log(n)) (unqualified O(n))

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• **Remove end of ArrayList:** *O*(1)

pushHeap

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- **Remove end of ArrayList:** *O*(1)
- **fixDown:**  $O(\log(n))$  fixes, each one costs  $O(1) = O(\log(n))$

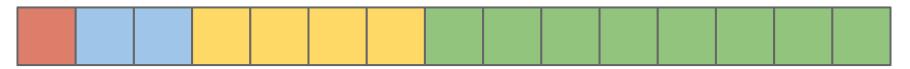
pushHeap

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- **fixUp:**  $O(\log(n))$  fixes, each one costs  $O(1) = O(\log(n))$
- **Total:** amortized O(log(n)) (unqualified O(n))

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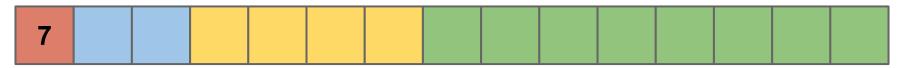
- **Remove end of ArrayList:** *O*(1)
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- **Total:** *O*(log(*n*))

- 1. Insert items into heap
- 2. Reconstruct sequence with dequeue



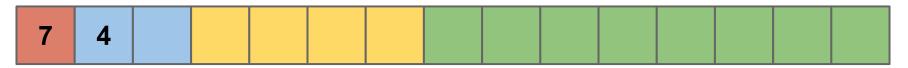
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<u>7</u>, 4, 8, 2, 5, 3, 9



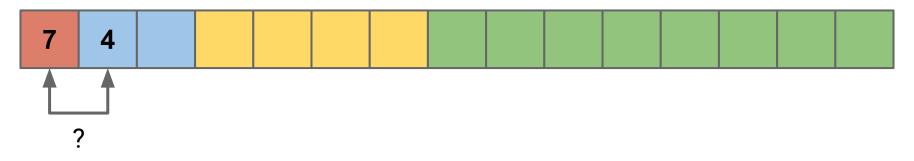
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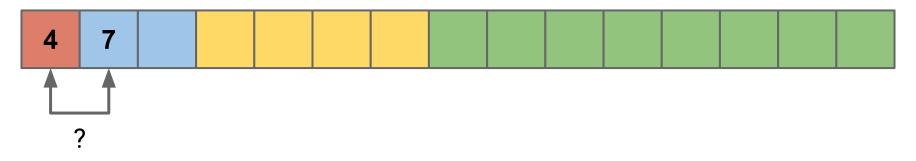
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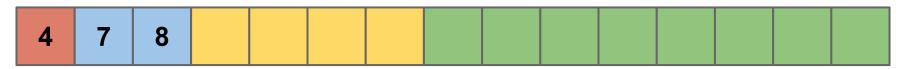
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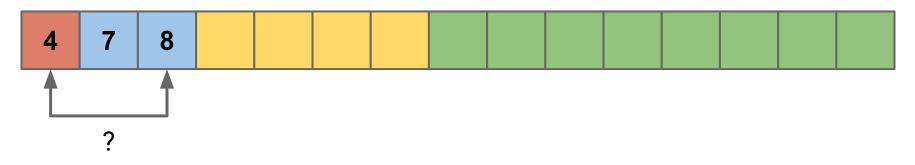
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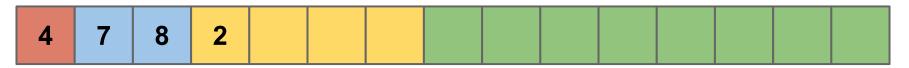


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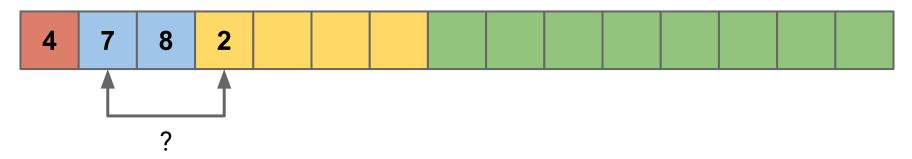
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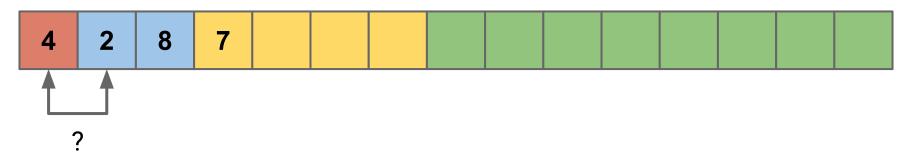
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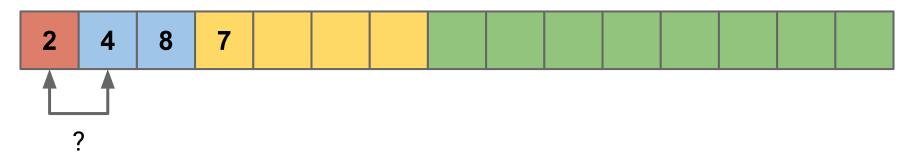
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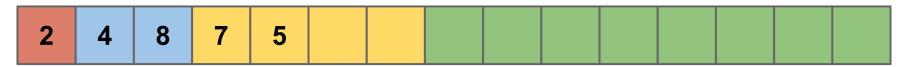


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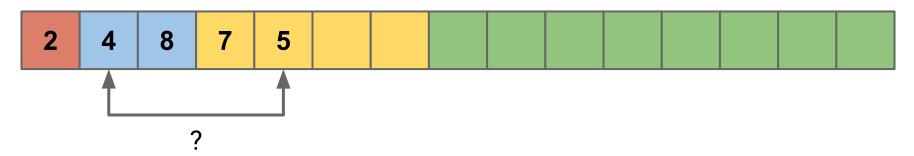


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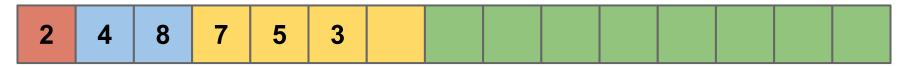


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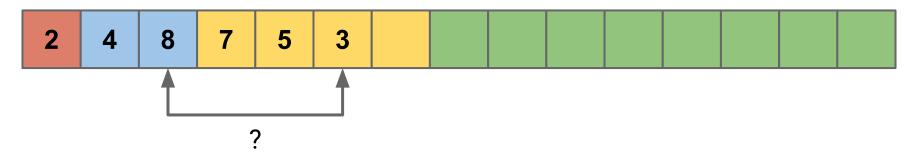


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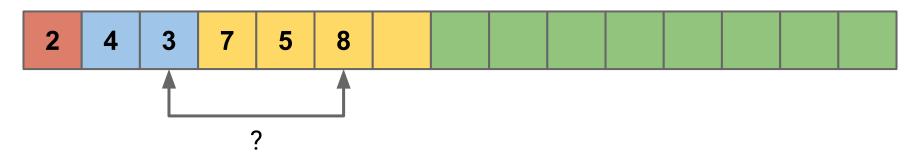
7, 4, 8, 2, 5, <u>3</u>, 9



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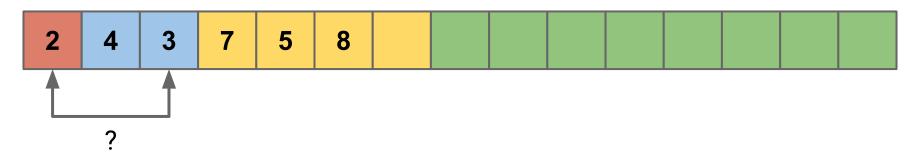


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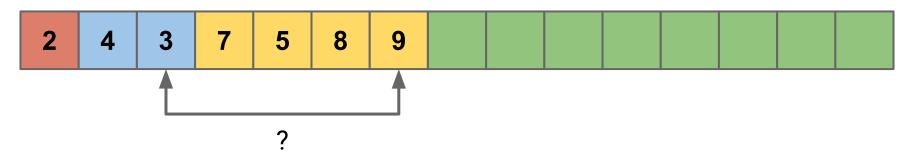
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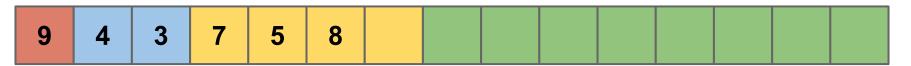
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2 4	3 7	7 5 8	9				
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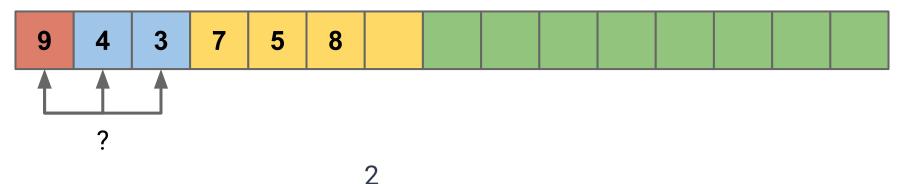
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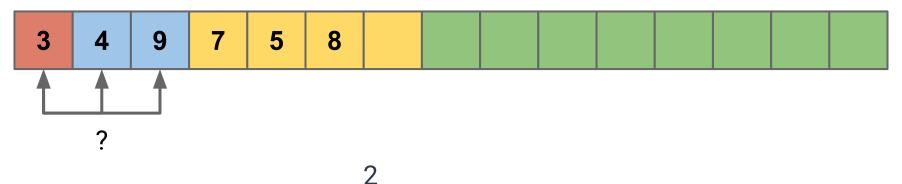
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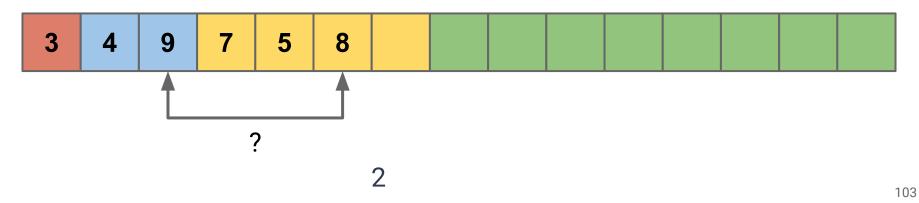
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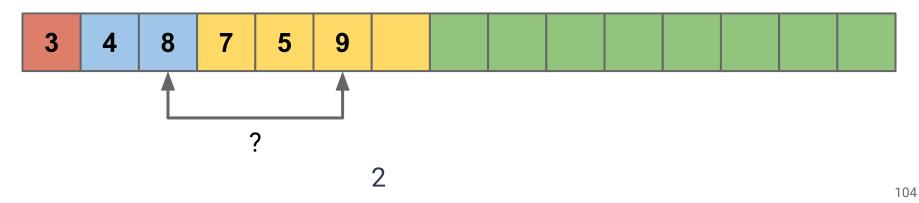
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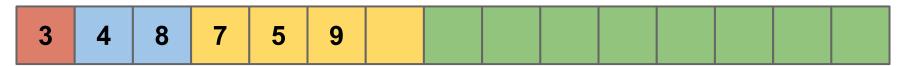
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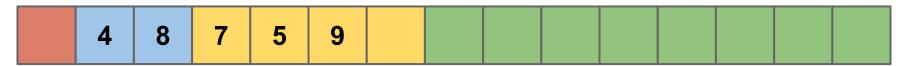
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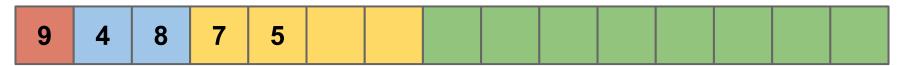
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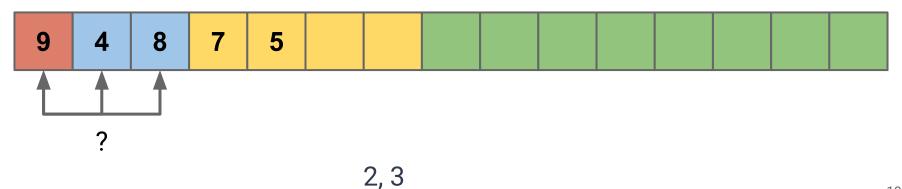
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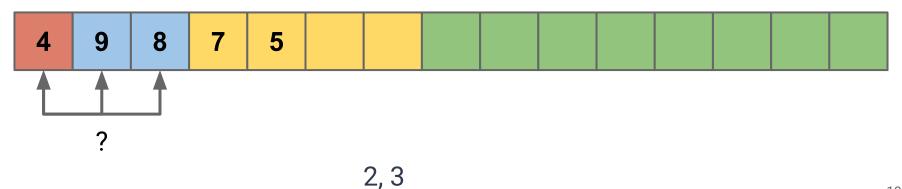
- 1. Insert items into heap
- 2. Reconstruct sequence with dequeue



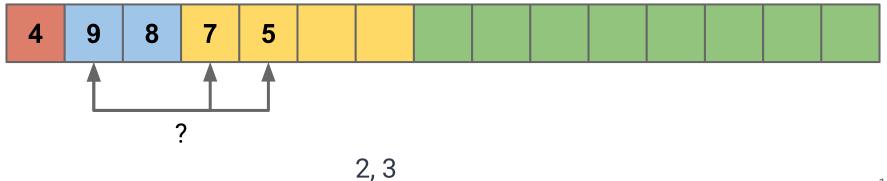
- 1. Insert items into heap
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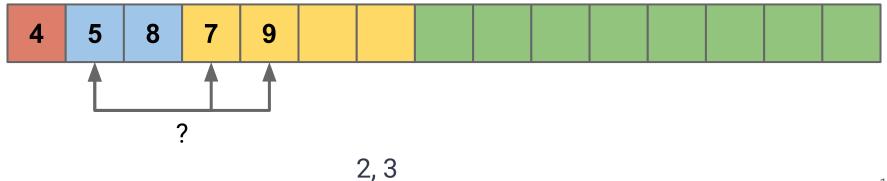
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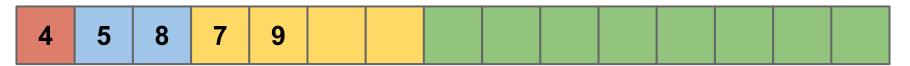
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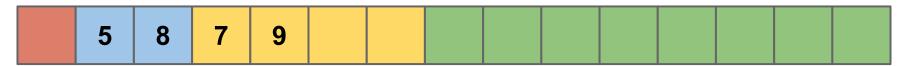
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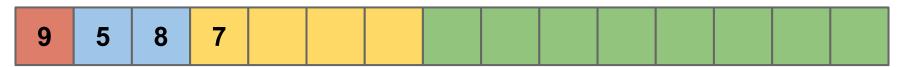
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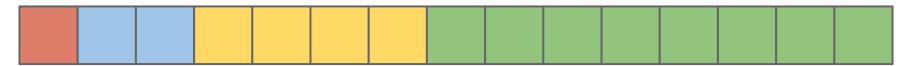
- 1. Insert items into heap
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### A few moments later...

- 1. Insert items into heap
- 2. Reconstruct sequence with dequeue

7, 4, 8, 2, 5, 3, 9



2, 3, 4, 5, 7, 8, 9

**Enqueue element** *i*:  $O(\log(i))$ 

Enqueue element *i*:  $O(\log(i))$ Dequeue element *i*:  $O(\log(n - i))$ 

Enqueue element *i*:  $O(\log(i))$ Dequeue element *i*:  $O(\log(n-i))$ 

$$\left(\sum_{i=1}^n O(\log(i))\right) + \left(\sum_{i=1}^n O(\log(n-i))\right)$$

Enqueue element *i*:  $O(\log(i))$ Dequeue element *i*:  $O(\log(n - i))$ 

$$\left(\sum_{i=1}^n O(\log(i))\right) + \left(\sum_{i=1}^n O(\log(n-i))\right) \quad < O(n\log(n))$$

# **Updating Heap Elements**

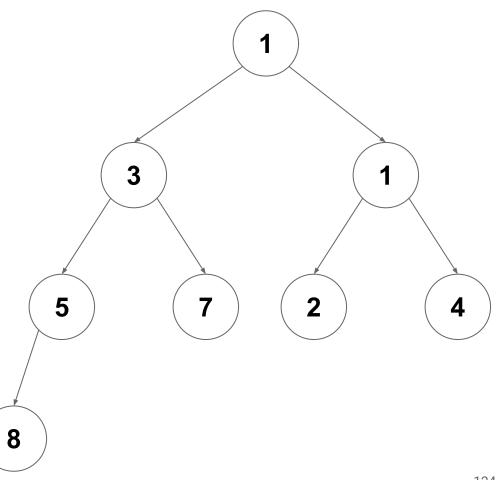
#### What if we want to update a value in our Heap?

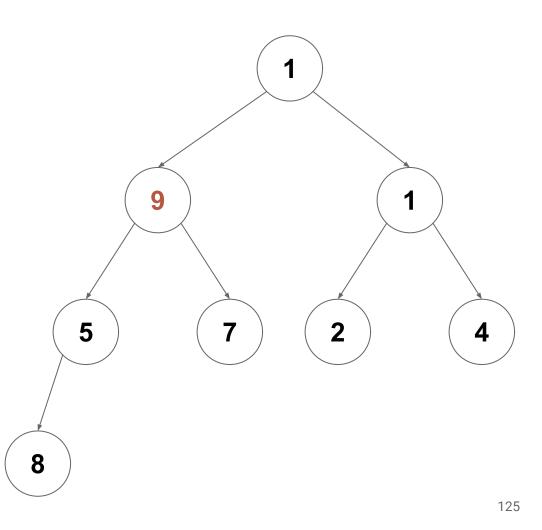
# **Updating Heap Elements**

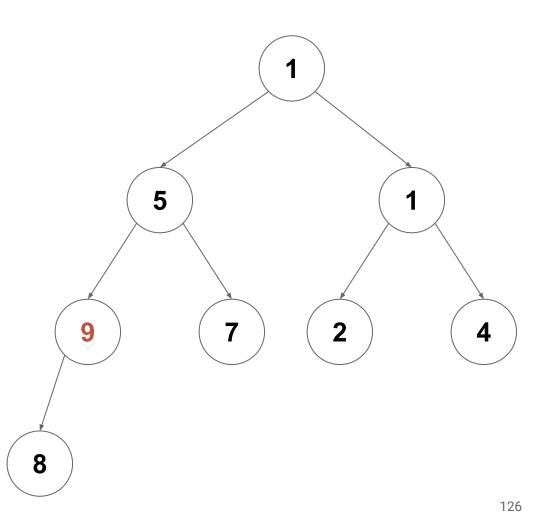
What if we want to update a value in our Heap?

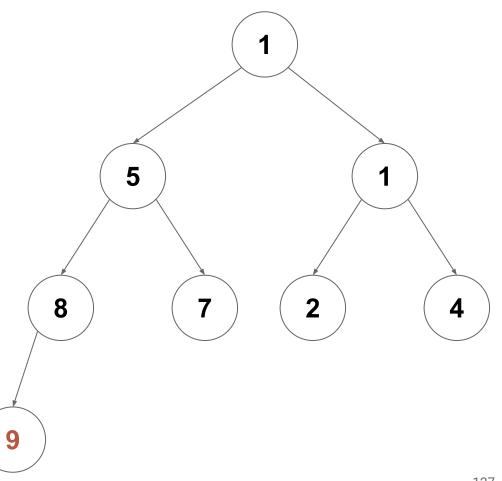
After update we can just call **fixUp** or **fixDown** based on the new value

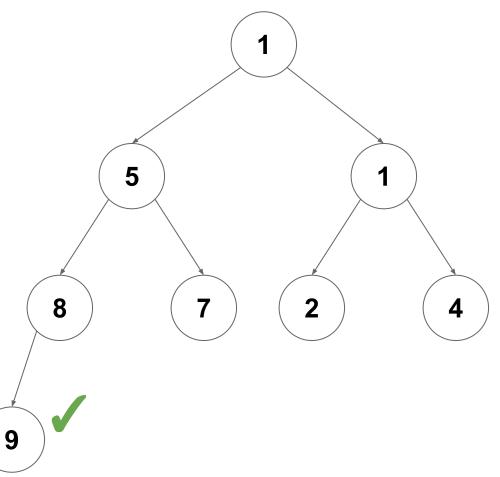
# What if we change the value of the 3 node to 9?











# **Updating Heap Elements**

What if we want to update a value in our Heap?

After update we can just call **fixUp** or **fixDown** based on the new value

# **Updating Heap Elements**

What if we want to update a value in our Heap?

After update we can just call fixUp or fixDown based on the new value

Can we apply this idea to an entire array?

#### Input: Array

#### **Output:** Array re-ordered to be a heap

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#### **Output:** Array re-ordered to be a heap

#### Idea: fixUp or fixDown all *n* elements in the array

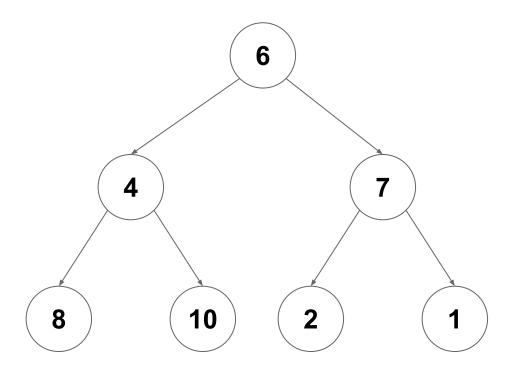
#### Input: Array

#### **Output:** Array re-ordered to be a heap

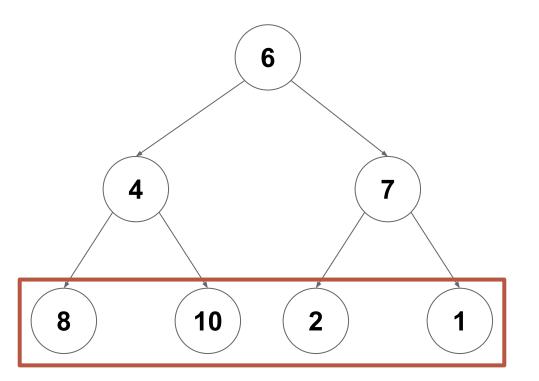
#### **Idea:** fixUp or fixDown all *n* elements in the array

#### Given the cost of **fixUp** and **fixDown** what do we expect the complexity **Heapify** will be?

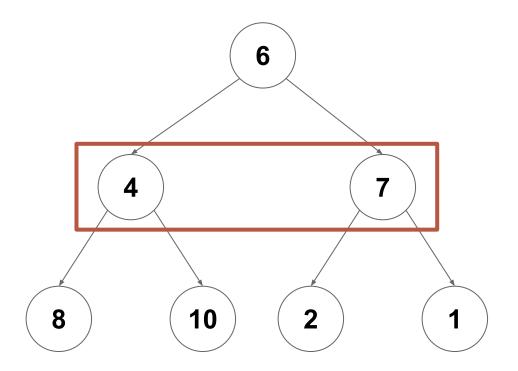
Given an arbitrary array (shown as a tree here) turn it into a heap



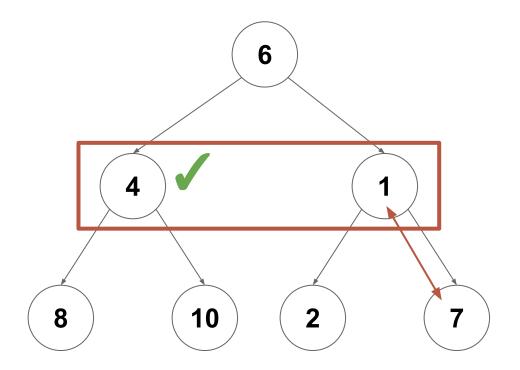
Start at the lowest level, and call **fixDown** on each node (0 swaps per node)

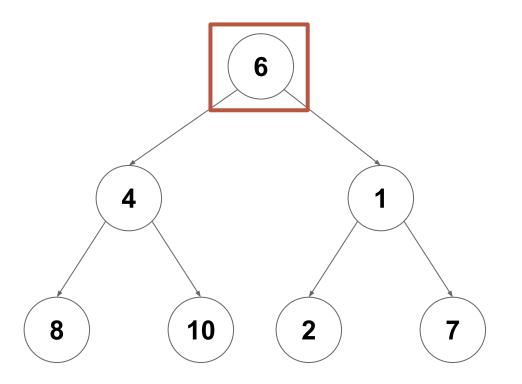


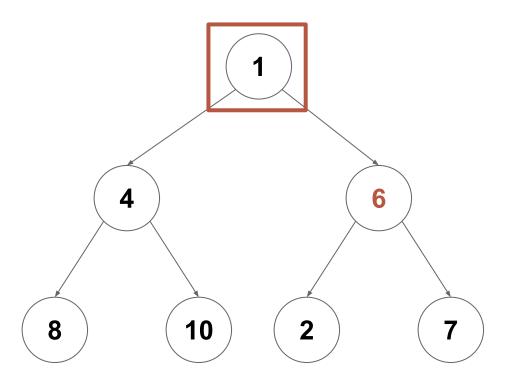
Do the same at the next lowest level (at most one swap per node)

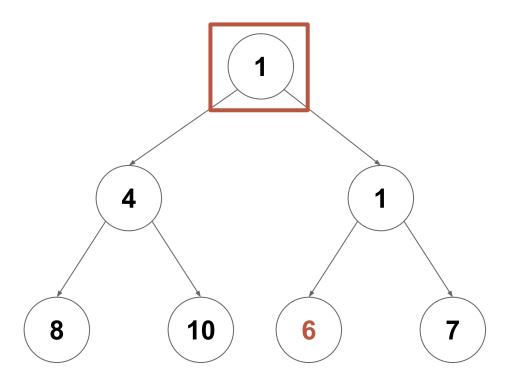


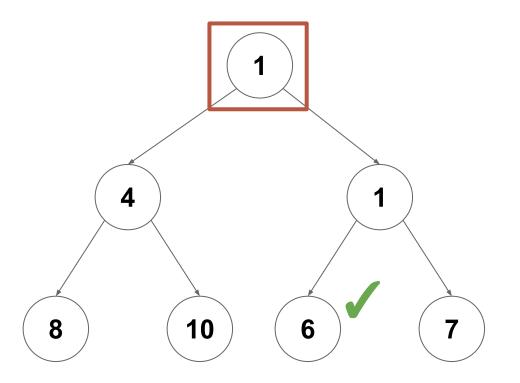
Do the same at the next lowest level (at most one swap per node)











At level log(n): Call fixDown on all n/2 nodes at this level (max 0 swaps each)

At level log(n): Call fixDown on all n/2 nodes at this level (max 0 swaps each) At level log(n)-1: Call fixDown on all n/4 nodes at this level (max 1 swaps each)

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At level log(n): Call fixDown on all n/2 nodes at this level (max 0 swaps each) At level log(n)-1: Call fixDown on all n/4 nodes at this level (max 1 swaps each) At level log(n)-2: Call fixDown on all n/8 nodes at this level (max 2 swaps each)

At level 1: Call fixDown on all 1 nodes at this level (max log(n) swaps each)

...

Sum the number of swaps required by each level

 $O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$ 

Pull out the *n* as a constant and distribute multiplication

 $O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i} + \frac{1}{2^i}\right)$ 

Focus on the dominant term only

 $O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i} + \frac{1}{2^i}\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i}\right)$ 

Change log(n) to infinity (can only increase complexity class if anything)

 $O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i}+\frac{1}{2^i}\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i}\right)$  $O\left(n\sum_{i=1}^{\infty}\frac{i}{2^{i}}\right)$ 

We can now treat the sum as a constant

 $O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i}+\frac{1}{2^i}\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i}\right)$ 

This is known to converge to a constant

Therefore we can heapify an array of size n in O(n)

 $O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i}+\frac{1}{2^i}\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i}\right)$  $O\left(n\sum_{i=1}^{\infty}\frac{i}{2^{i}}\right) = O\left(n\right)$ 

Therefore we can heapify an array of size n in O(n)

(but heap sort still requires *n* log(*n*) due to dequeue costs)

 $O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i} + \frac{1}{2^i}\right)$  $O\left(n\sum_{i=1}^{\log(n)}\frac{i}{2^i}\right)$  $O\left(n\sum_{i=1}^{\infty}\frac{i}{2^{i}}\right) = O\left(n\right)$