

CSE 250

Data Structures

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Lec 26: More Tree Operations

Announcements

- PA2 was due last night, submissions close Tuesday
- WA4 comes out today – Due Sunday
- Classes cancelled Monday for the Eclipse
 - Recitation next week is midterm review, no attendance required
 - If you have recitation on Monday but still want to attend, you may attend a Tuesday recitation (as long as there is space)
- TA hiring starting soon – If you want to join 250 course staff email me!

Collection ADTs

Property	Seq	Set	Bag
Explicit Order	✓		
Enforced Uniqueness		✓	
Iterable	✓	✓	✓

BST Operations

Operation	Runtime
find	$O(d)$
insert	$O(d)$
remove	$O(d)$

BST Operations

Operation	Runtime
find	$O(d)$
insert	$O(d)$
remove	$O(d)$

What is the runtime in terms of n ? $O(n)$

What about the lower bound? $\Omega(\log(n))$

*Can we do better? **TBD...***

Collection ADTs

Property	Seq	Set	Bag
Explicit Order	✓		
Enforced Uniqueness		✓	
Iterable	✓	✓	✓

Tree Traversals

Goal: Visit every element of a tree (in linear time?)

Pre-Order (top-down)

Visit the **root**, then the **left** subtree, then the **right** subtree

In-Order

Visit the **left** subtree, then the **root**, then the **right** subtree

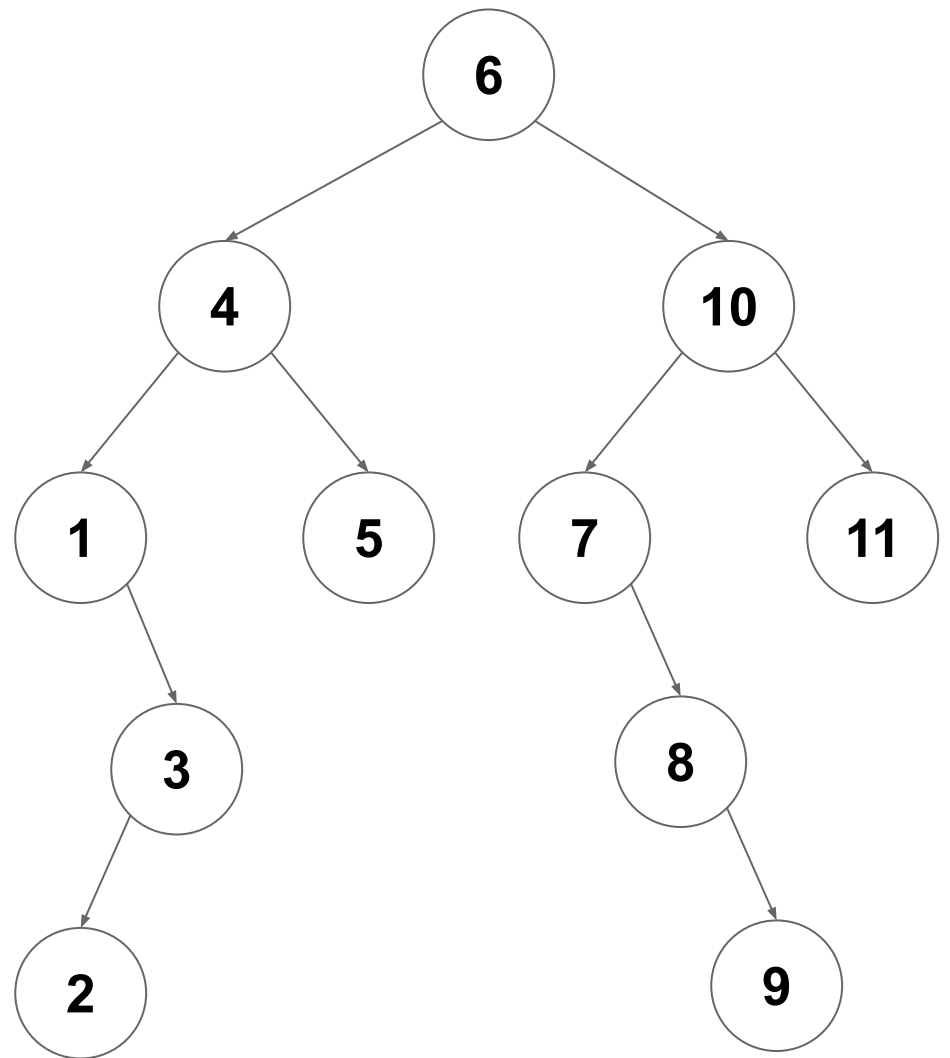
Post-Order (bottom-up)

Visit the **left** subtree, then the **right** subtree, then the **root**

Tree Traversal: In-Order

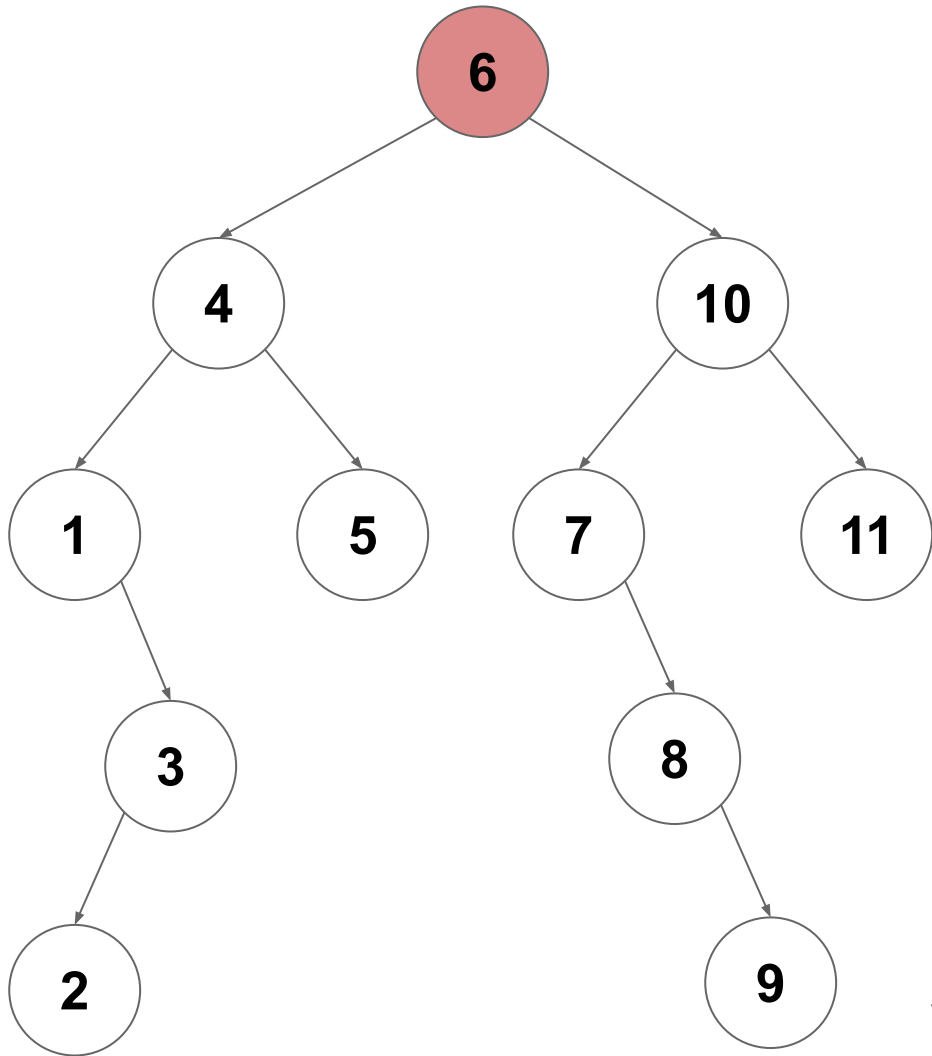
```
1 void inOrderVisit(Optional<TreeNode<T>> root, Visitor v) {  
2     if (root.isPresent()) {  
3         inOrderVisit(root.get().leftChild, v);  
4         v.visit(root.get().value);  
5         inOrderVisit(root.get().rightChild, v);  
6     }  
7 }
```


In-Order Traversal on a BST



In-Order Traversal on a BST

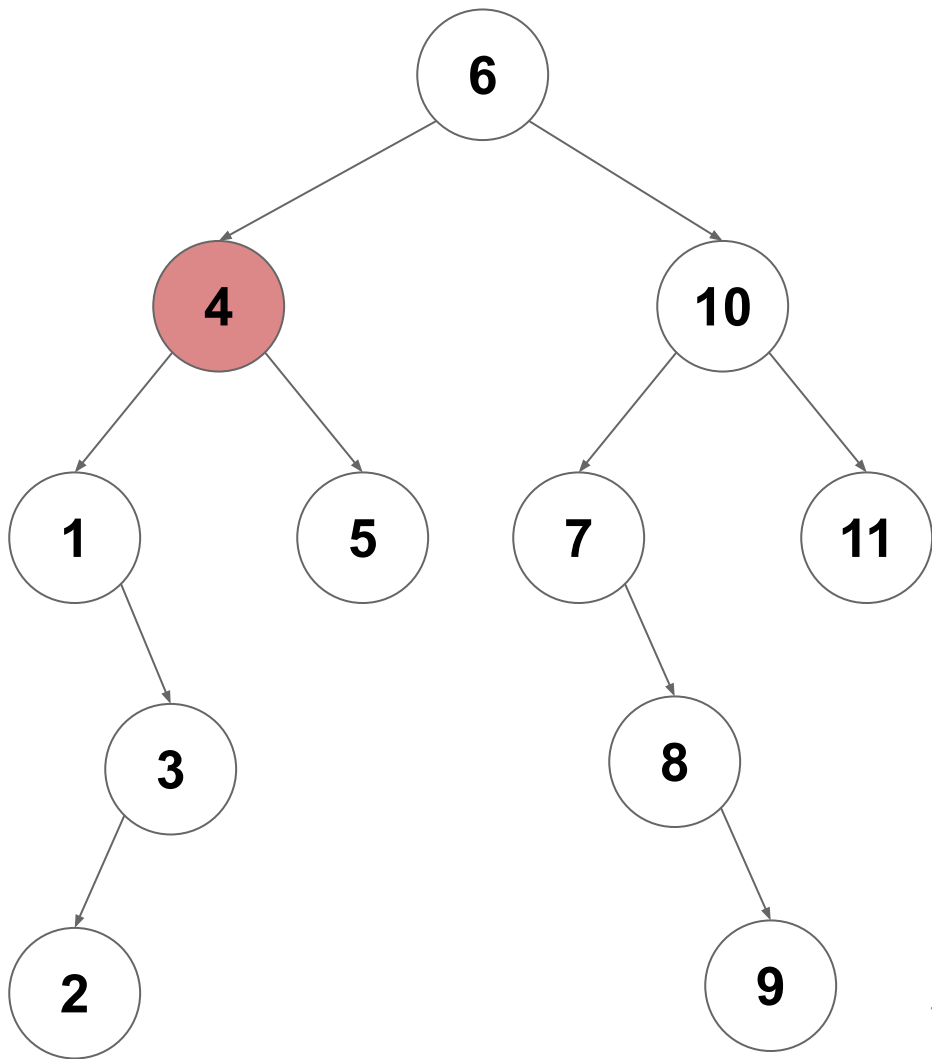
`inorderVisit(6)`



In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

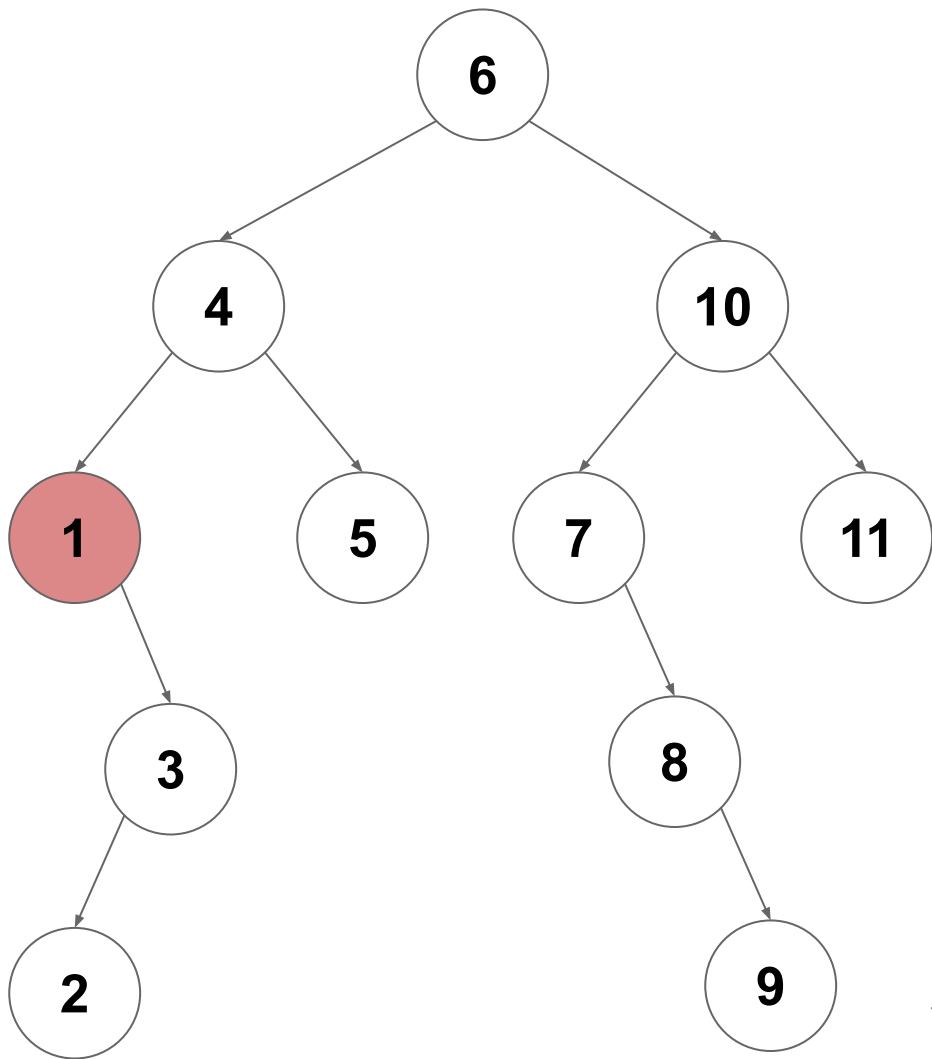


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(1)`



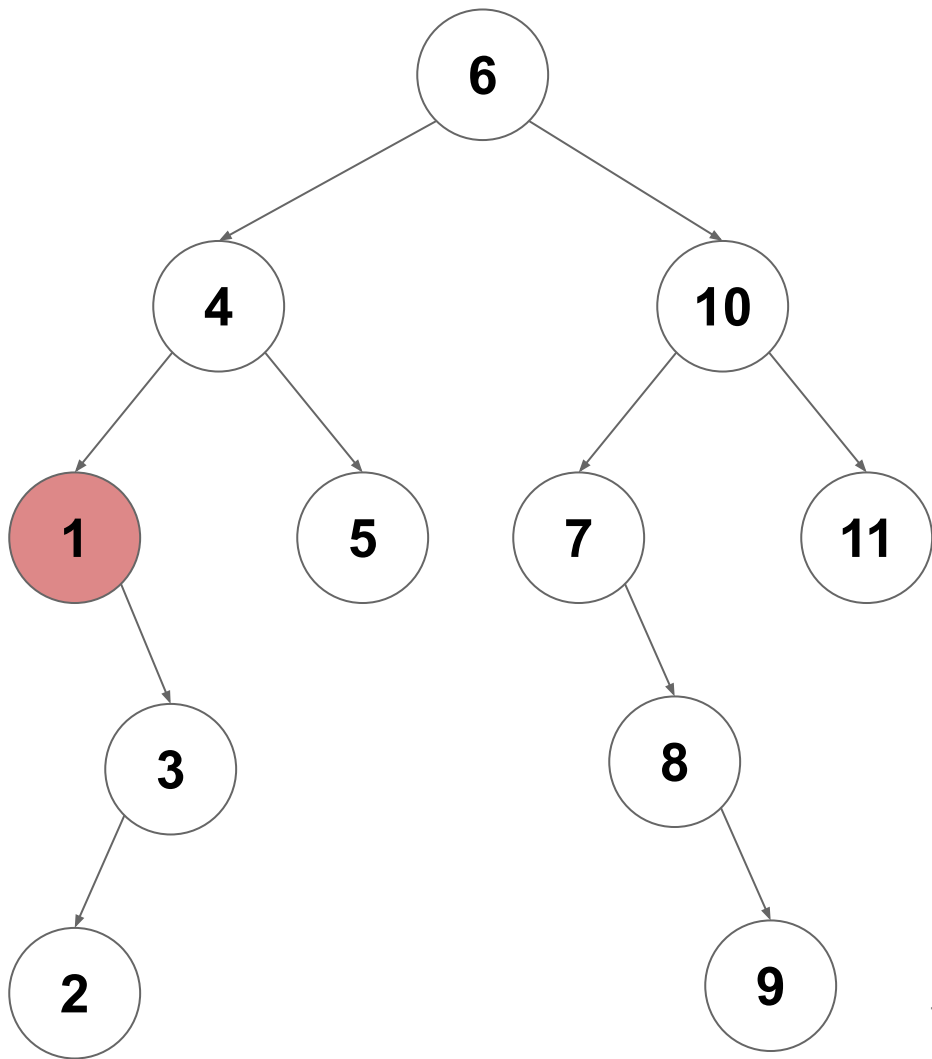
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(1)`

`inorderVisit(empty)`



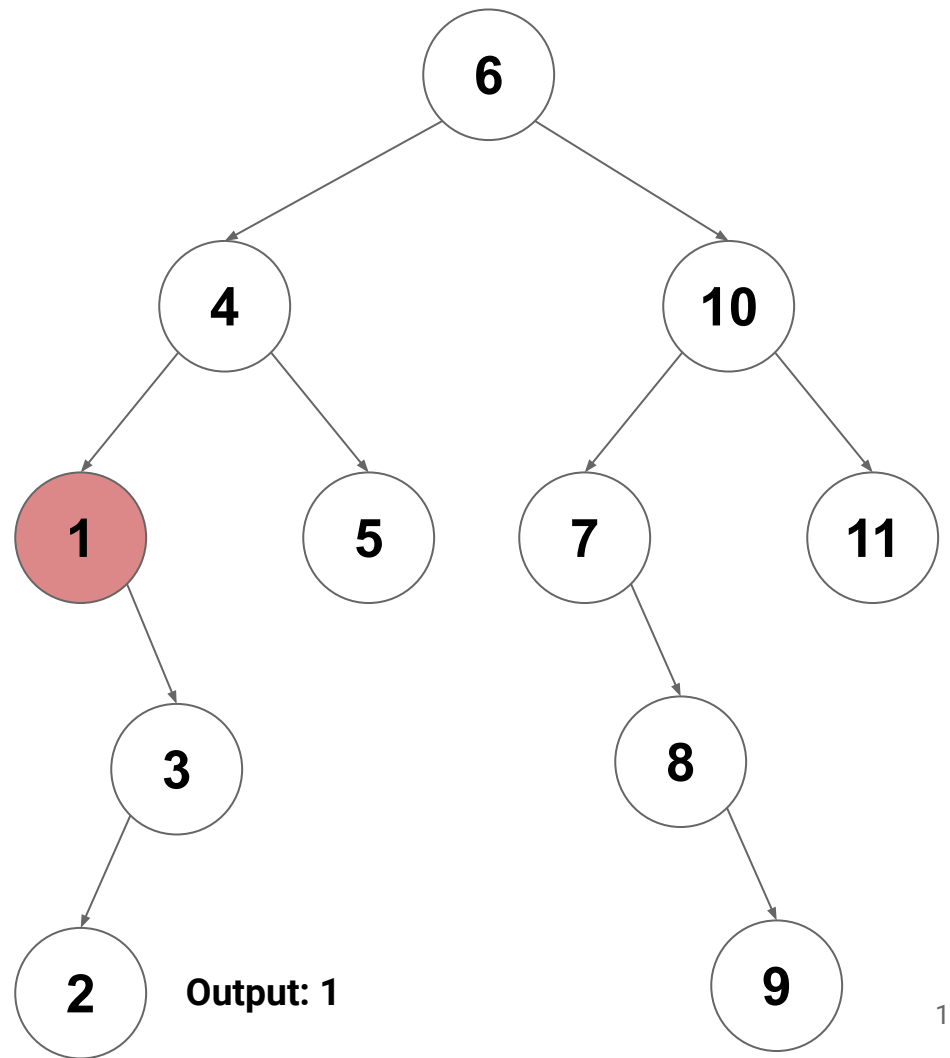
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(1)`

`visit(1)`



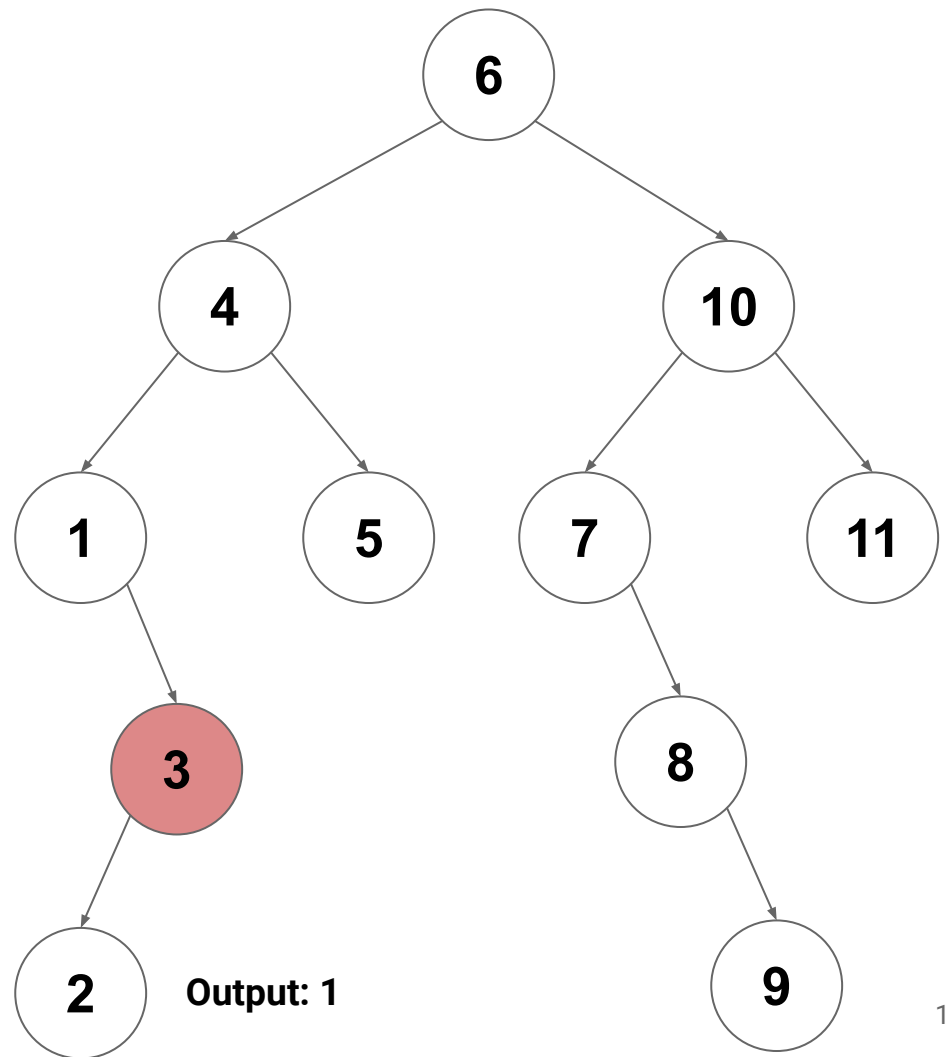
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(1)`

`inorderVisit(3)`



In-Order Traversal on a BST

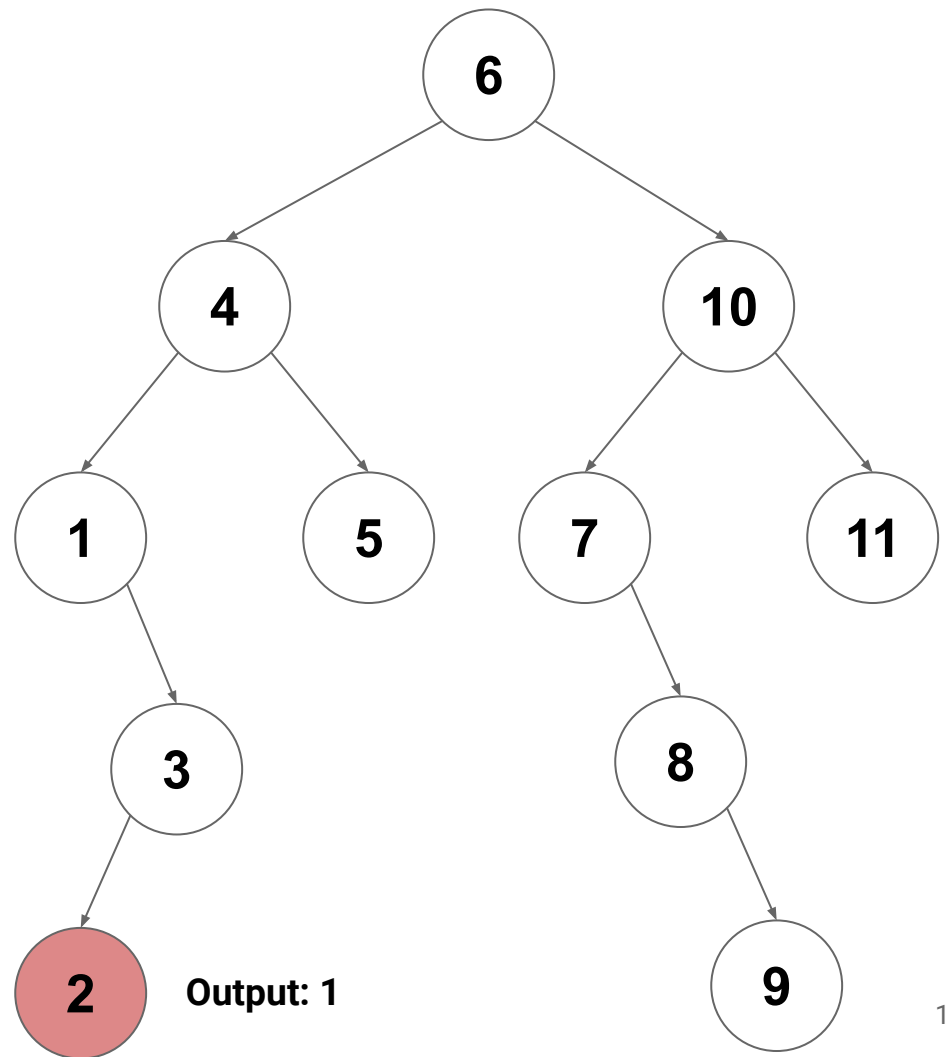
`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(1)`

`inorderVisit(3)`

`inorderVisit(2)`



In-Order Traversal on a BST

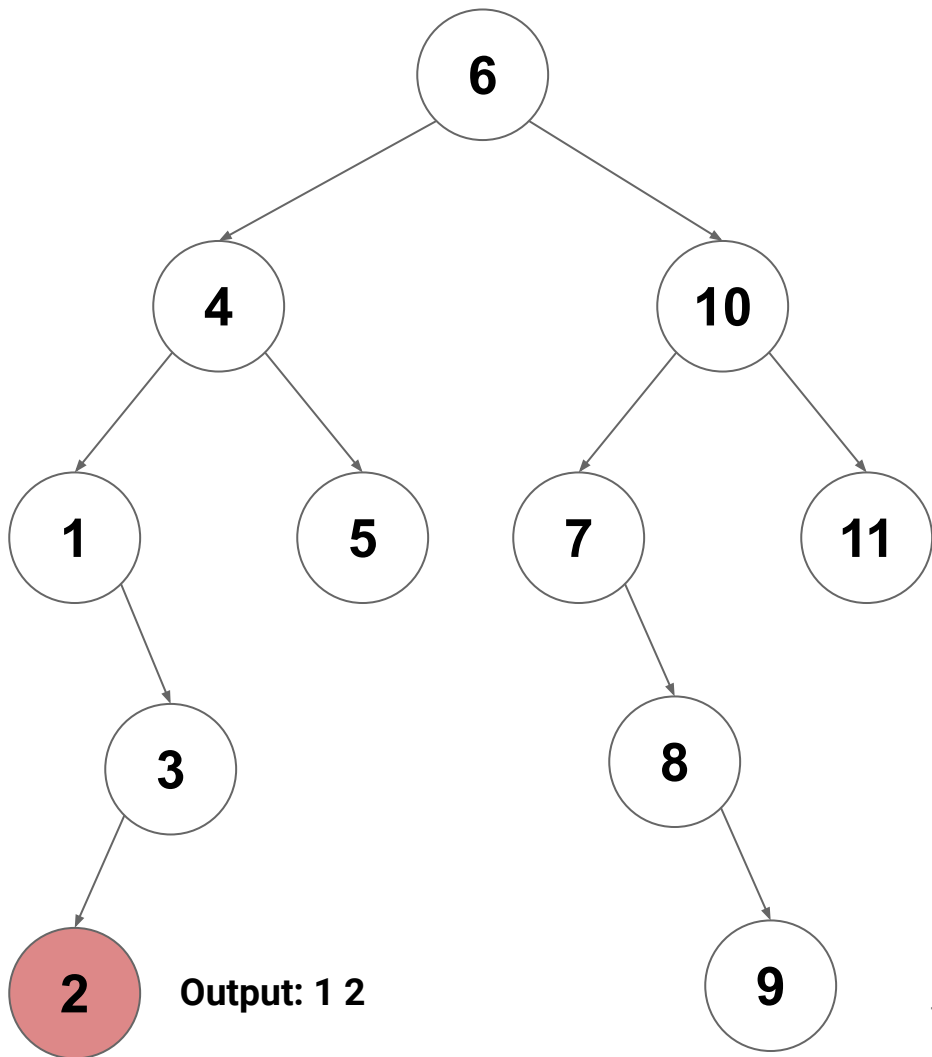
`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(1)`

`inorderVisit(3)`

`visit(2)`



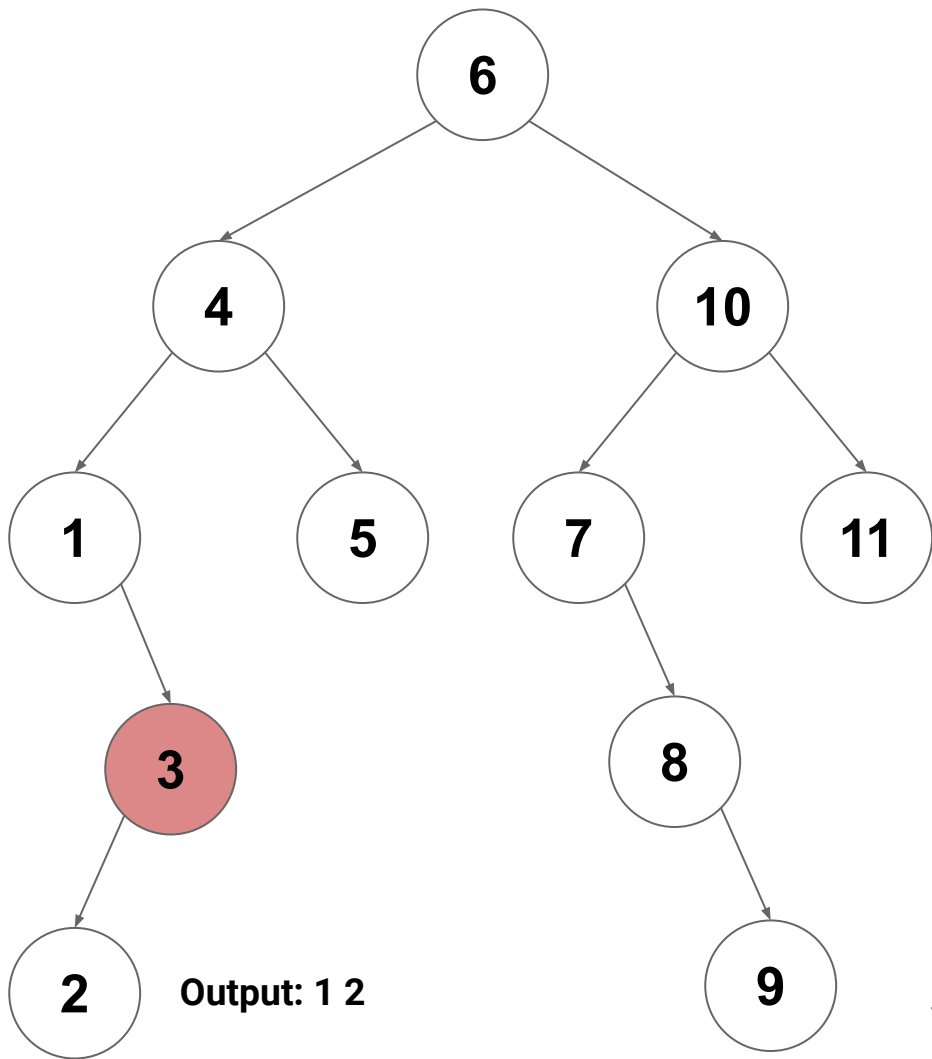
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(1)`

`inorderVisit(3)`



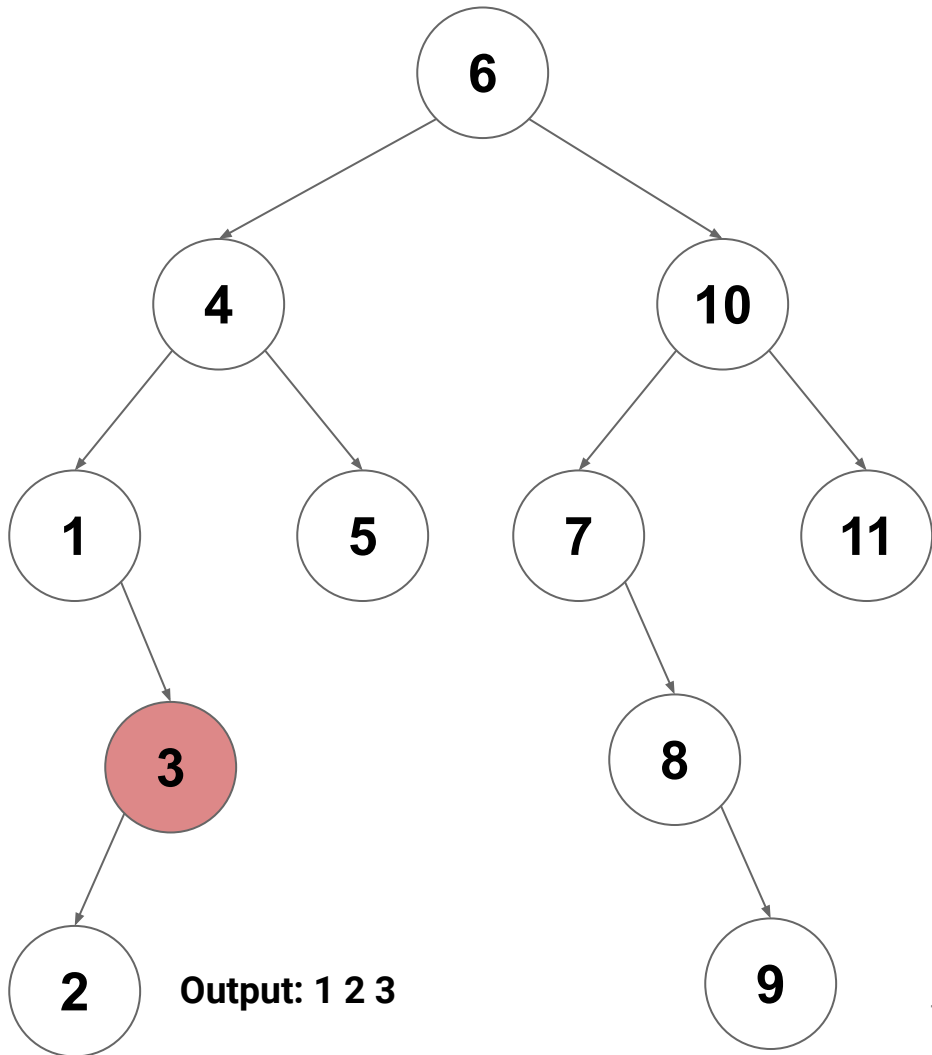
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(1)`

`visit(3)`

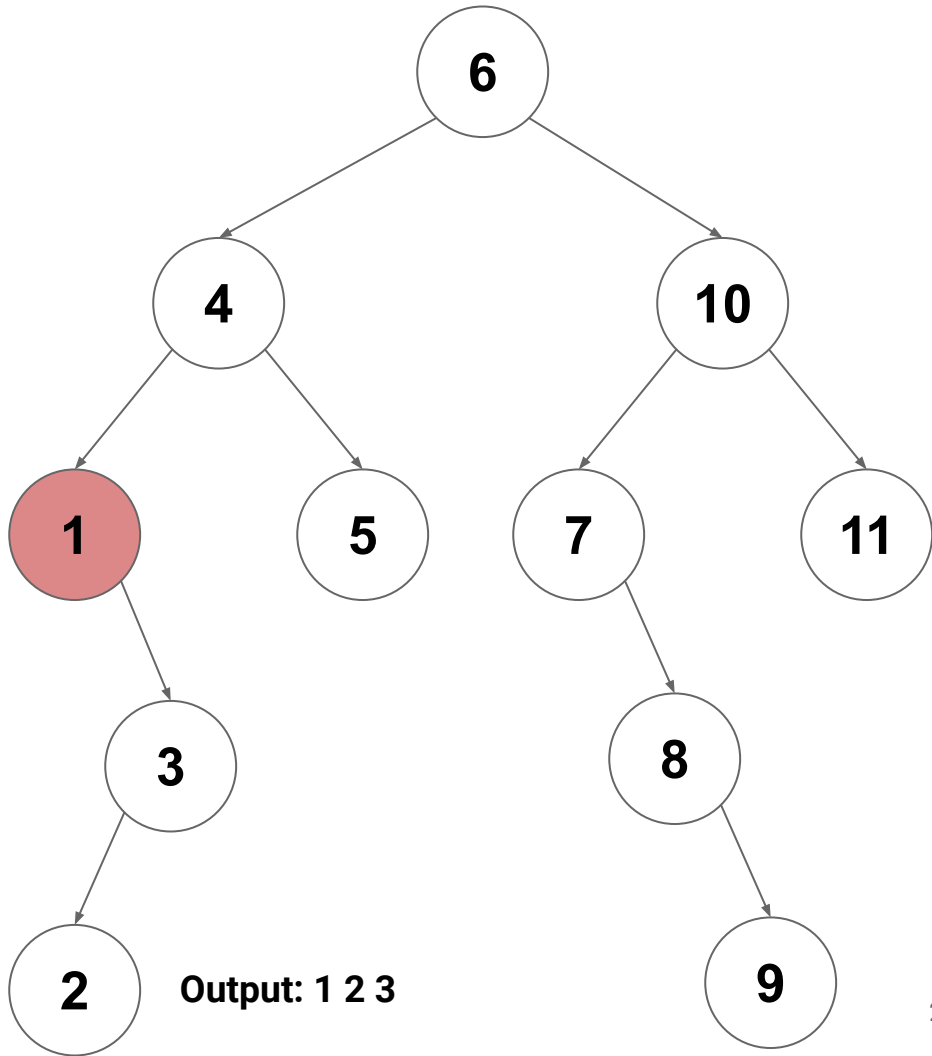


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

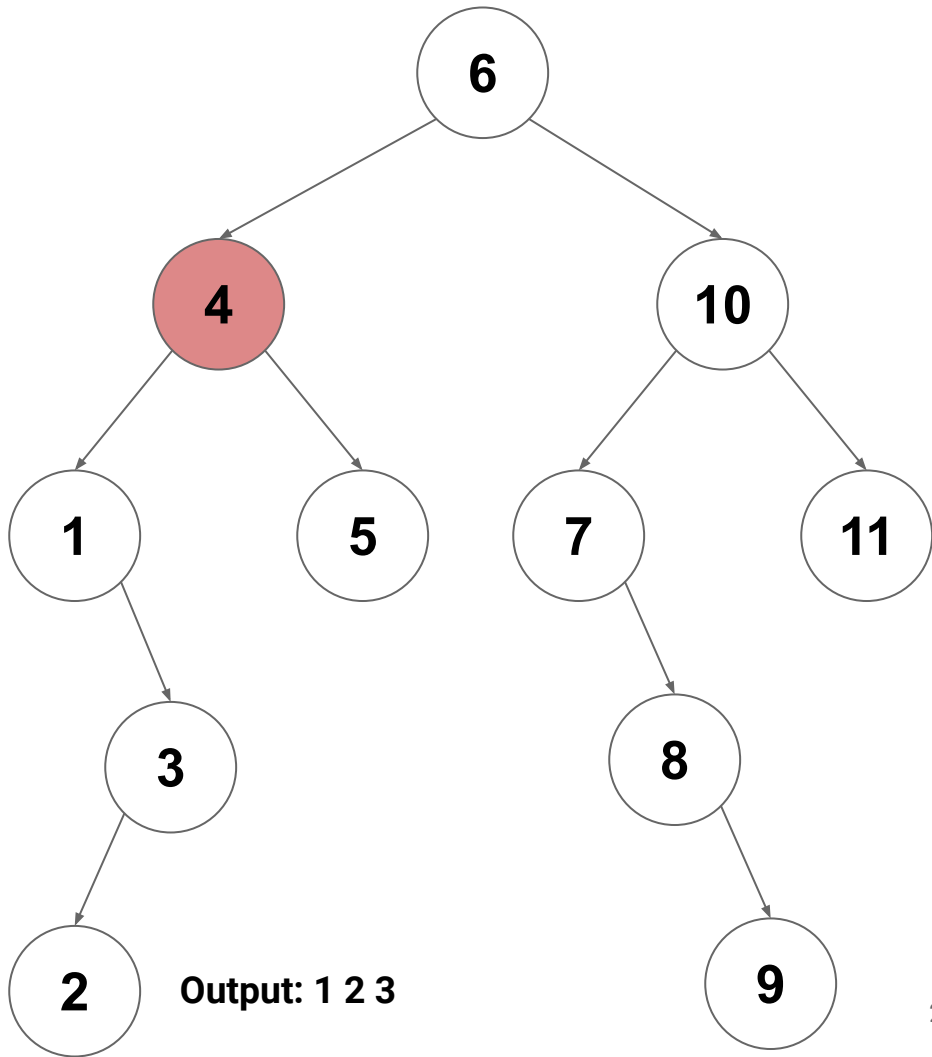
`inorderVisit(1)`



In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

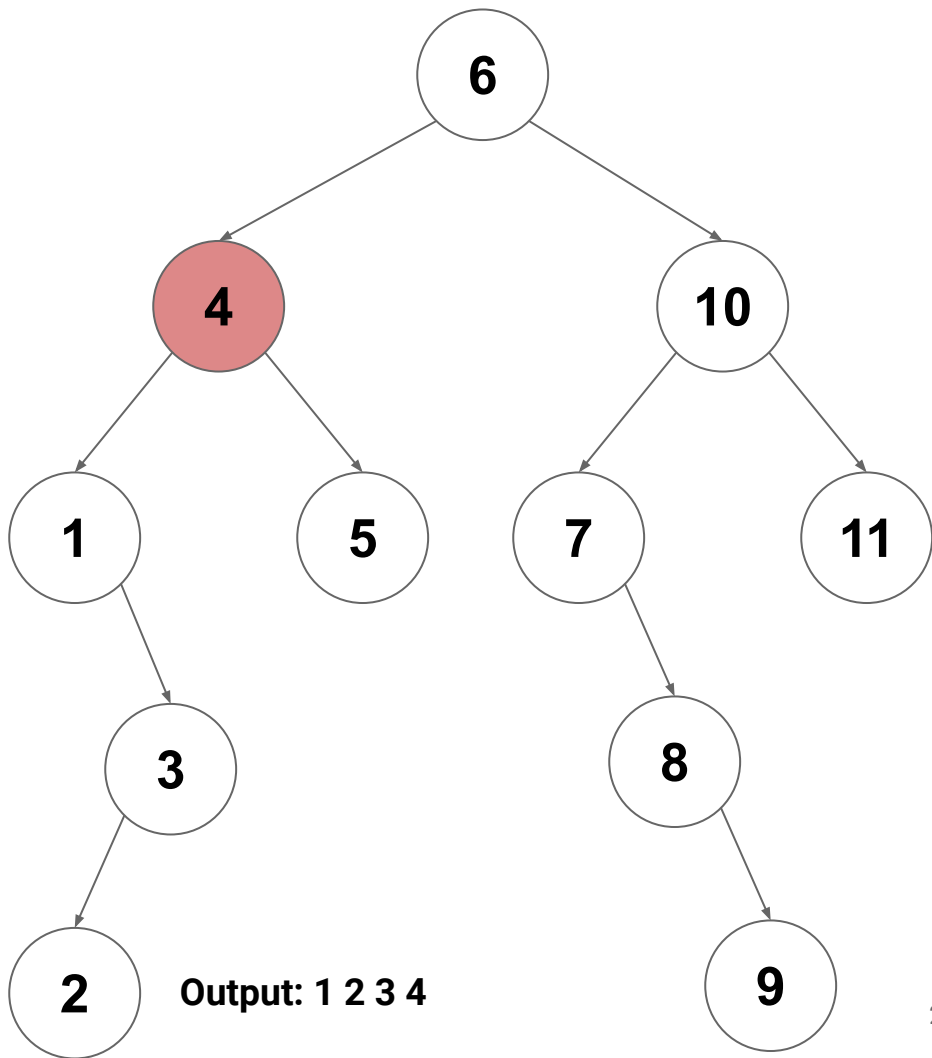


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

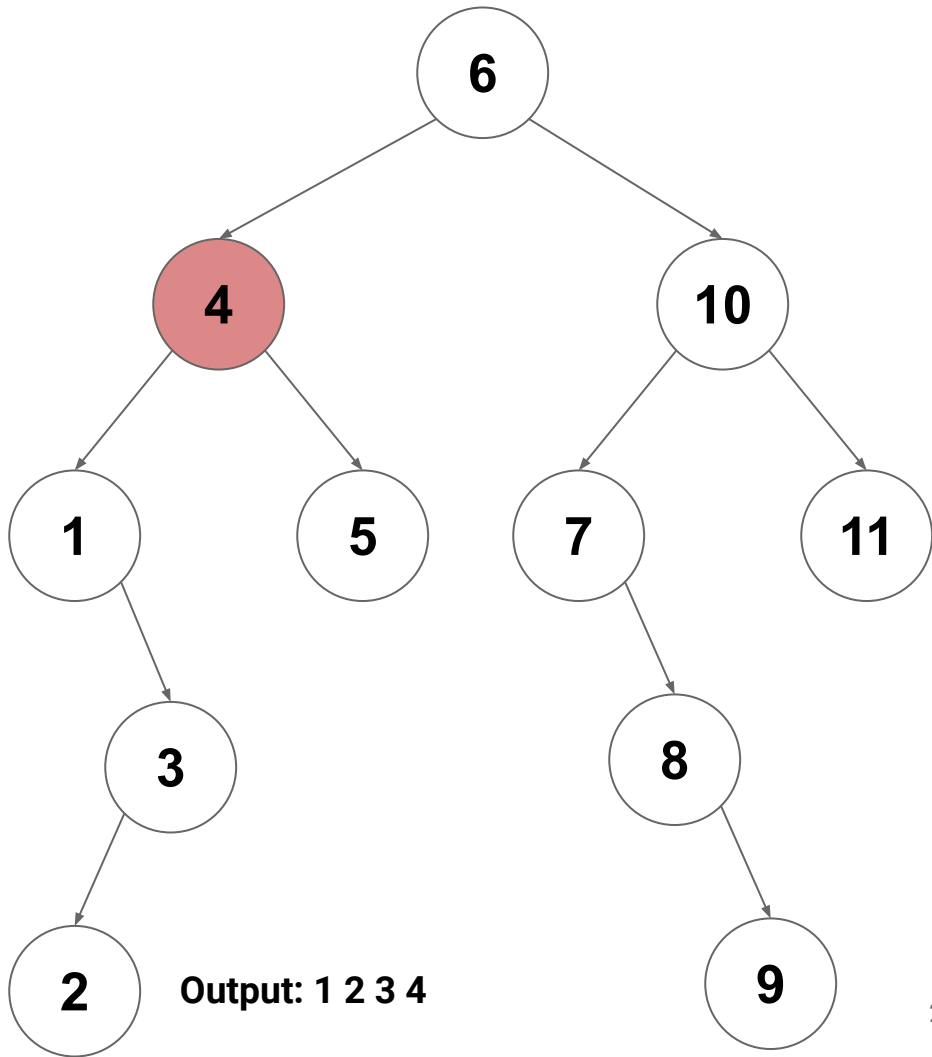
`visit(4)`



In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

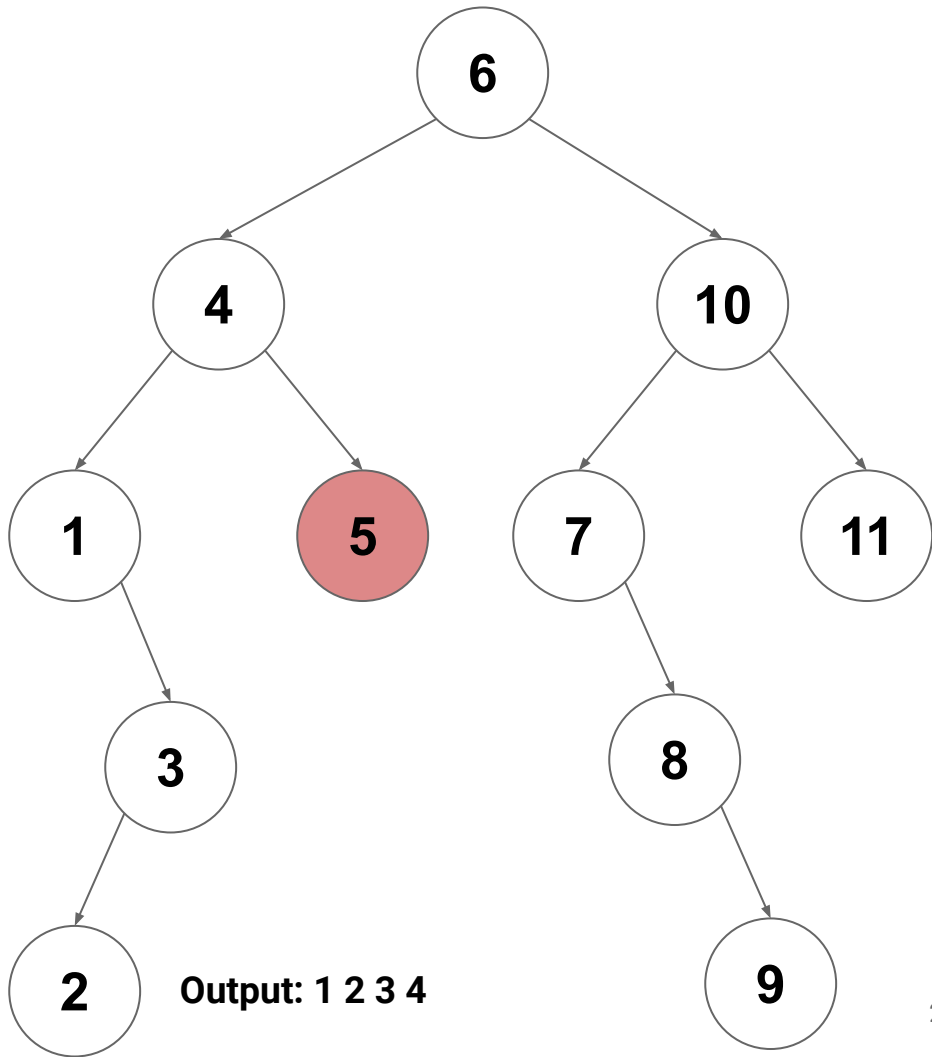


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

`inorderVisit(5)`

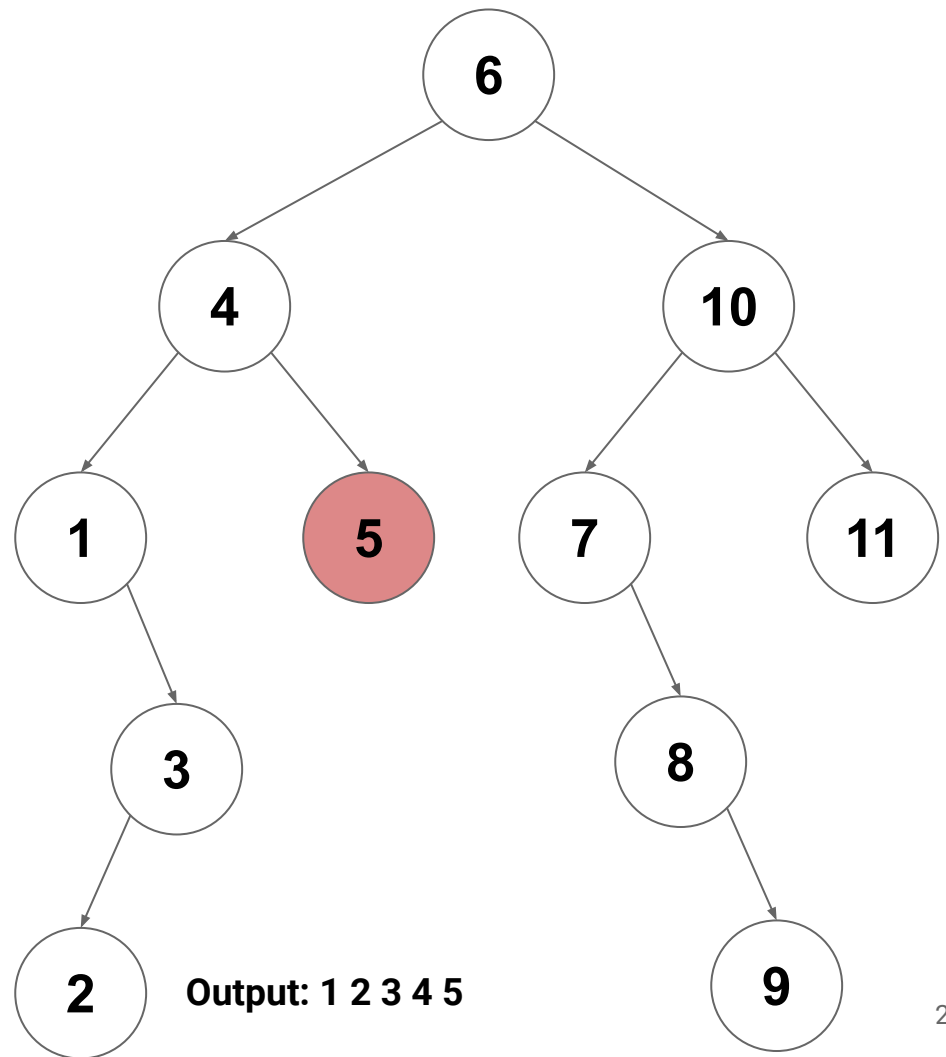


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(4)`

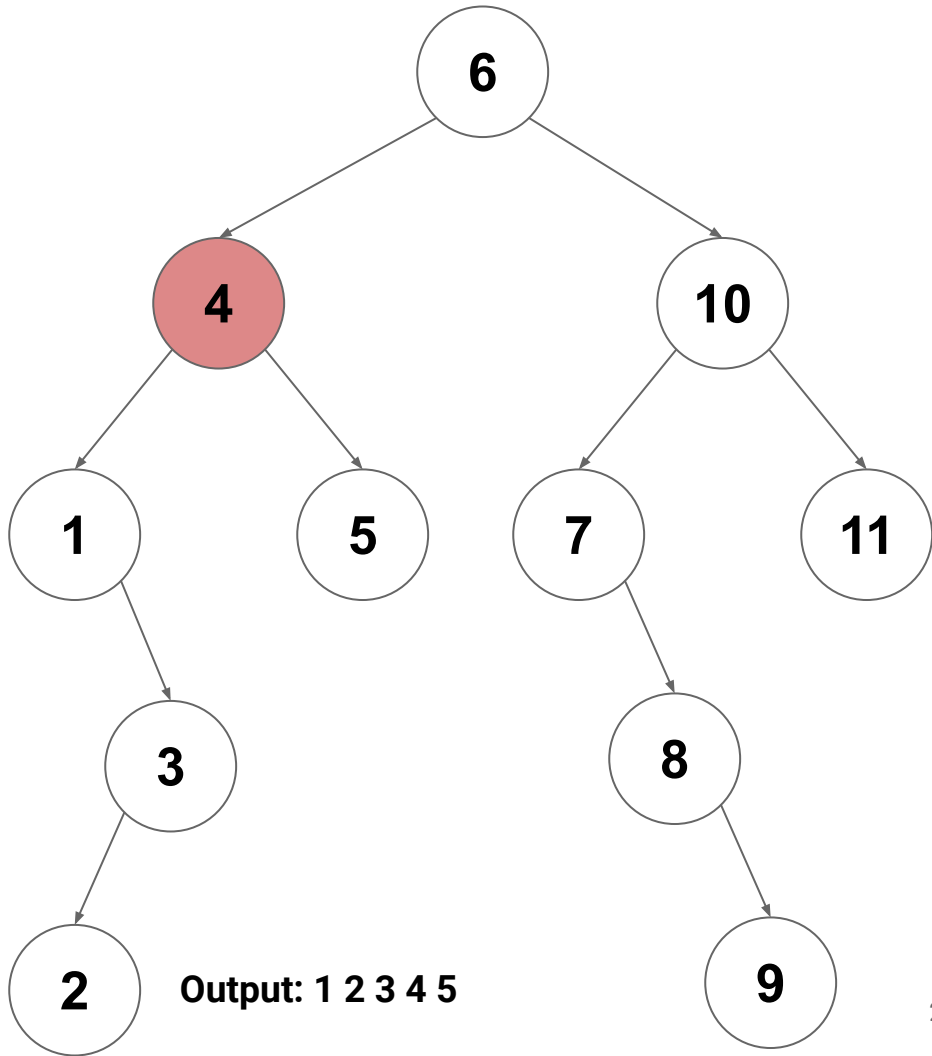
`visit(5)`



In-Order Traversal on a BST

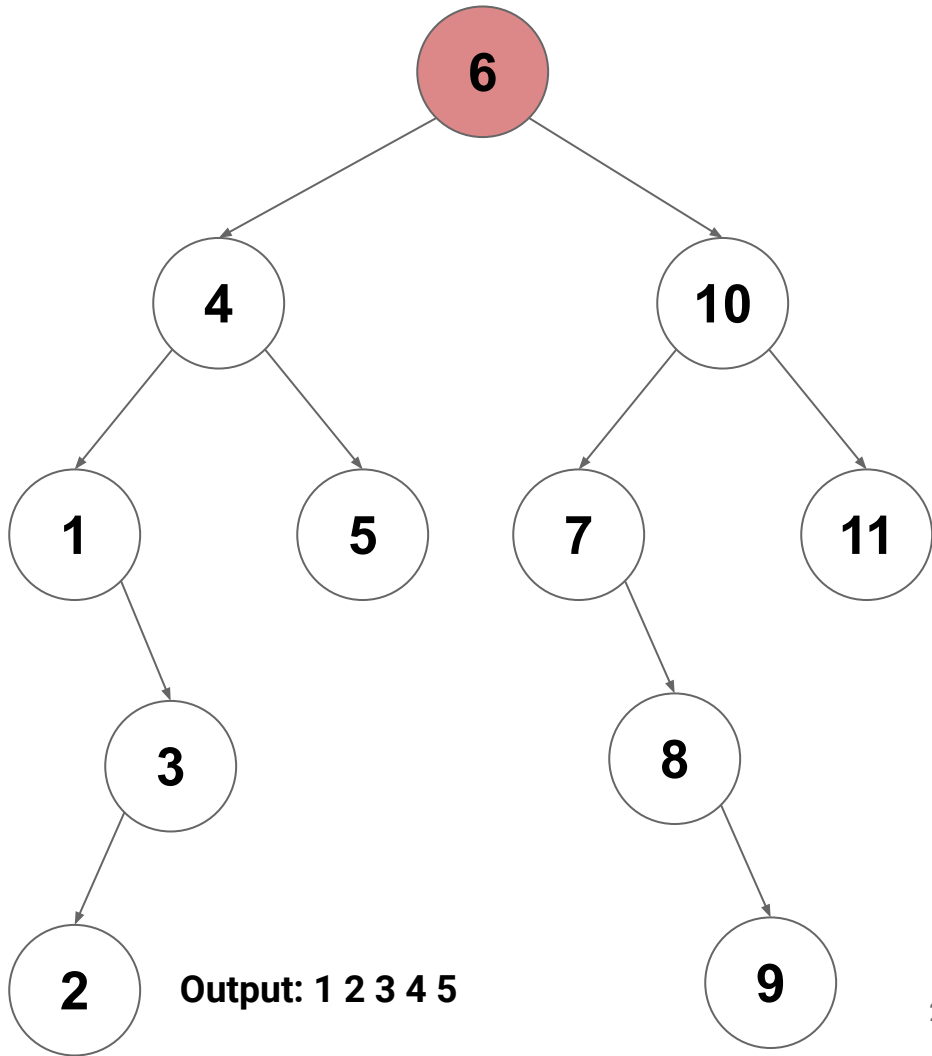
`inorderVisit(6)`

`inorderVisit(4)`



In-Order Traversal on a BST

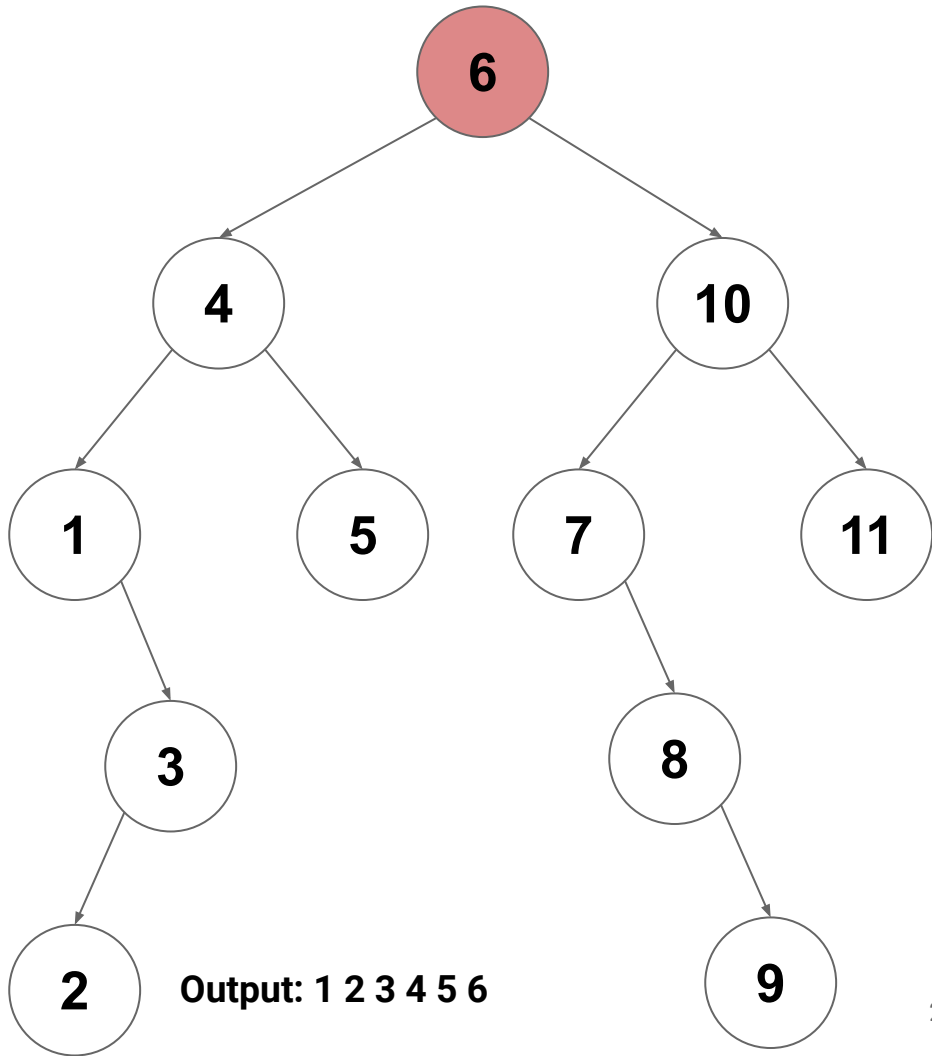
`inorderVisit(6)`



In-Order Traversal on a BST

`inorderVisit(6)`

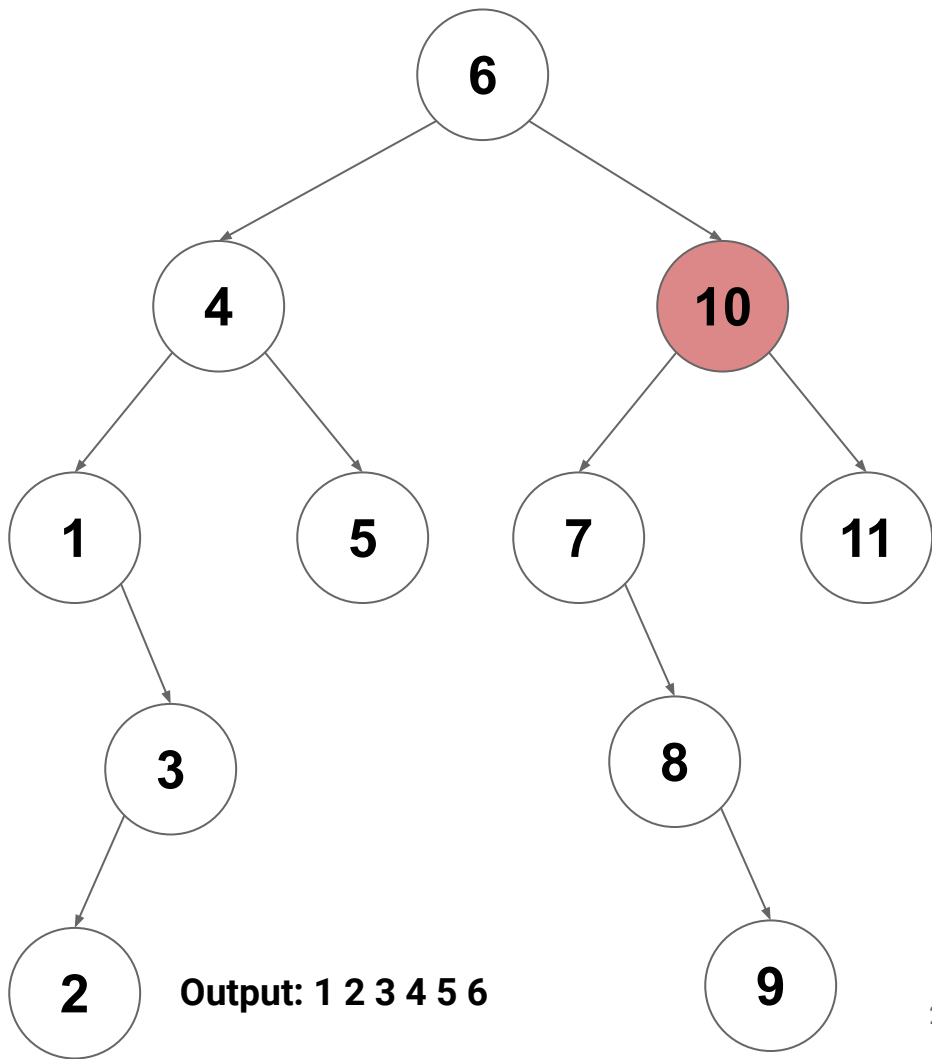
`visit(6)`



In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

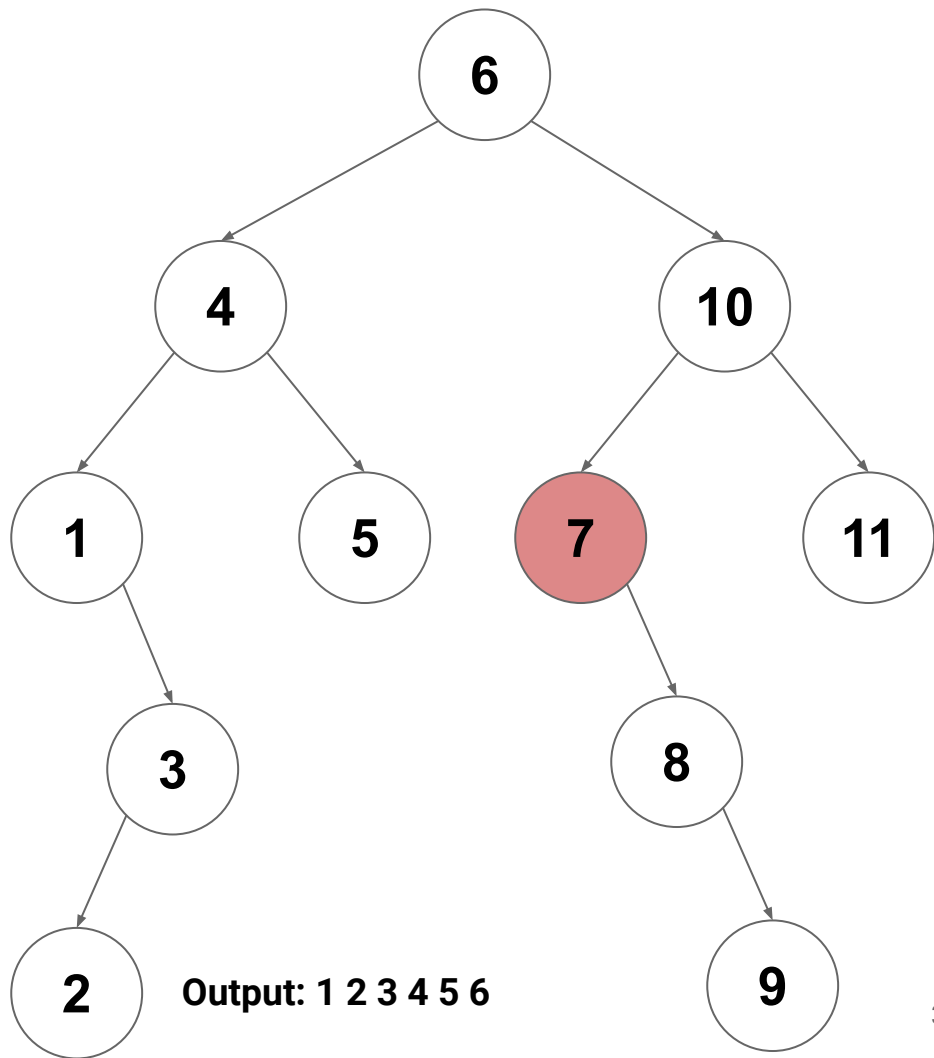


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(7)`



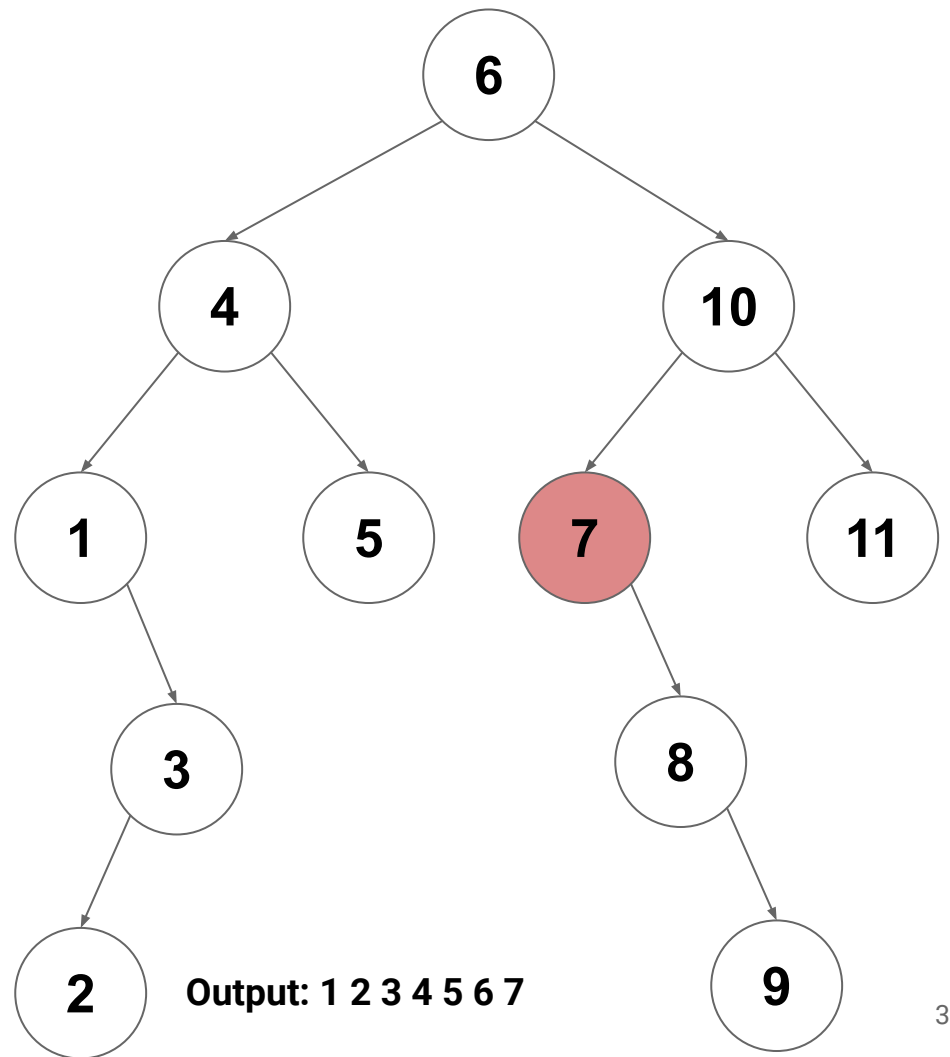
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(7)`

`visit(7)`



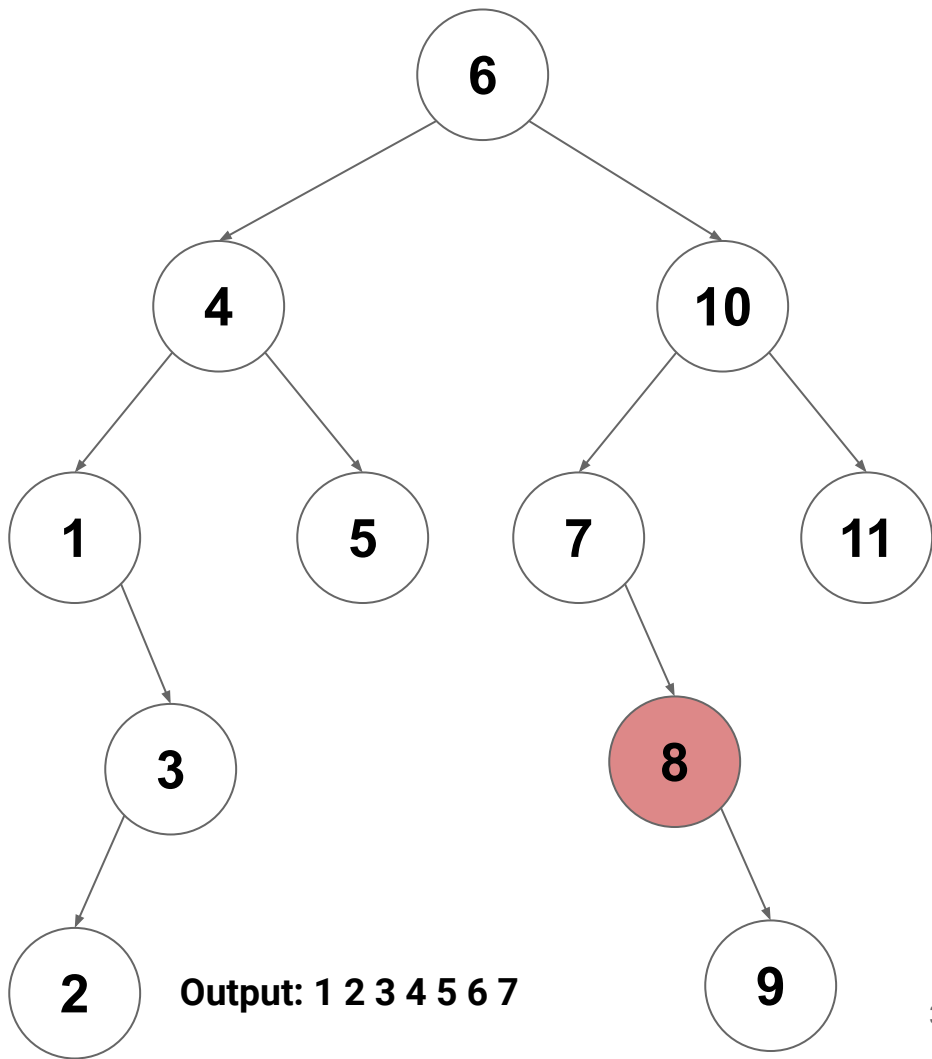
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(7)`

`inorderVisit(8)`



In-Order Traversal on a BST

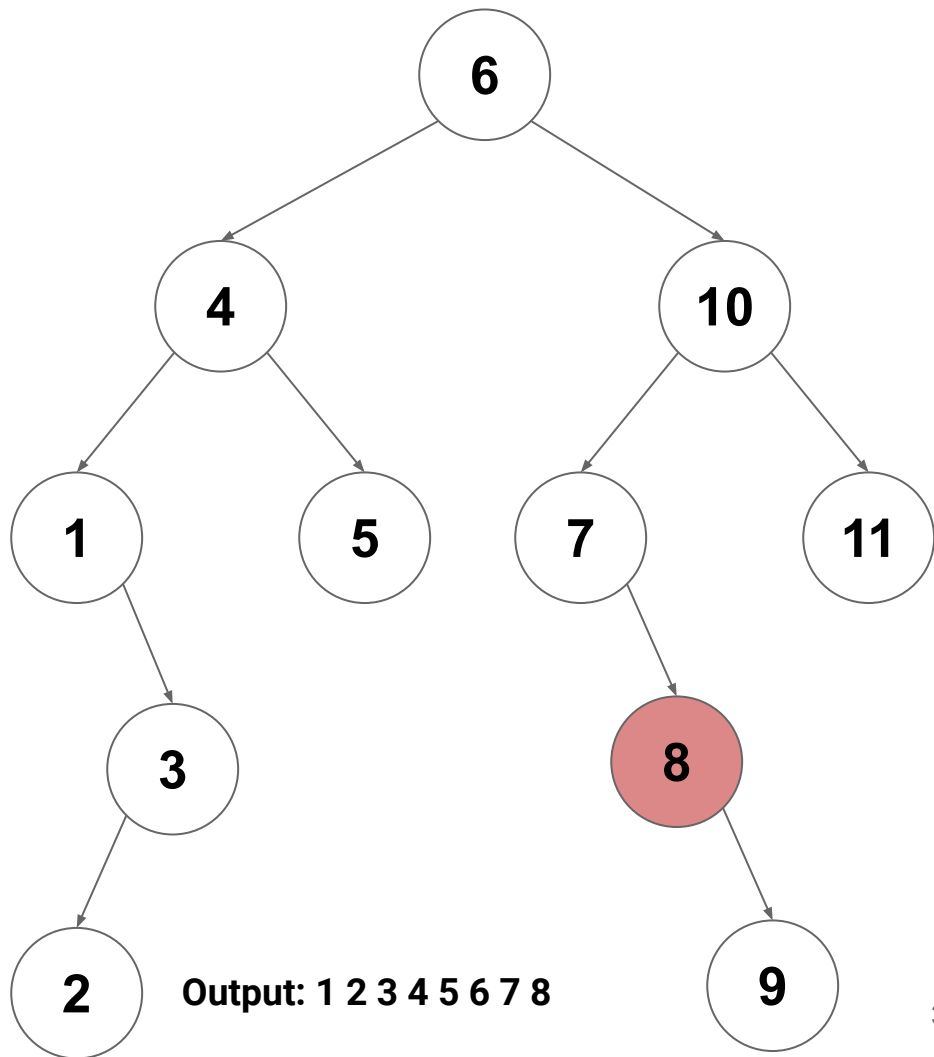
`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(7)`

`inorderVisit(8)`

`visit(8)`



In-Order Traversal on a BST

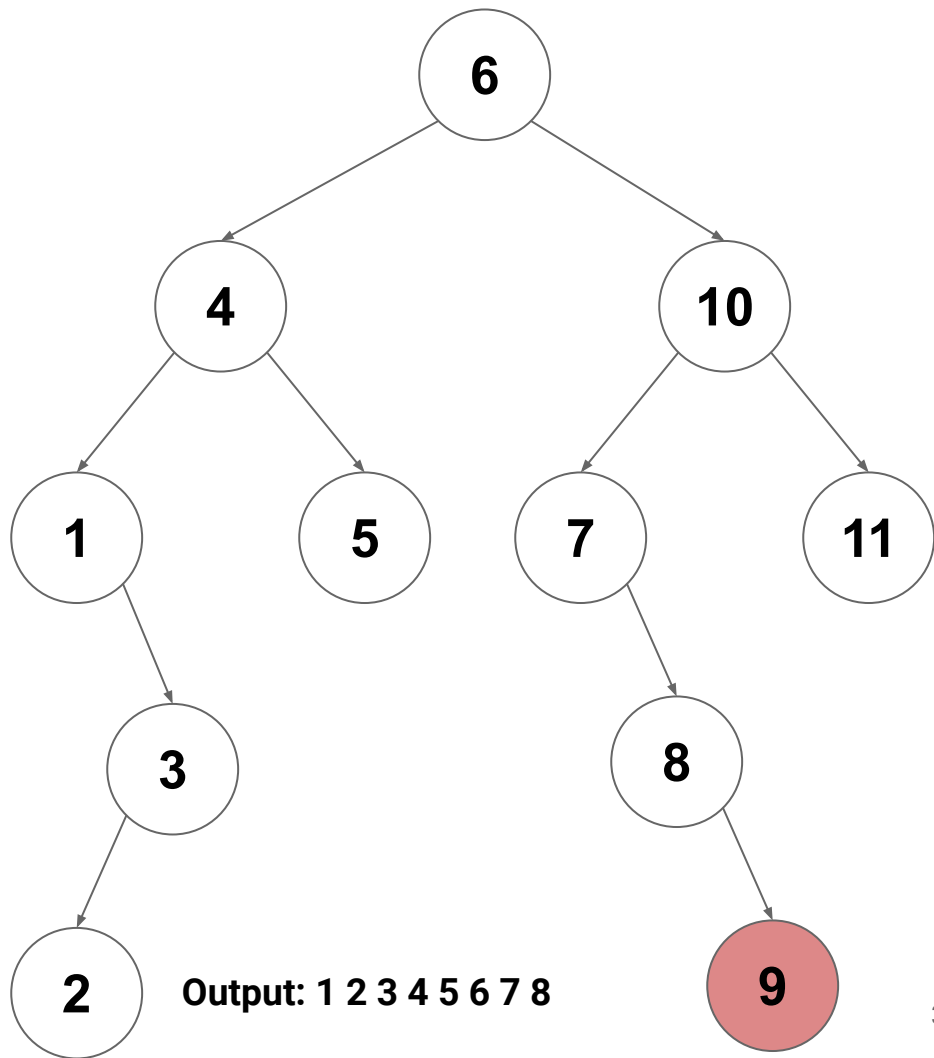
`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(7)`

`inorderVisit(8)`

`inorderVisit(9)`



In-Order Traversal on a BST

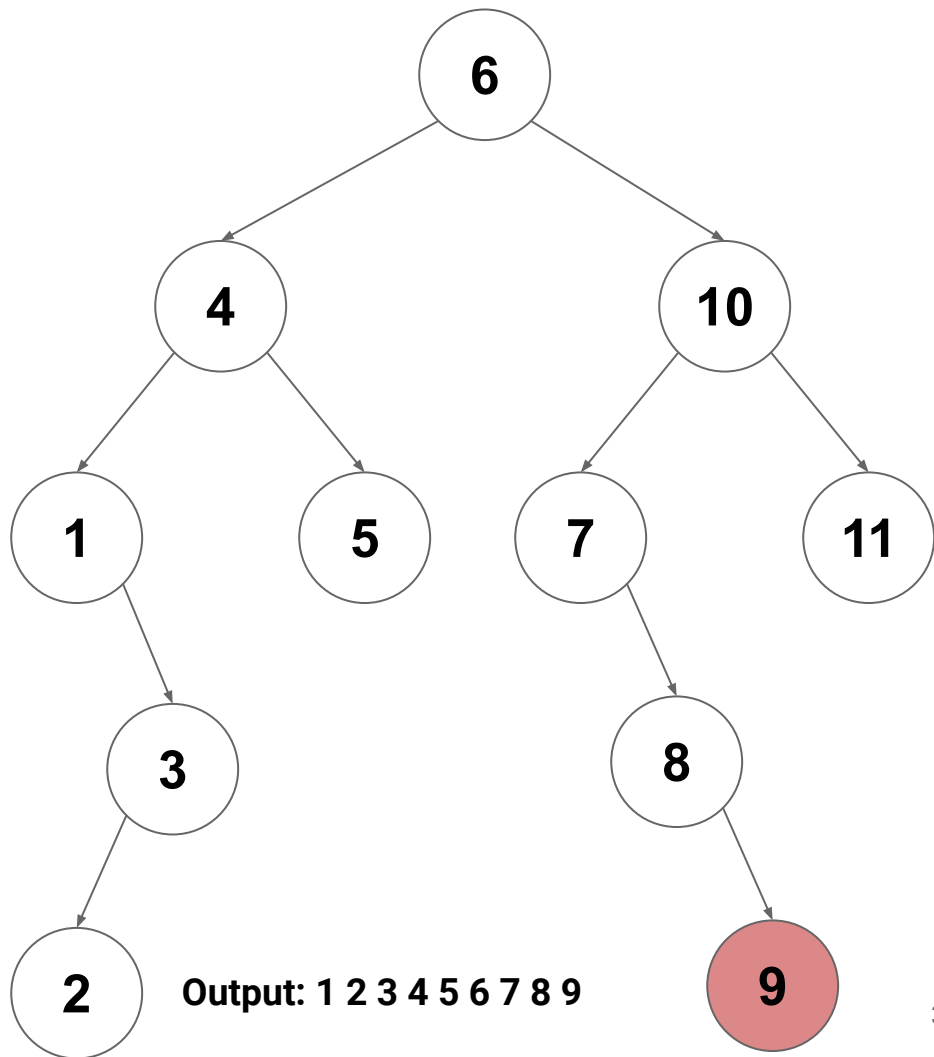
`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(7)`

`inorderVisit(8)`

`visit(9)`



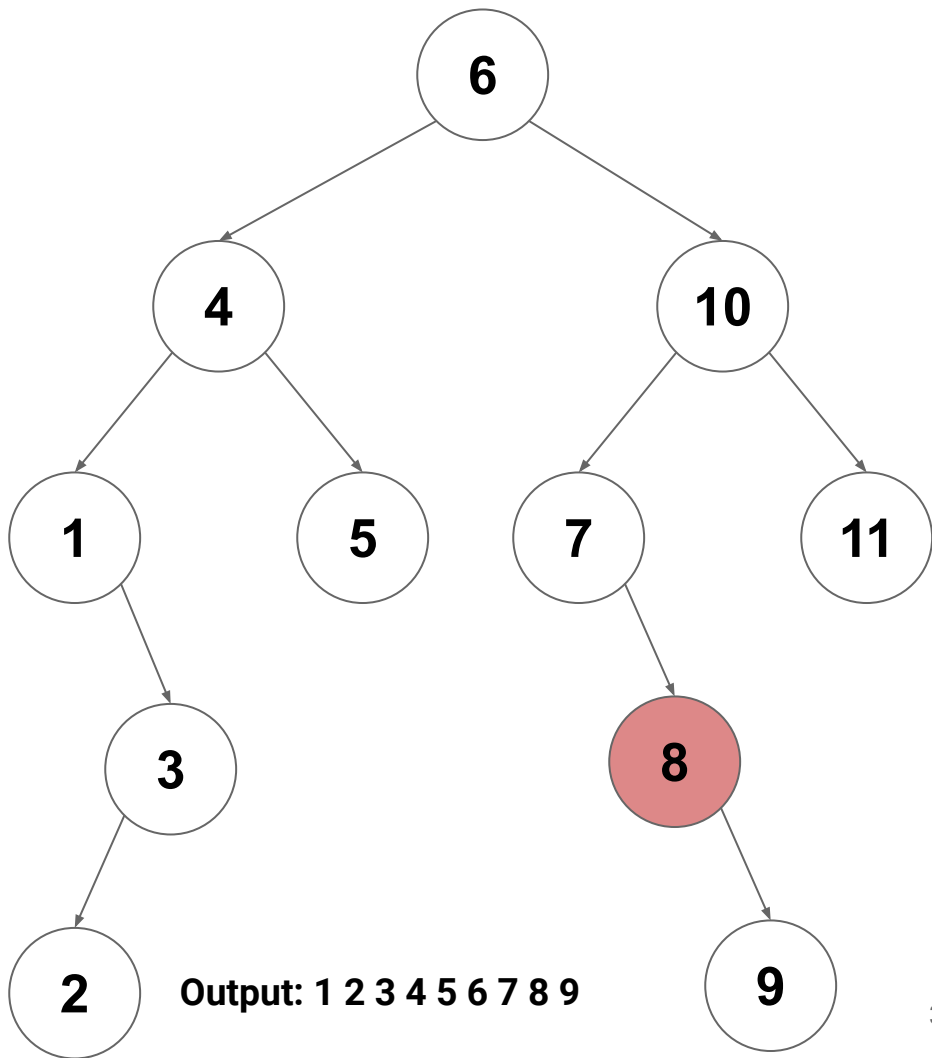
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(7)`

`inorderVisit(8)`

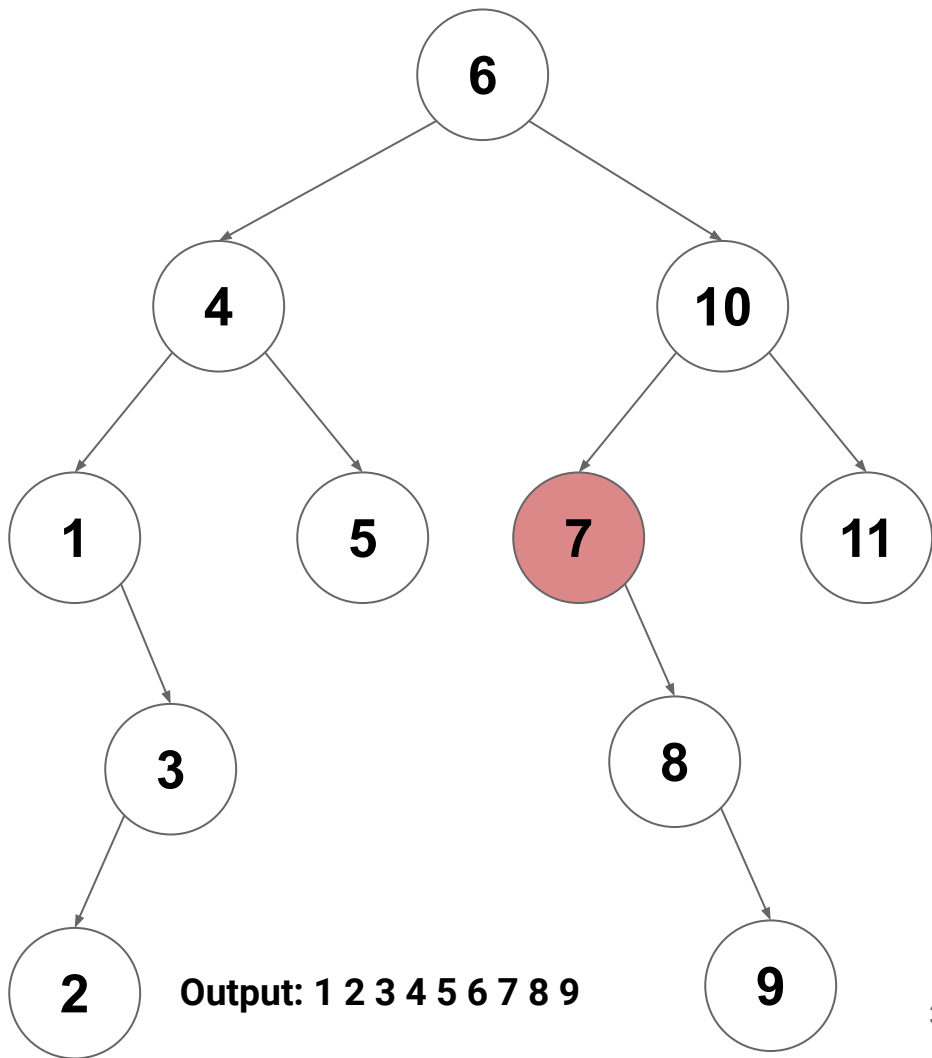


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

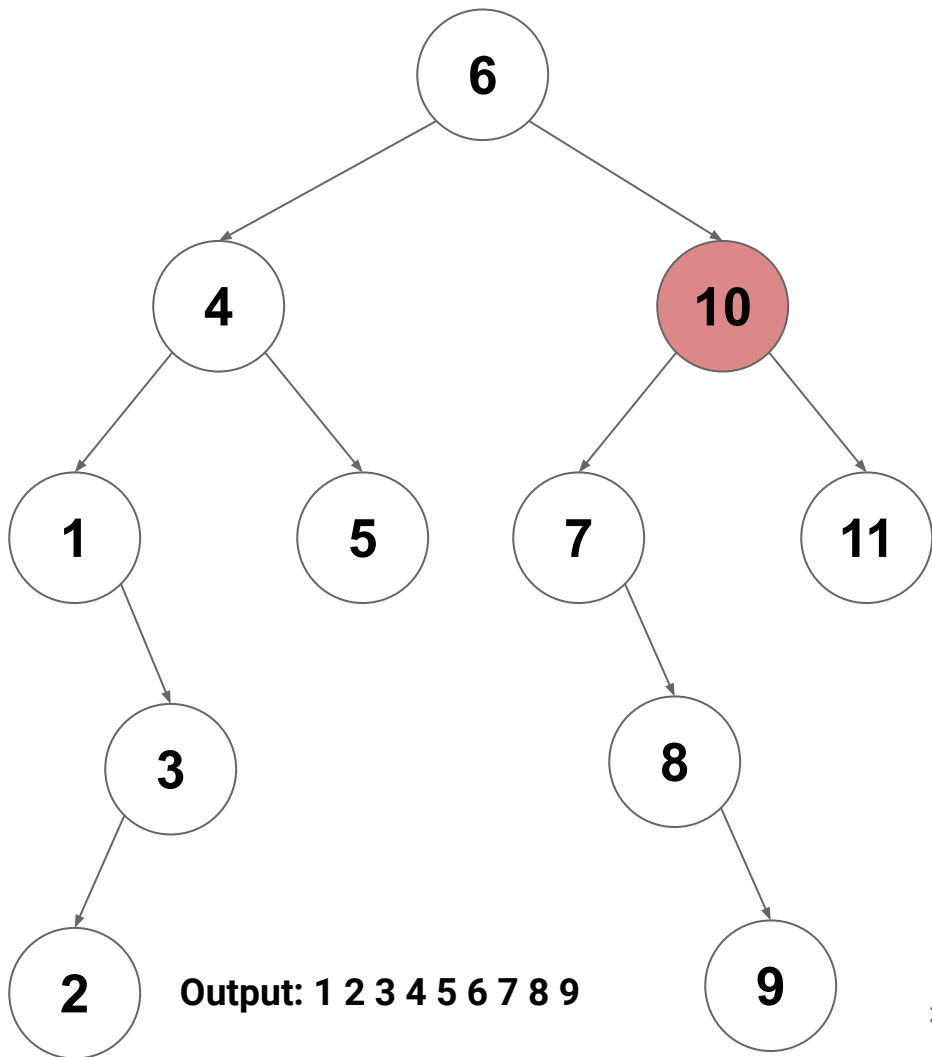
`inorderVisit(7)`



In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

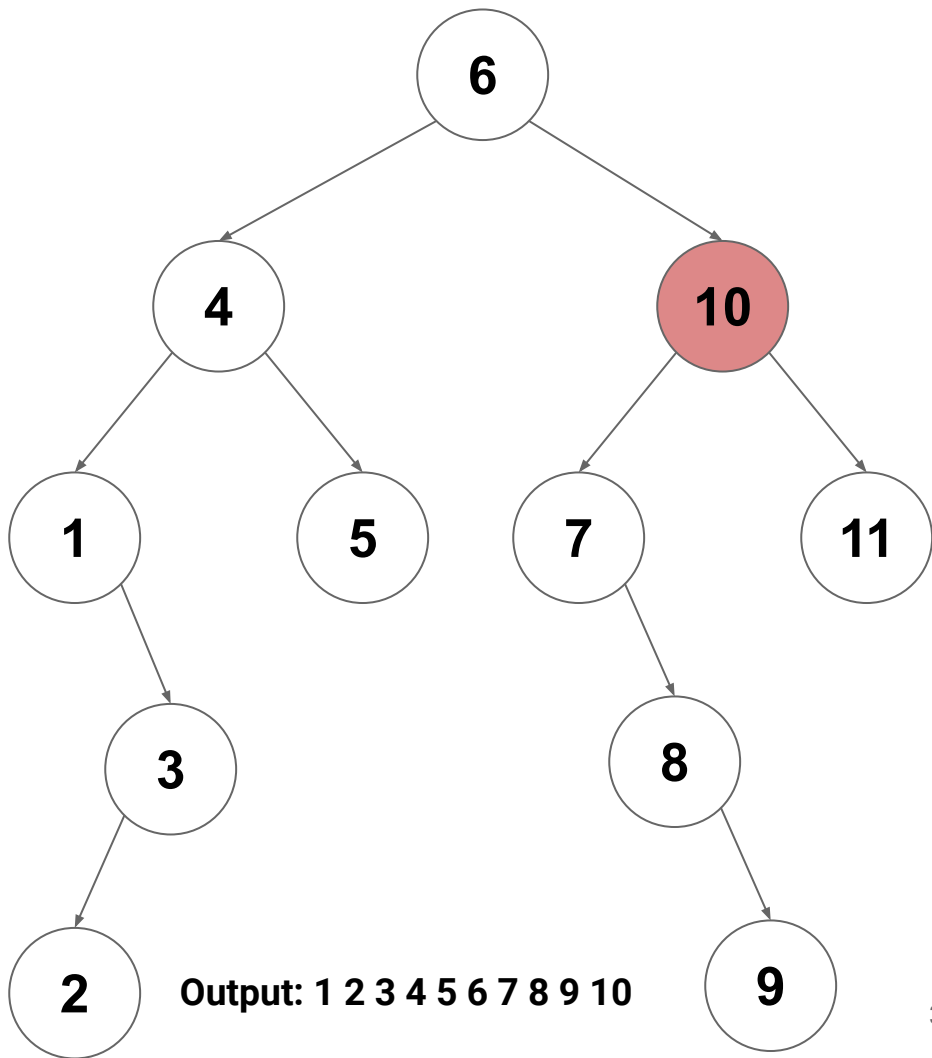


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

`visit(10)`

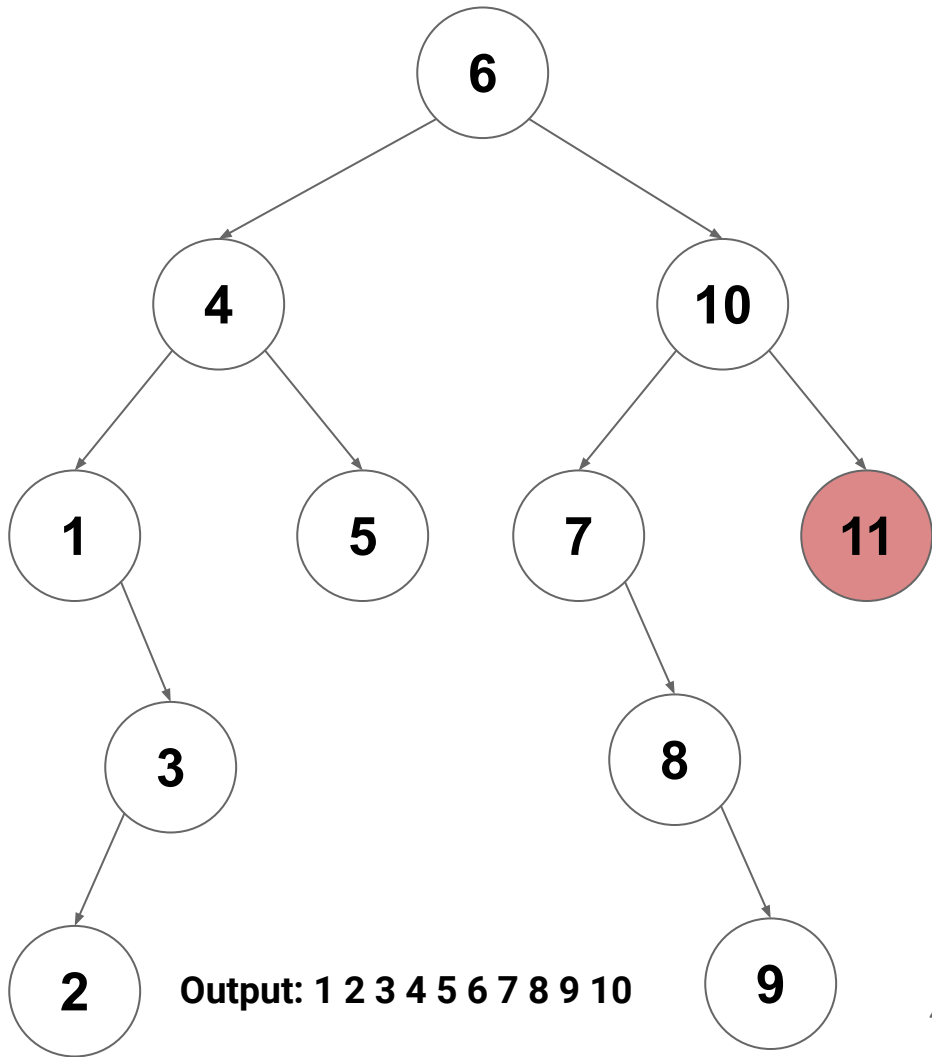


In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(11)`



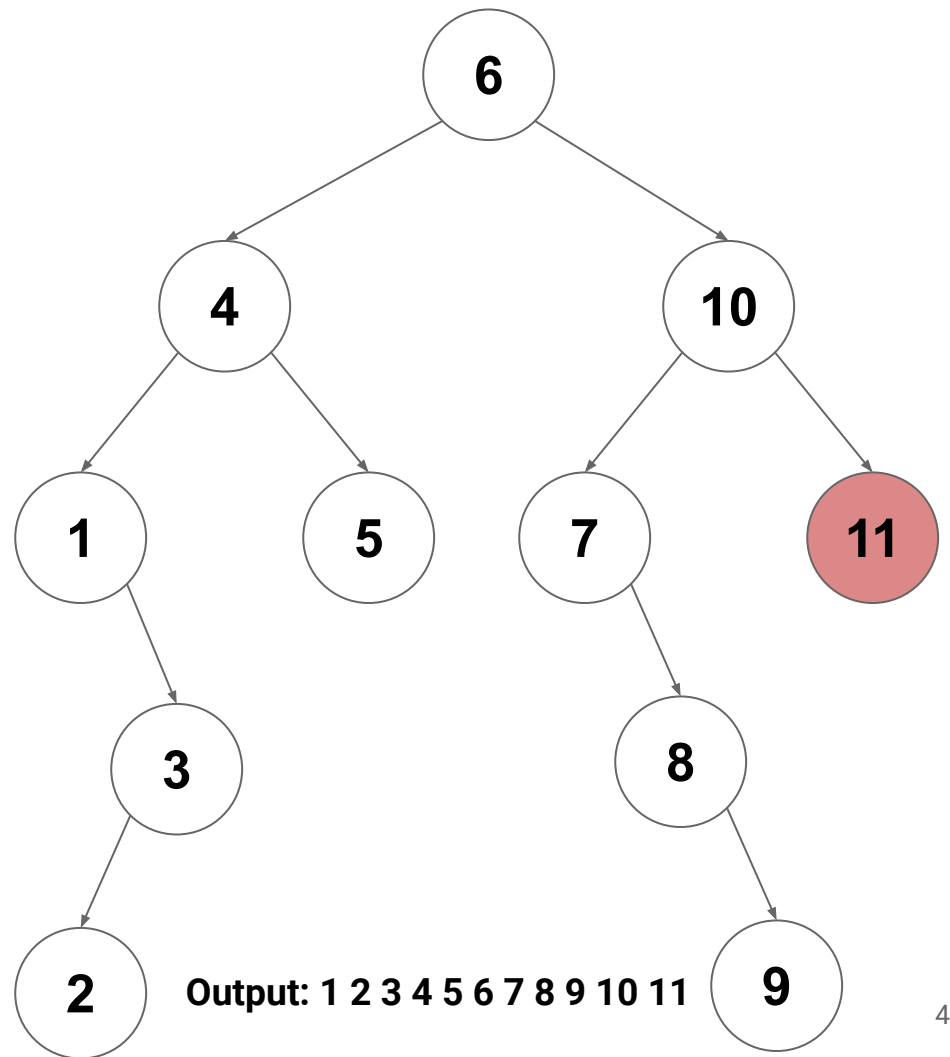
In-Order Traversal on a BST

`inorderVisit(6)`

`inorderVisit(10)`

`inorderVisit(11)`

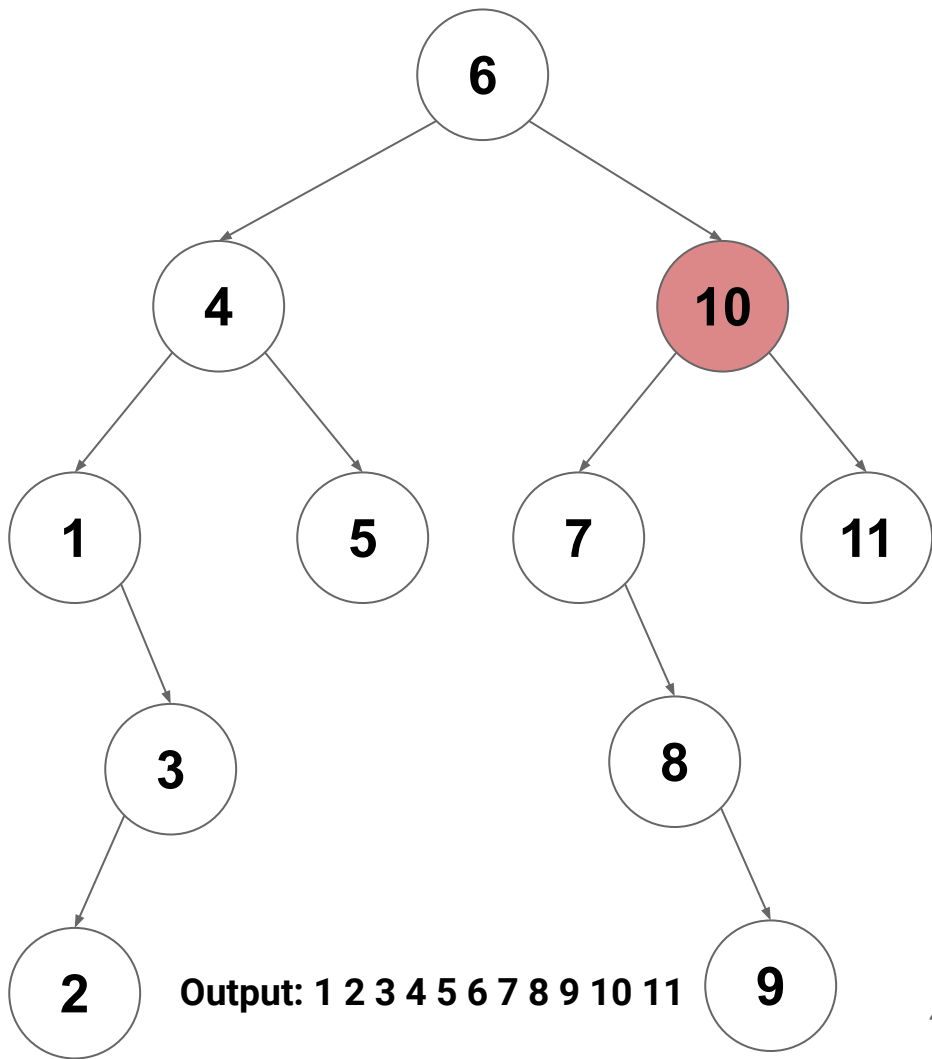
`visit(11)`



In-Order Traversal on a BST

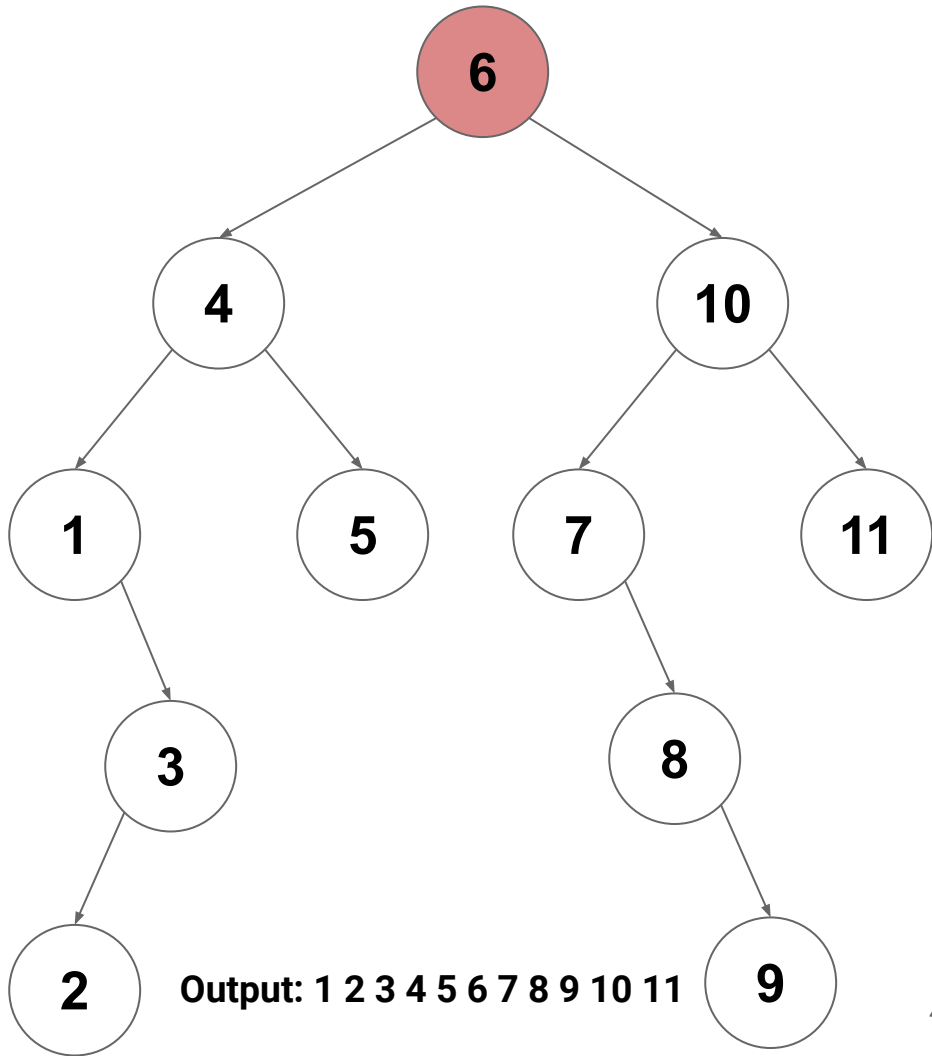
`inorderVisit(6)`

`inorderVisit(10)`

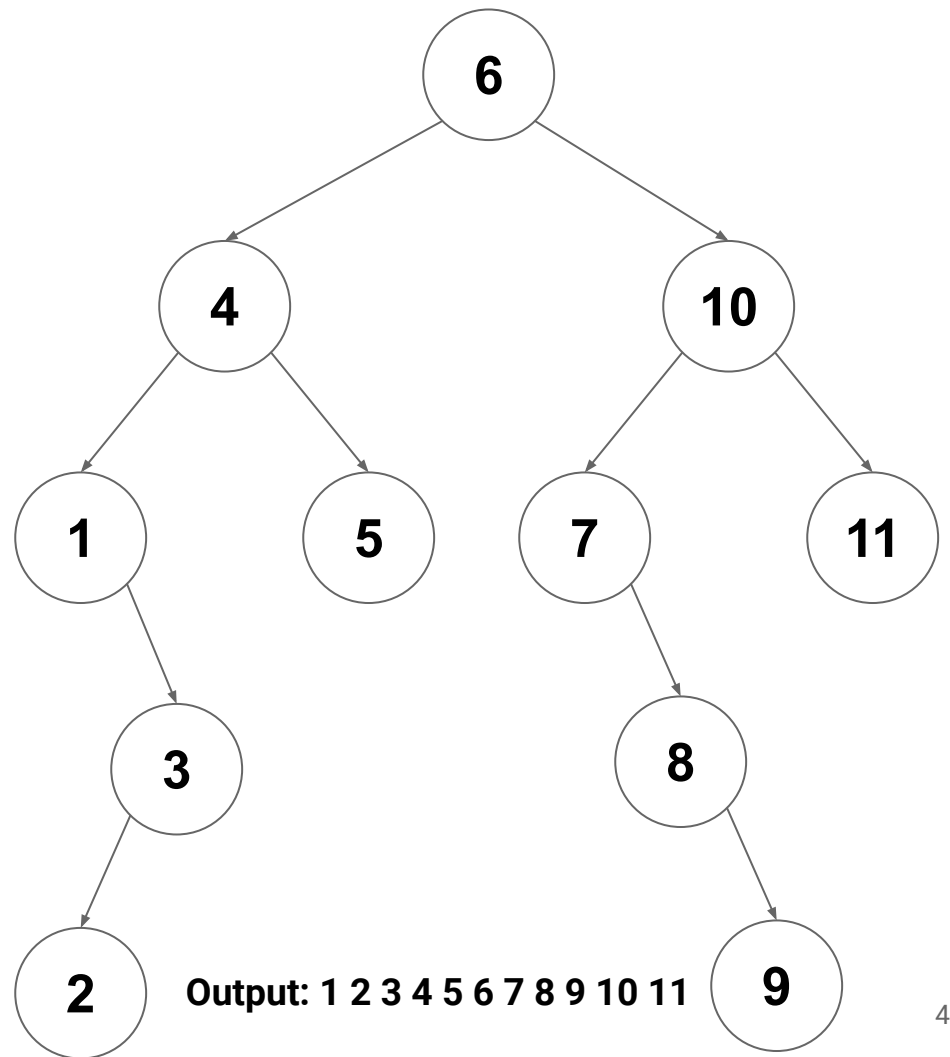


In-Order Traversal on a BST

`inorderVisit(6)`



In-Order Traversal on a BST



Tree Traversal: In-Order Iterator

```
1 class TreeIterator<T> implements Iterator<T> {
2     Stack<TreeNode<T>> toVisit;
3     TreeIterator() {
4         toVisit = new Stack<>();
5         pushLeft(root);
6     }
7     void pushLeft(Optional<TreeNode<T>> node) {
8         if (node.isPresent()) {
9             toVisit.push(node.get());
10            pushLeft(node.get().leftChild());
11        }
12    }
13    /* ... */
14 }
```

Tree Traversal: In-Order Iterator

```
1 class TreeIterator<T> implements Iterator<T> {  
2     Stack<TreeNode<T>> toVisit;    Keep track of what we need to visit in a stack  
3     TreeIterator() {  
4         toVisit = new Stack<>();    Recursively push all the left nodes (they are  
5         pushLeft(root);            the smallest and therefore should be visited  
6     }                                first)  
7     void pushLeft(Optional<TreeNode<T>> node) {  
8         if (node.isPresent()) {  
9             toVisit.push(node.get());  
10            pushLeft(node.get().leftChild());  
11        }  
12    }  
13    /* ... */  
14 }
```

Tree Traversal: In-Order Iterator

```
1 class TreeIterator<T> implements Iterator<T> {
2     Stack<TreeNode<T>> toVisit;
3     TreeIterator() {
4         toVisit = new Stack<>();
5         pushLeft(root);
6     }
7     void pushLeft(Optional<TreeNode<T>> node) {
8         if (node.isPresent()) {
9             toVisit.push(node.get());
10            pushLeft(node.get().leftChild());
11        }
12    }
13    /* ... */
14 }
```

Push the node, and then recursively push it's left children

Tree Traversal: In-Order Iterator

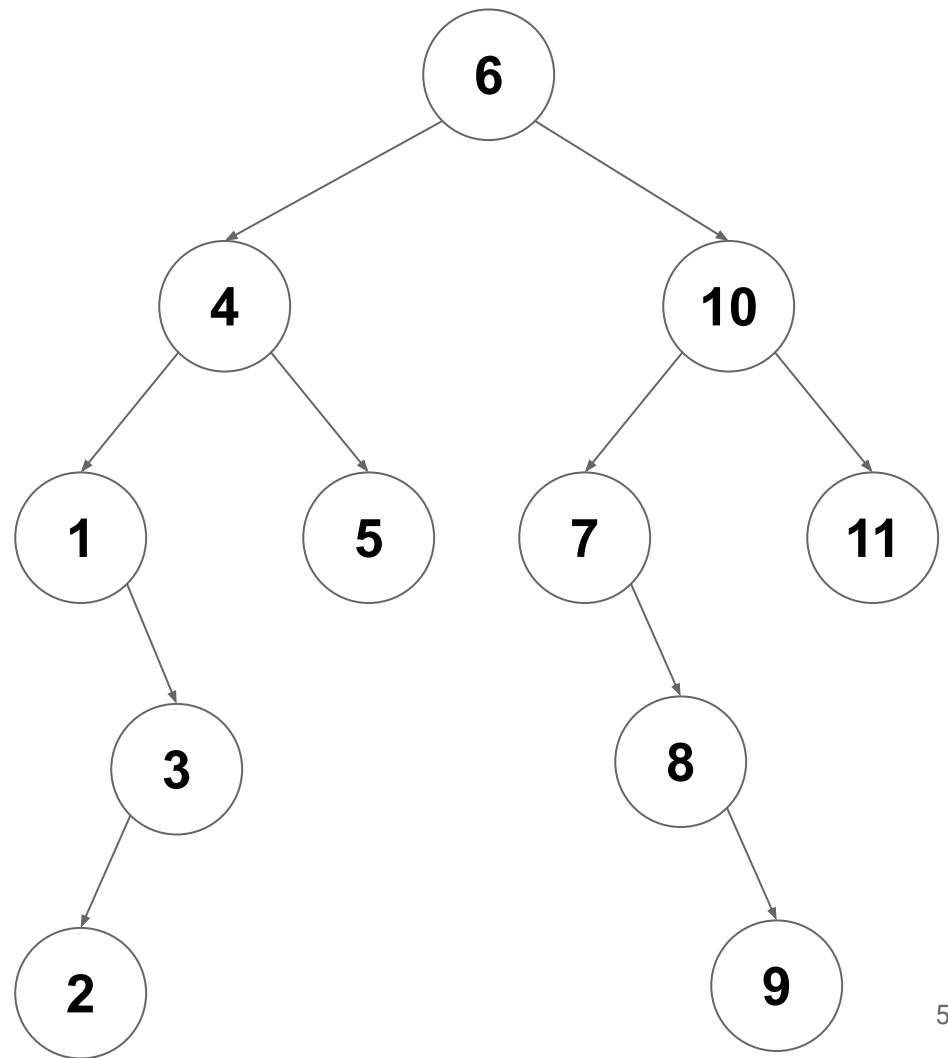
```
1 class TreeIterator<T> implements Iterator<T> {
2     /* ... */
3
4     boolean hasNext() { return !toVisit.isEmpty(); }
5
6     T next() {
7         TreeNode<T> nextNode = toVisit.pop();
8         pushLeft(nextNode.rightChild);
9         return nextNode.value;
10    }
11 }
```


Tree Traversal: In-Order Iterator

```
1 class TreeIterator<T> implements Iterator<T> {  
2     /* ... */  
3  
4     boolean hasNext() { return !toVisit.isEmpty(); }  
5  
6     T next() {  
7         TreeNode<T> nextNode = toVisit.pop();  
8         pushLeft(nextNode.rightChild);  
9         return nextNode.value;  
10    }  
11 }
```

Pop the next node, then push the left children of it's right subtree

In-Order Traversal with an Iterator

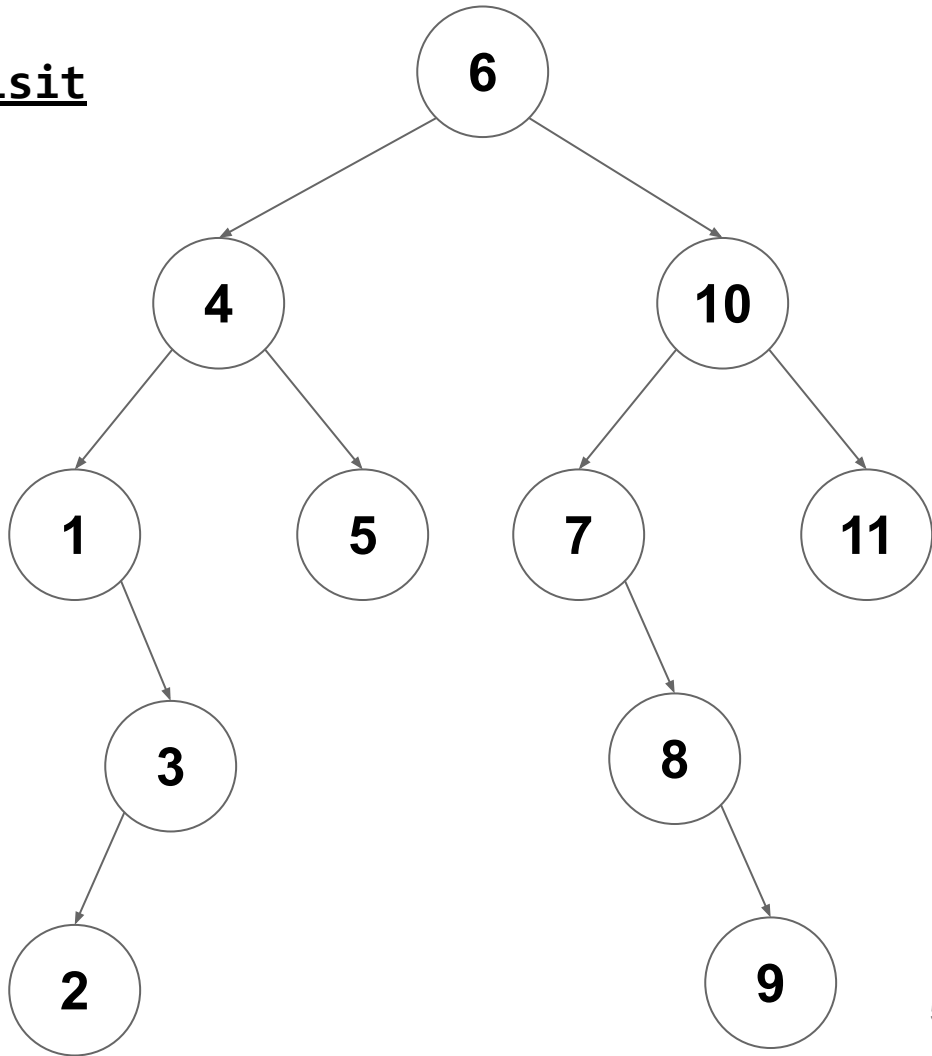


In-Order Traversal with an Iterator

When we create the iterator, the `toVisit` stack is initialized

toVisit

6
4
1

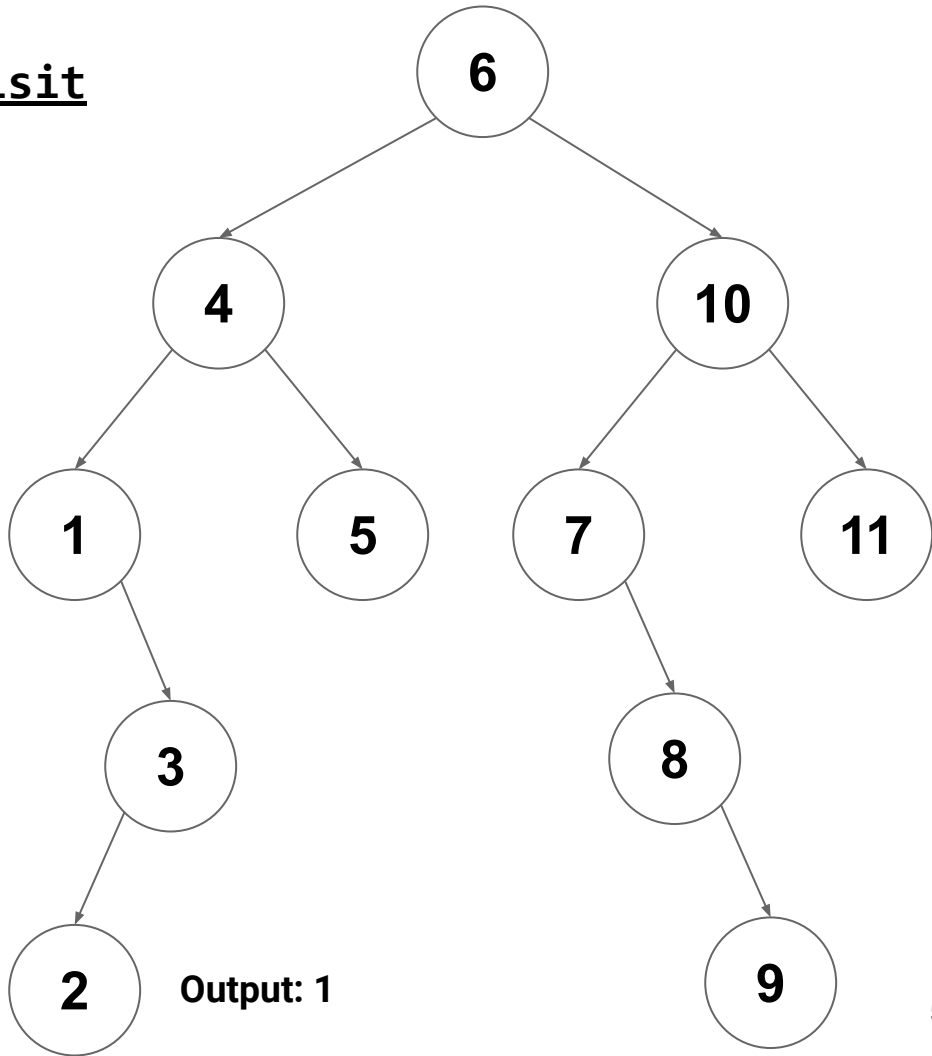


In-Order Traversal with an Iterator

next pops the stack (1),
and calls pushLeft on
the right subtree of 1

toVisit

6
4
3
2

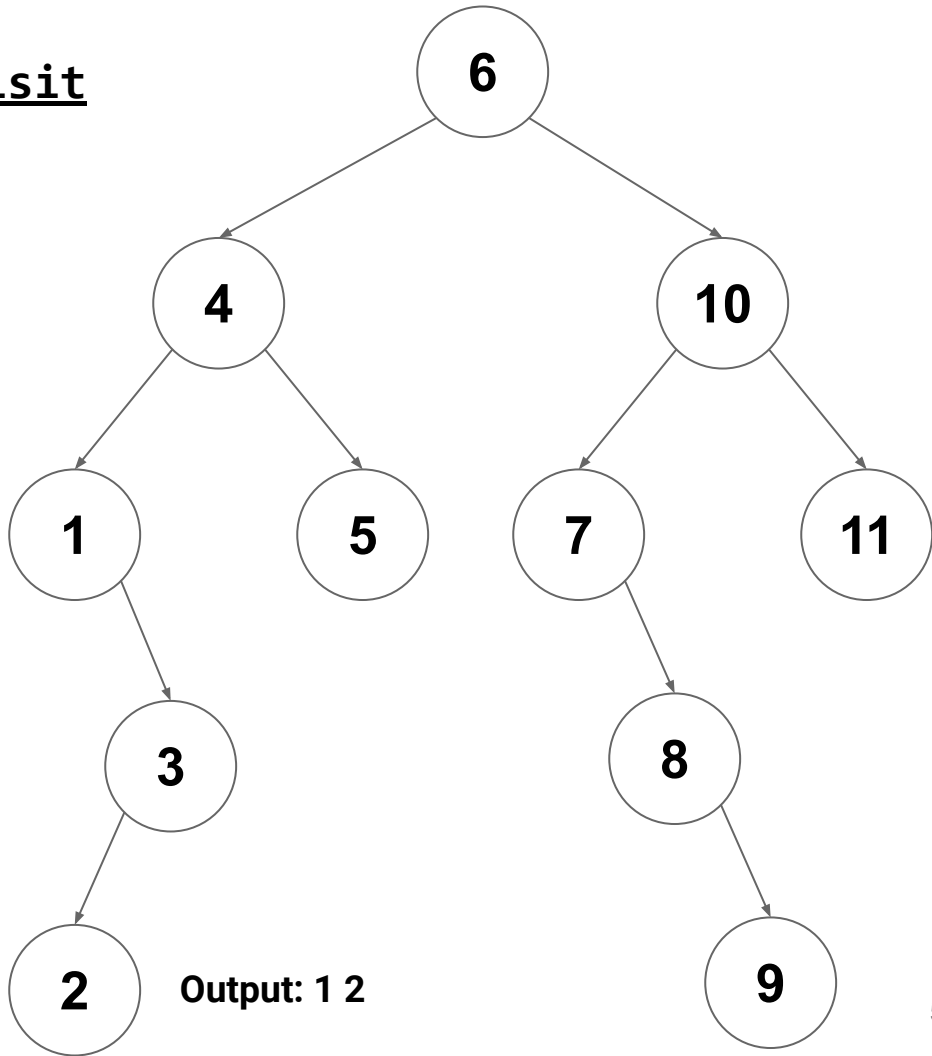


In-Order Traversal with an Iterator

next pops the stack (2)
and pushes the right
subtree (nothing)

toVisit

6
4
3



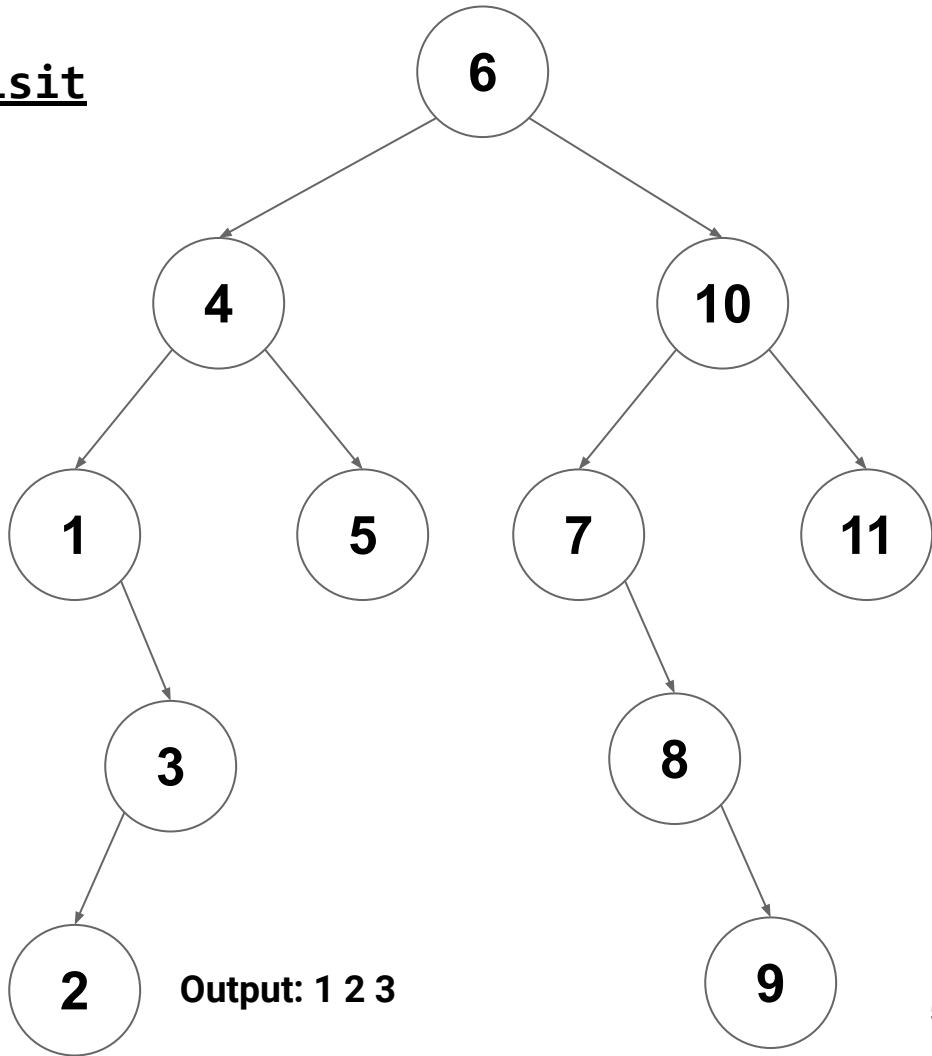
In-Order Traversal with an Iterator

next pops the stack (3)
and pushes the right
subtree (nothing)

toVisit

6

4



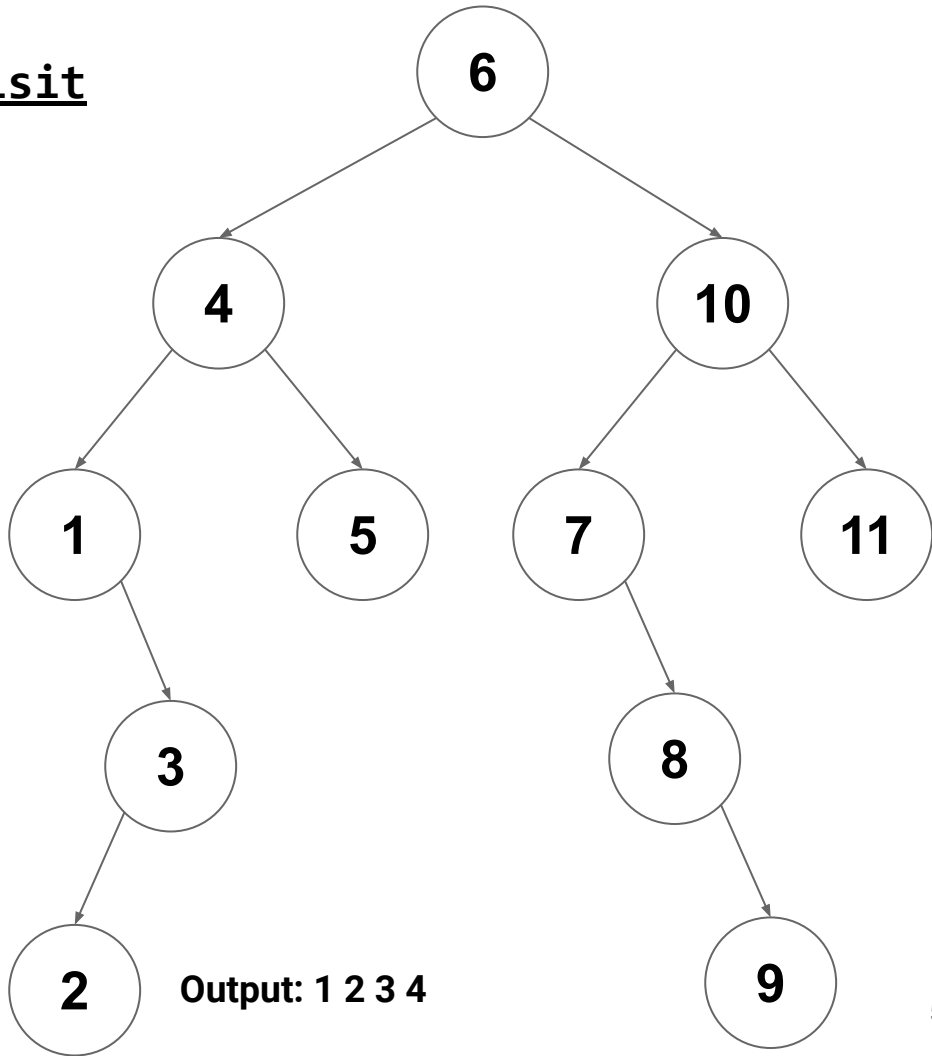
In-Order Traversal with an Iterator

next pops the stack (4)
and pushes the right
subtree

toVisit

6

5

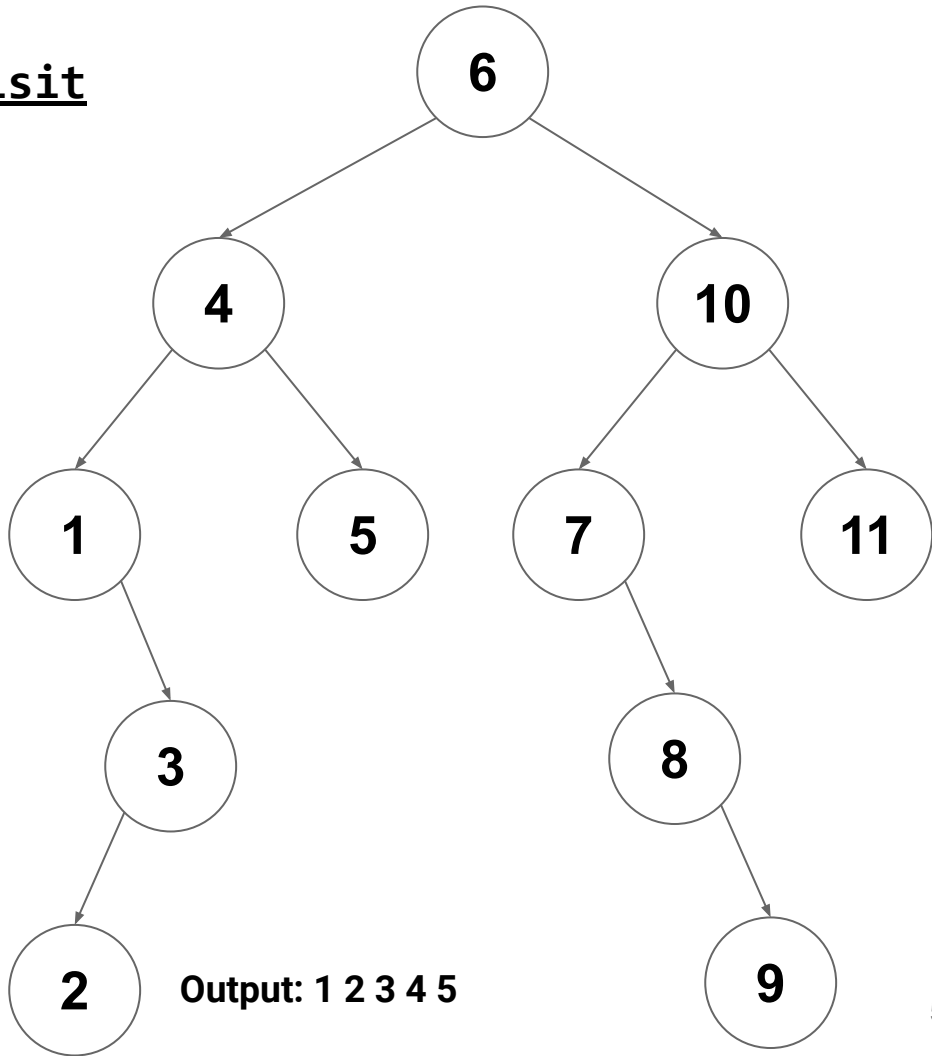


In-Order Traversal with an Iterator

next pops the stack (5)
and pushes the right
subtree (nothing)

toVisit

6



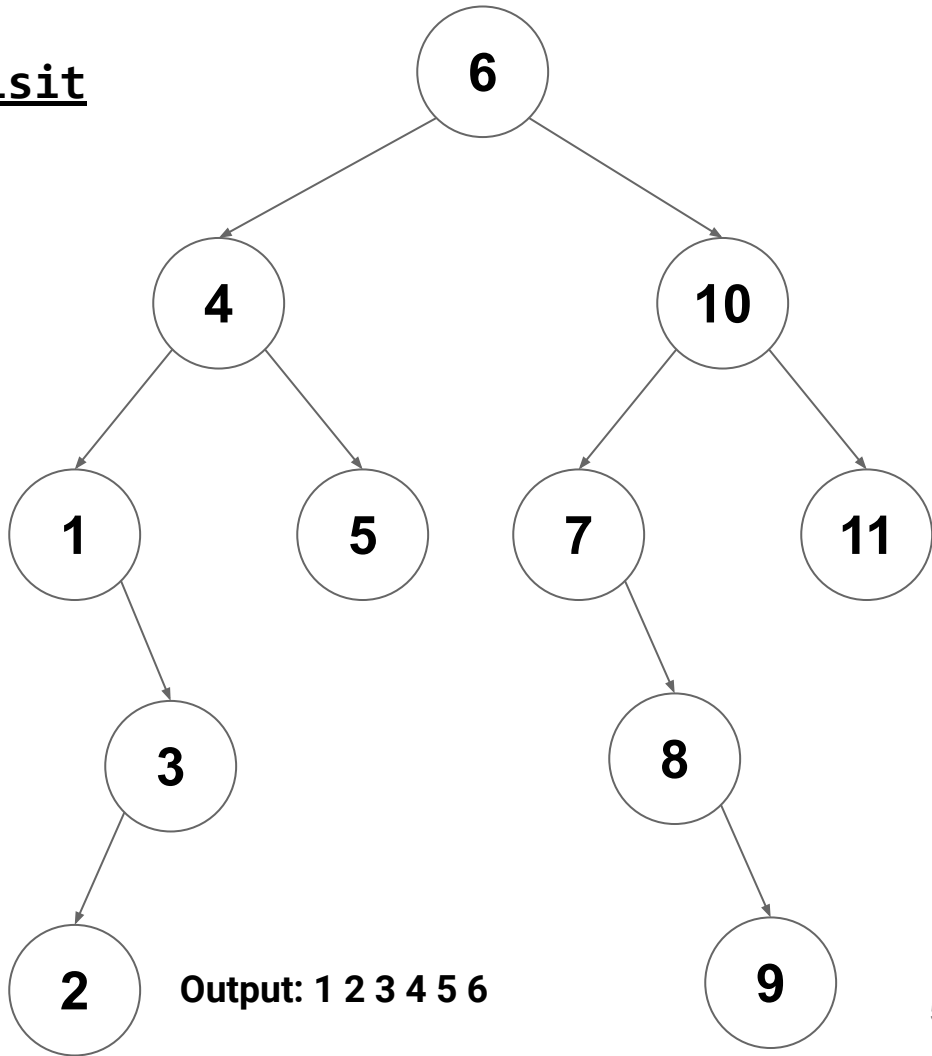
In-Order Traversal with an Iterator

next pops the stack (6)
and pushes the right
subtree (10 7)

toVisit

10

7



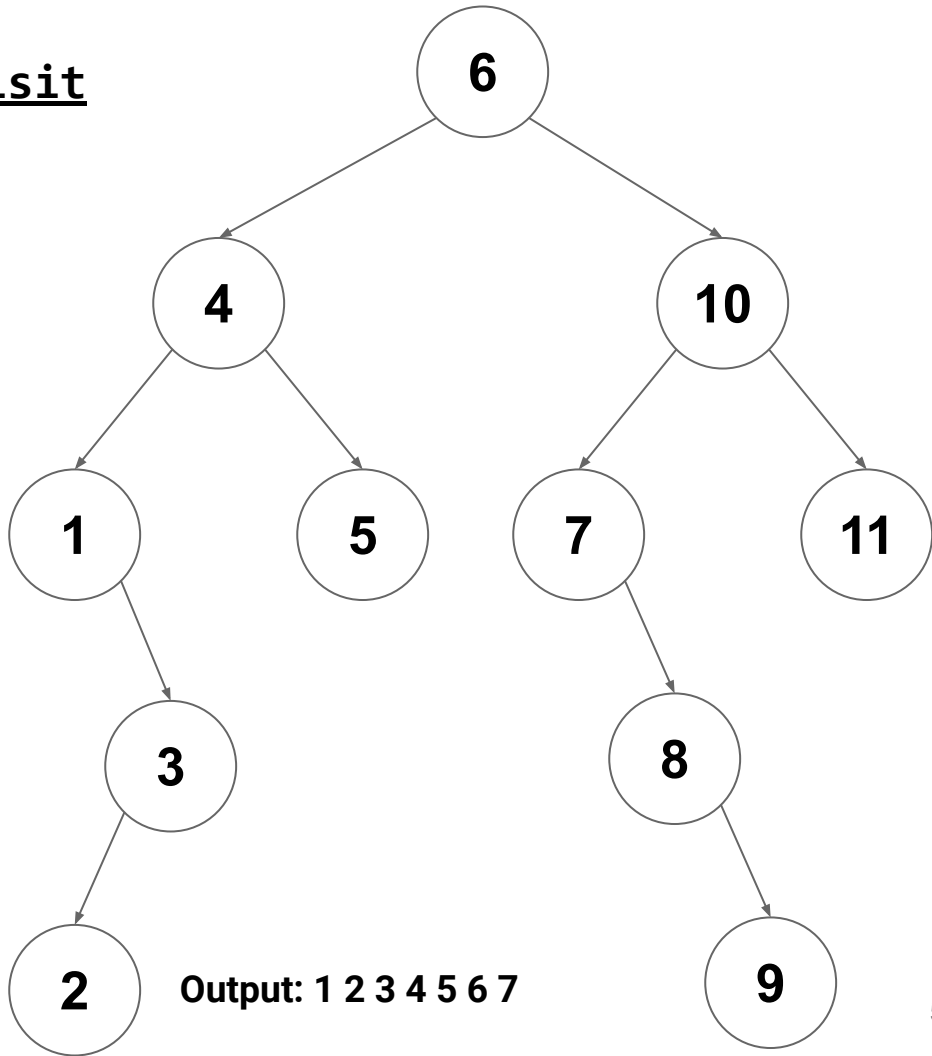
In-Order Traversal with an Iterator

next pops the stack (7)
and pushes the right
subtree (8)

toVisit

10

8



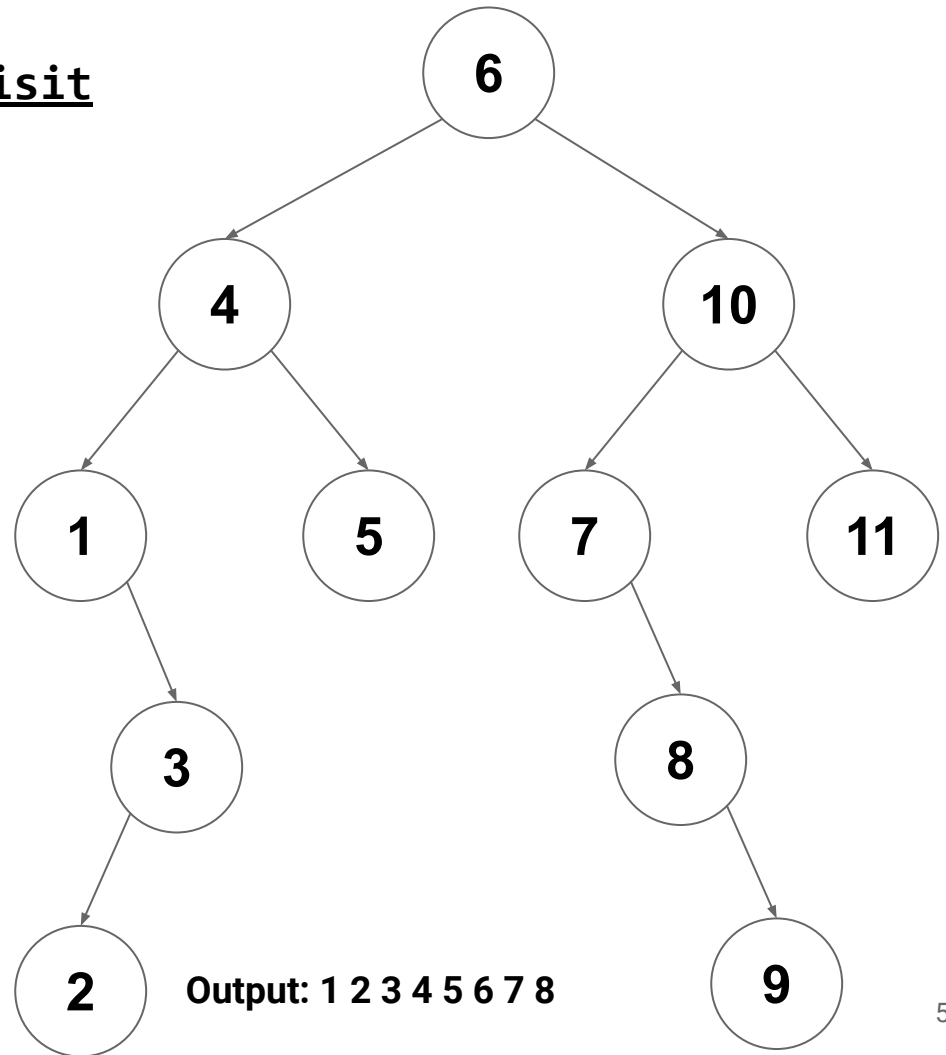
In-Order Traversal with an Iterator

next pops the stack (8)
and pushes the right
subtree (9)

toVisit

10

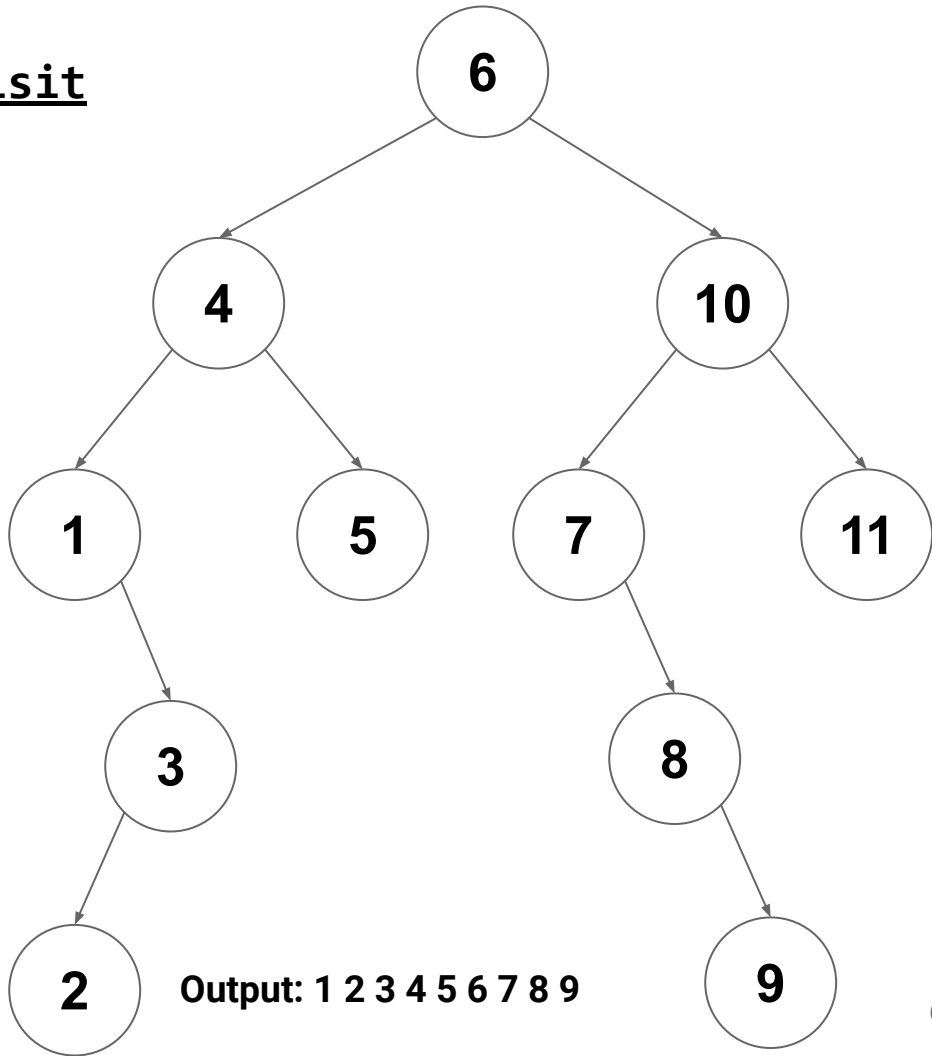
9



In-Order Traversal with an Iterator

next pops the stack (9)
and pushes the right
subtree (nothing)

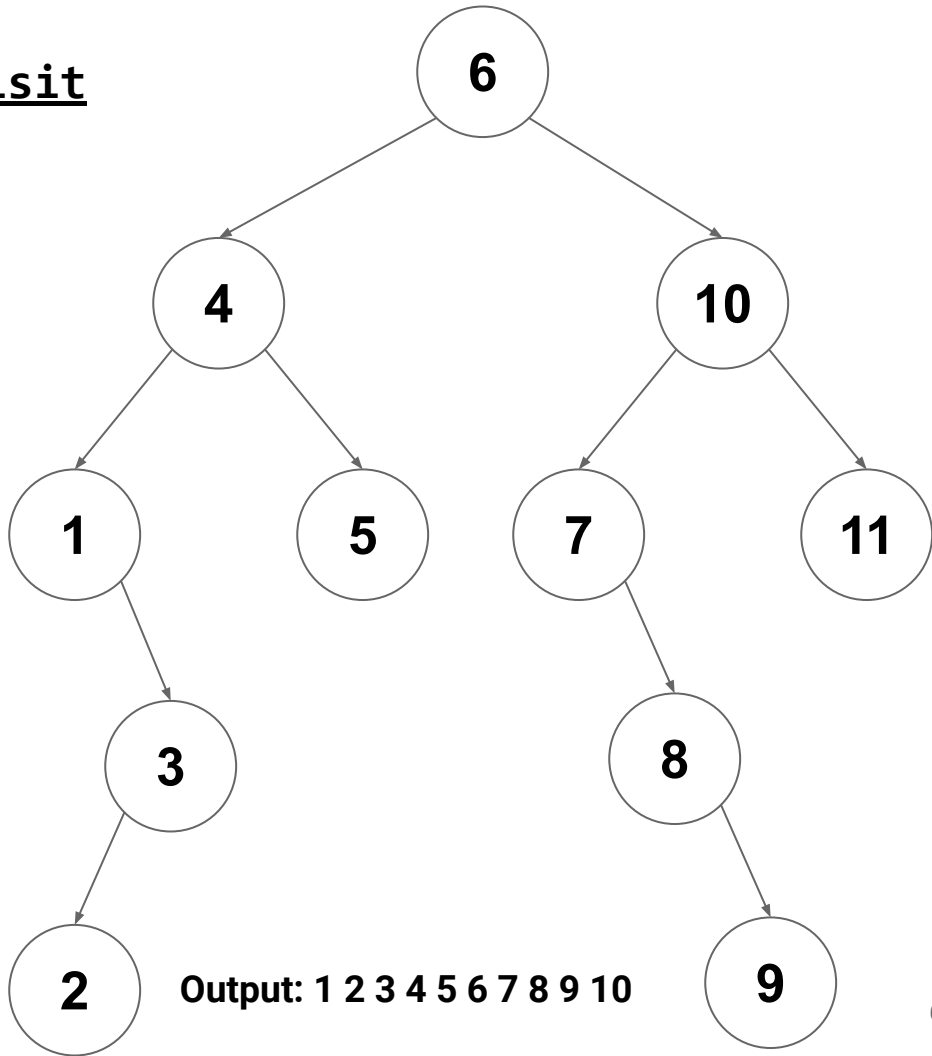
toVisit
10



In-Order Traversal with an Iterator

next pops the stack (10)
and pushes the right
subtree (11)

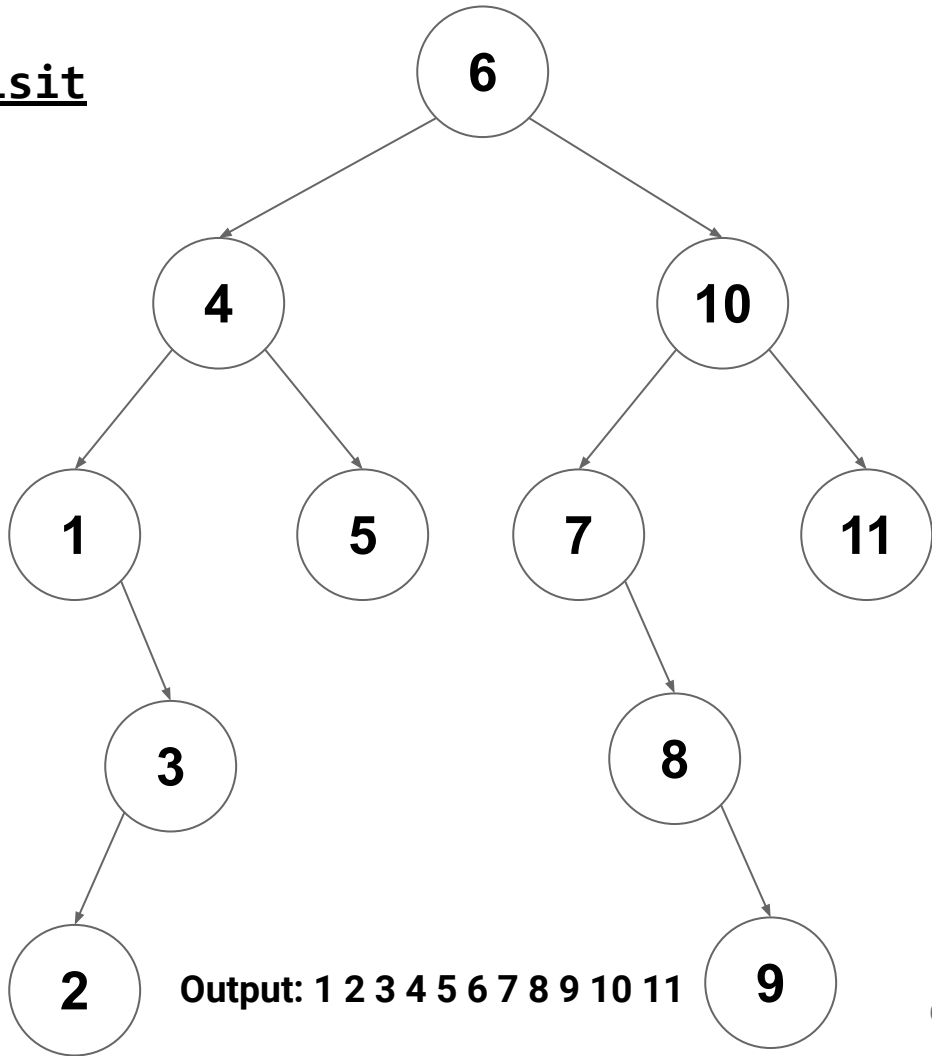
toVisit
11



In-Order Traversal with an Iterator

next pops the stack (11)
and pushes the right
subtree (nothing)

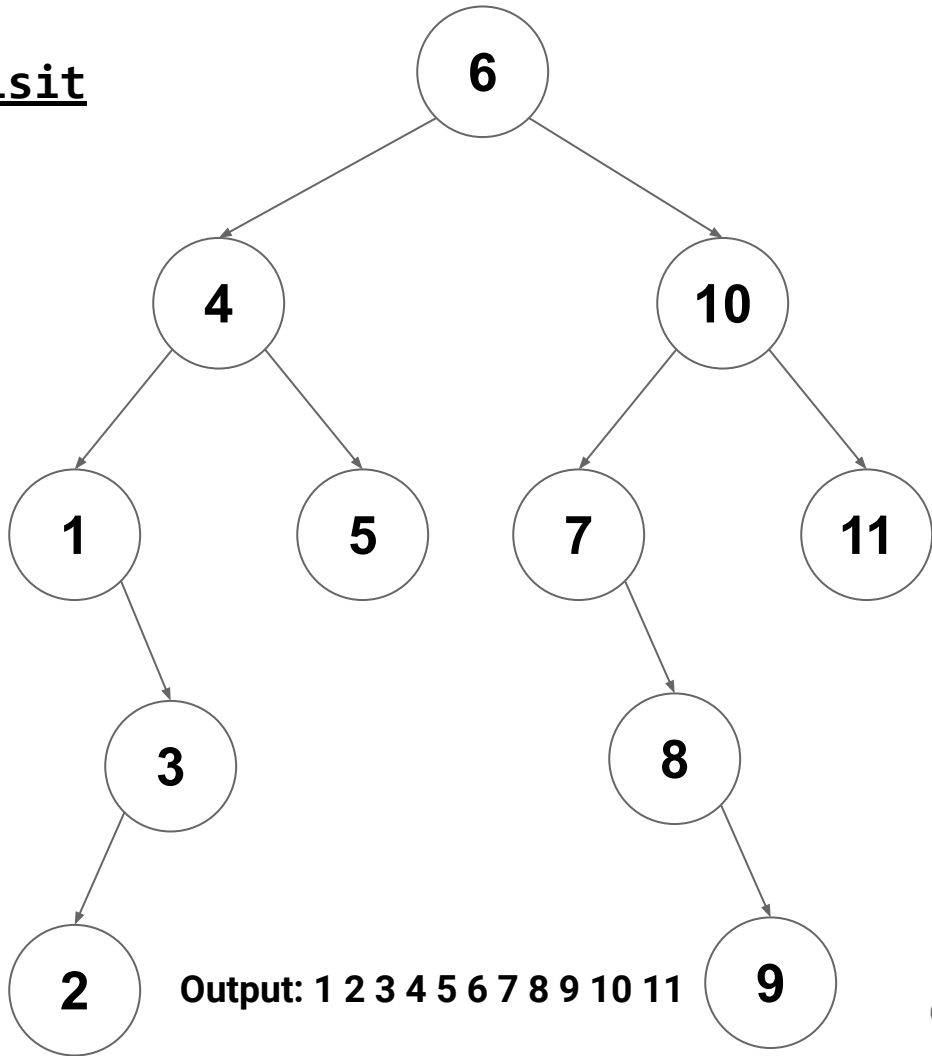
toVisit



In-Order Traversal with an Iterator

Our `toVisit` stack is empty, so `isEmpty` will now be true

toVisit



Complexity

```
1 TreeIterator() {  
2     toVisit = new Stack<>();  
3     pushLeft(root);  
4 }
```

What is our worst-case runtime to initialize the iterator?

Complexity

```
1 TreeIterator() {  
2     toVisit = new Stack<>();  
3     pushLeft(root);  
4 }
```

What is our worst-case runtime to initialize the iterator? $O(d)$

Complexity

```
1 TreeIterator() {  
2   toVisit = new Stack<>();  
3   pushLeft(root);  
4 }
```

What is our worst-case runtime to initialize the iterator? $O(d)$

(we may have to push as many as d nodes onto the stack)

Complexity

```
1 T next() {  
2   TreeNode<T> nextNode = toVisit.pop();  
3   pushLeft(nextNode.rightChild);  
4   return nextNode.value;  
5 }
```

What is our worst-case runtime to call next?

Complexity

```
1 T next() {  
2   TreeNode<T> nextNode = toVisit.pop();  
3   pushLeft(nextNode.rightChild);  
4   return nextNode.value;  
5 }
```

*What is our worst-case runtime to call **next**? $O(d)$*

*(we may have to push as many as **d** nodes onto the stack)*

Complexity

What is the worst-case complexity to visit ALL n nodes?

Complexity

What is the worst-case complexity to visit ALL n nodes?

Each node is at the top of the stack exactly once:

Complexity

What is the worst-case complexity to visit ALL n nodes?

Each node is at the top of the stack exactly once:

- One push **$O(1)$**

Complexity

What is the worst-case complexity to visit ALL n nodes?

Each node is at the top of the stack exactly once:

- One push $O(1)$
- One pop $O(1)$

Complexity

What is the worst-case complexity to visit ALL n nodes?

Each node is at the top of the stack exactly once:

- One push $O(1)$
- One pop $O(1)$

Total: $O(n)$

Balancing Trees

BST Operations

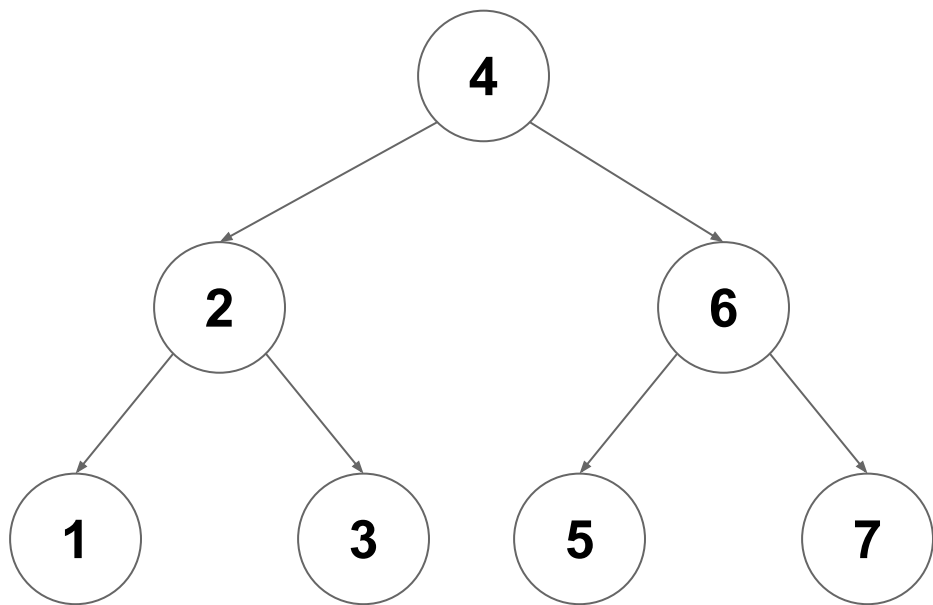
Operation	Runtime
<code>find</code>	$O(d)$
<code>insert</code>	$O(d)$
<code>remove</code>	$O(d)$

What is the runtime in terms of n ? $O(n)$

$$\log(n) \leq d \leq n$$

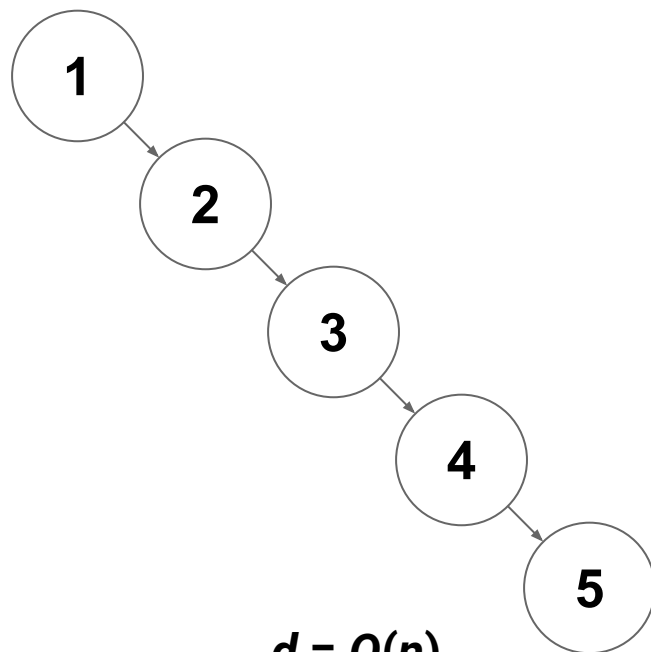
Tree Depth vs Size

If $\text{height}(\text{left}) \approx \text{height}(\text{right})$



$$d = O(\log(n))$$

If $\text{height}(\text{left}) \ll \text{height}(\text{right})$



$$d = O(n)$$

Balanced Trees

Balanced Trees are good: Faster find, insert, remove

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What do we mean by balanced?

Balanced Trees

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What do we mean by balanced? **$|\text{height}(\text{right}) - \text{height}(\text{left})| \leq 1$**

Balanced Trees

Balanced Trees are good: Faster `find`, `insert`, `remove`

What do we mean by balanced? $|\text{height}(\text{right}) - \text{height}(\text{left})| \leq 1$

How do we keep a tree balanced?

Balanced Trees - Two Approaches

Option 1

Keep left/right subtrees within **+/-1** of each other in height

(add a field to track amount of "imbalance")

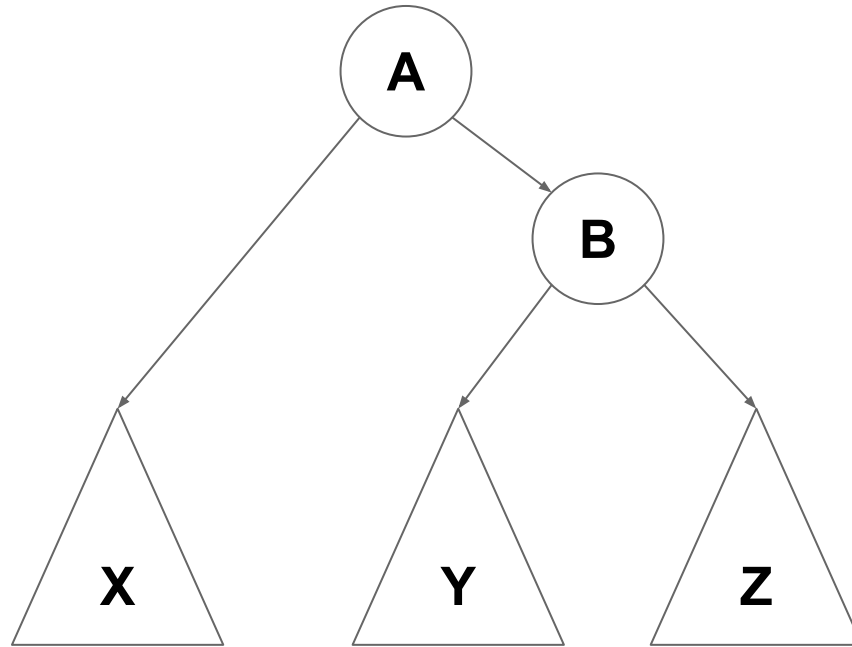
Option 2

Keep leaves at some minimum depth (**$d/2$**)

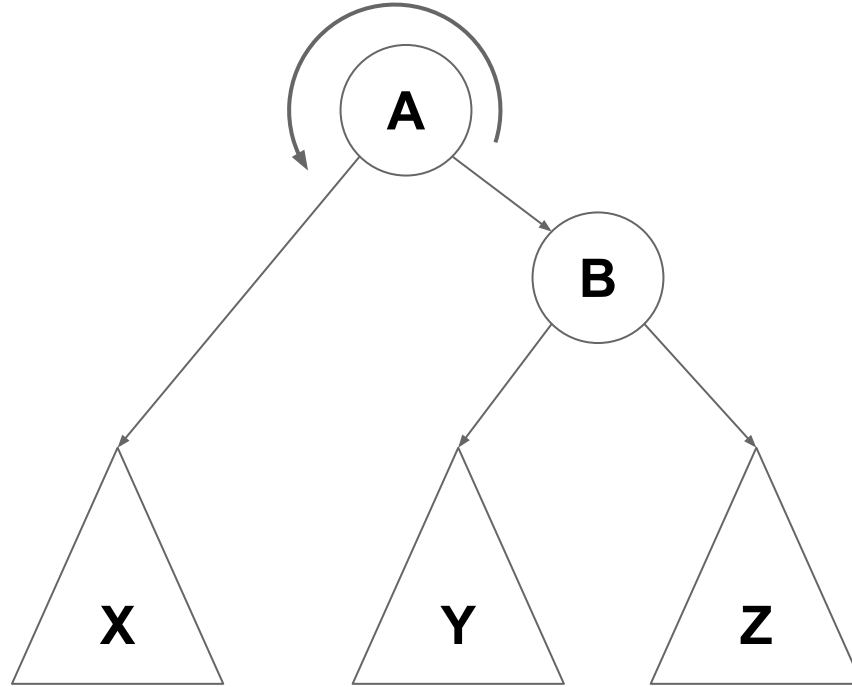
(Add a color to each node marking it as "red" or "black")

**Ok...but how do we enforce
this...?**

Rebalancing Trees (rotations)

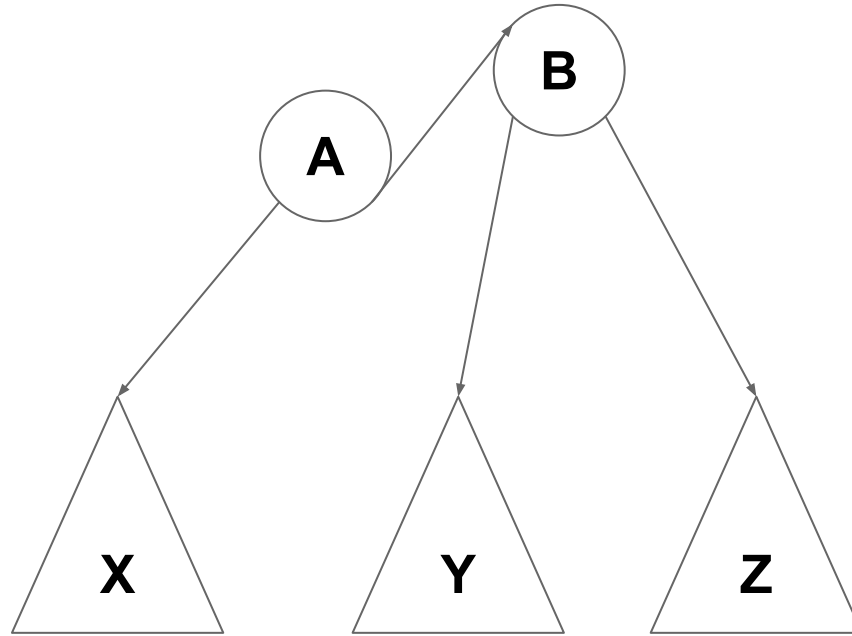


Rebalancing Trees (rotations)



Rotate(A, B)

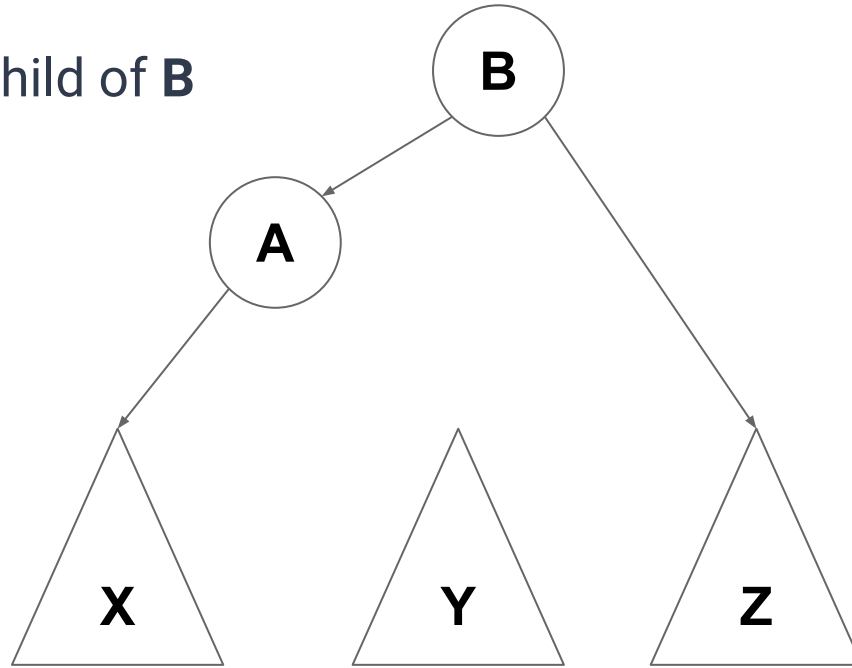
Rebalancing Trees (rotations)



Rotate(A, B)

Rebalancing Trees (rotations)

Make **A** the left child of **B**

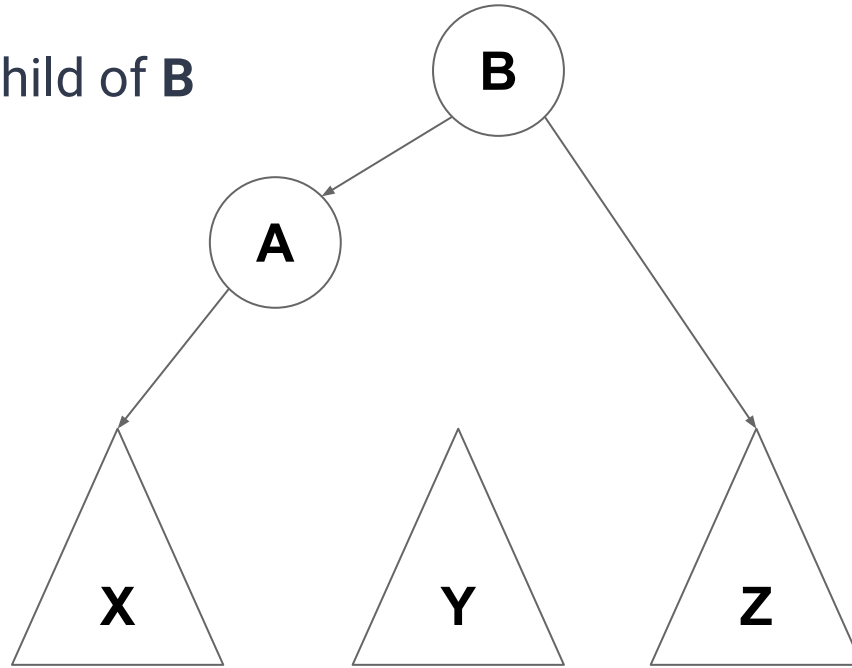


Rotate(A, B)

Rebalancing Trees (rotations)

Make **A** the left child of **B**

What about **Y**?



Rotate(A, B)

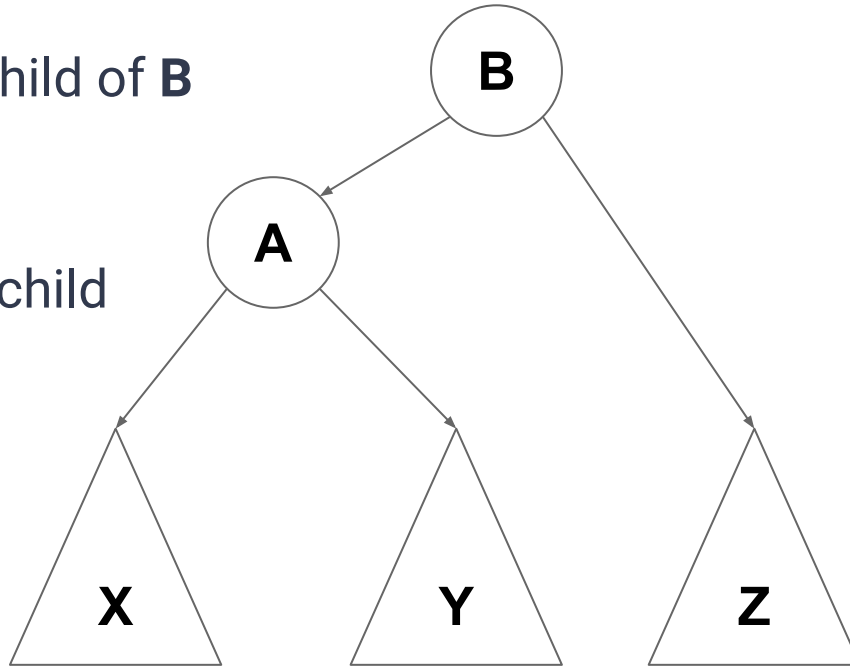
Rebalancing Trees (rotations)

Make **A** the left child of **B**

What about **Y**?

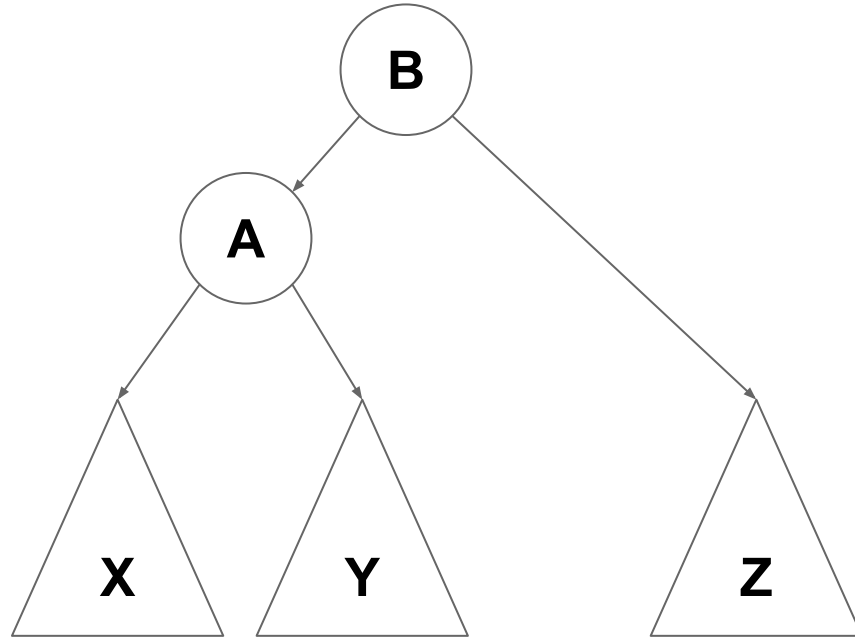
Make it the right child

of **A**



Rotate(A, B)

Rebalancing Trees (rotations)

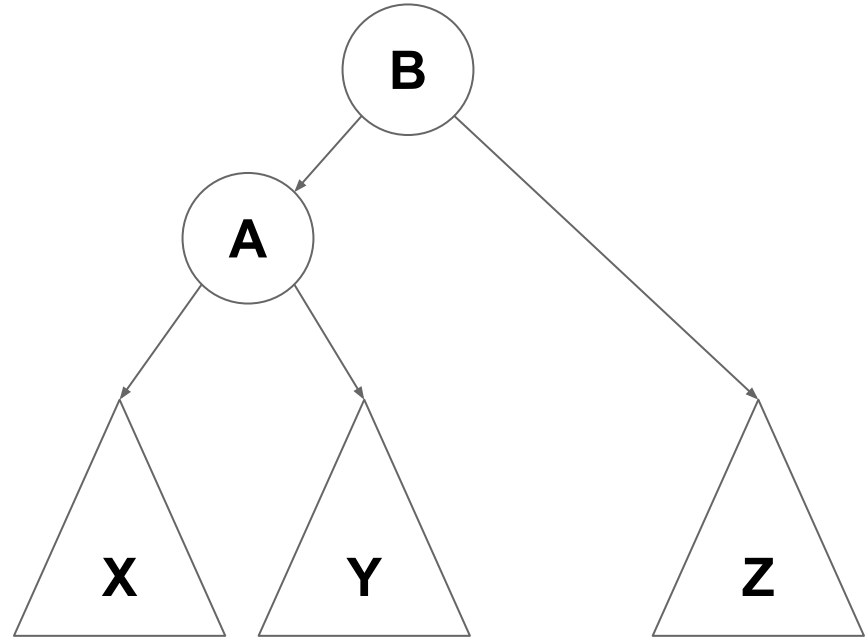


Rotate(A, B)

Rebalancing Trees (rotations)

A became **B**'s left child

B's left child became **A**'s right child



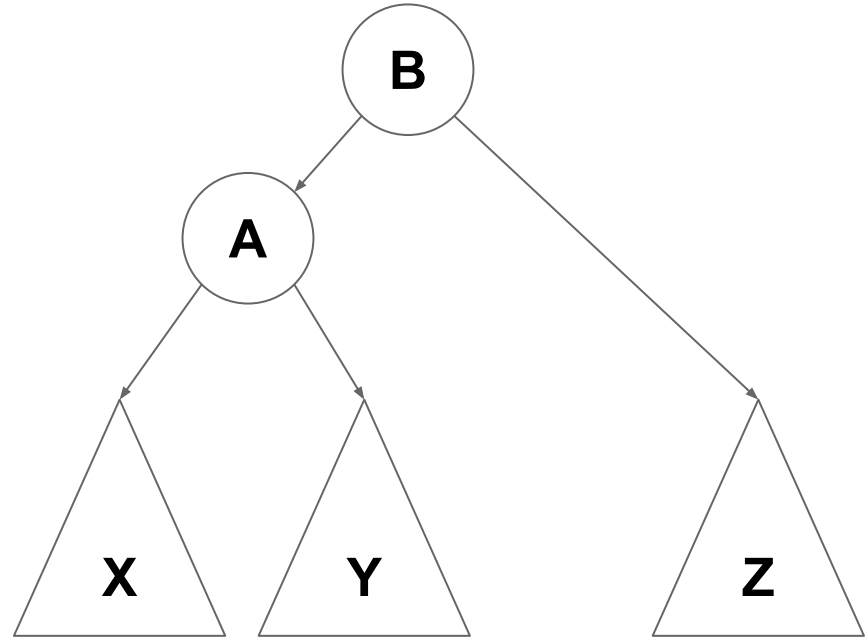
Rotate(A, B)

Rebalancing Trees (rotations)

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Is ordering maintained?



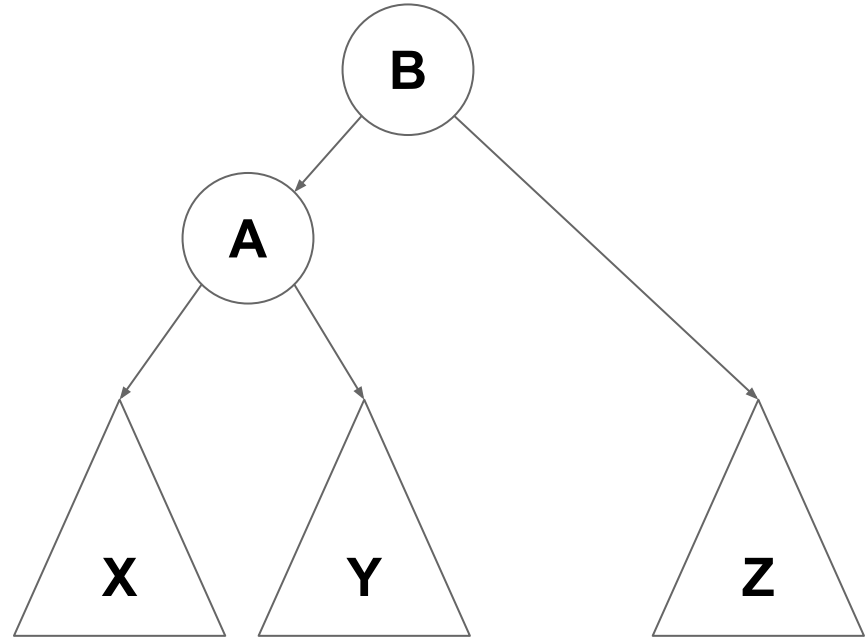
Rotate(A, B)

Rebalancing Trees (rotations)

A became **B**'s left child

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Is ordering maintained? Yes!



Rotate(A, B)

Rebalancing Trees (rotations)

A became **B**'s left child

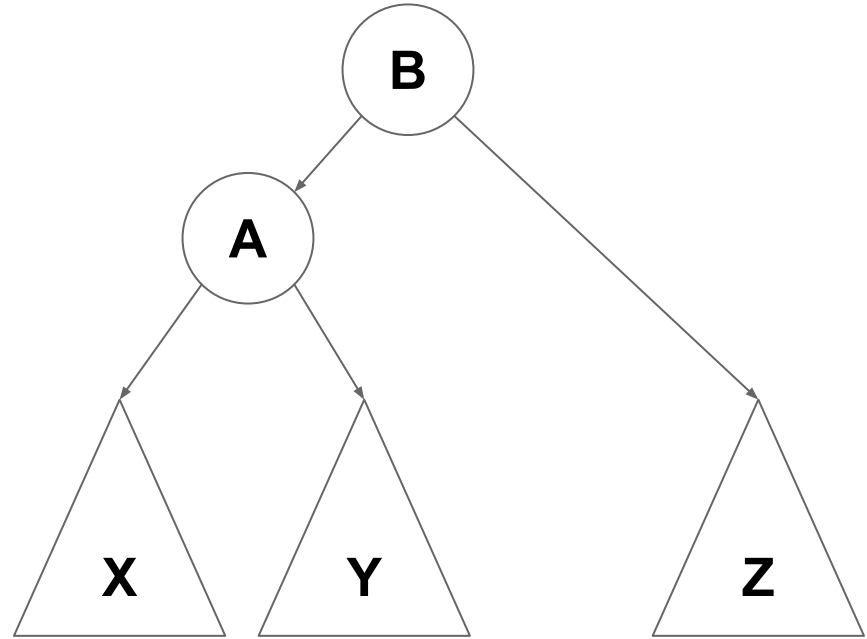
B's left child became **A**'s right child

Is ordering maintained? Yes!

B used to be the right child of **A**

Therefore **B** is bigger than **A**

Therefore **A** is smaller than **B** ✓



Rotate(A, B)

Rebalancing Trees (rotations)

A became **B**'s left child

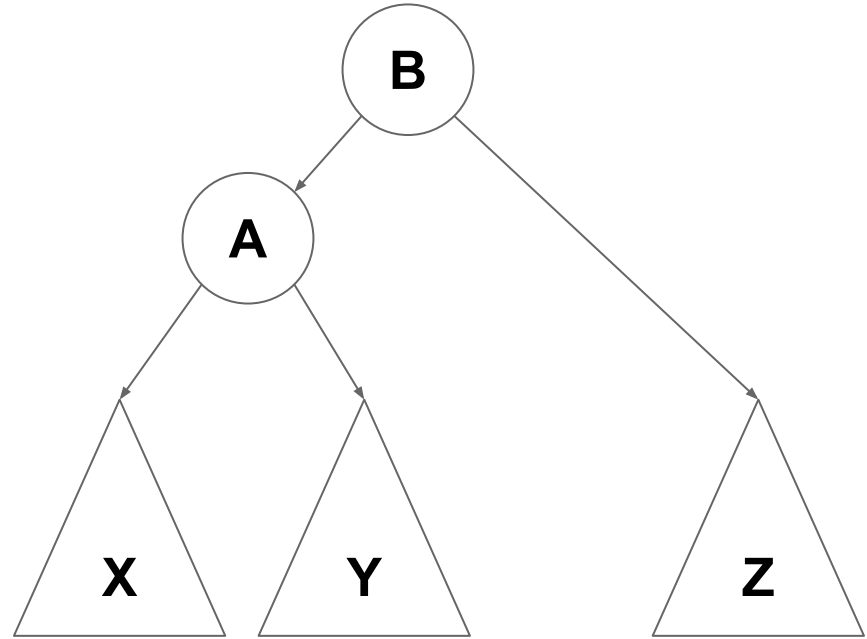
B's left child became **A**'s right child

Is ordering maintained? Yes!

Y used to be in the left subtree of **B**

Therefore **Y** is smaller than **B**

It is still left of **B** ✓



Rotate(A, B)

Rebalancing Trees (rotations)

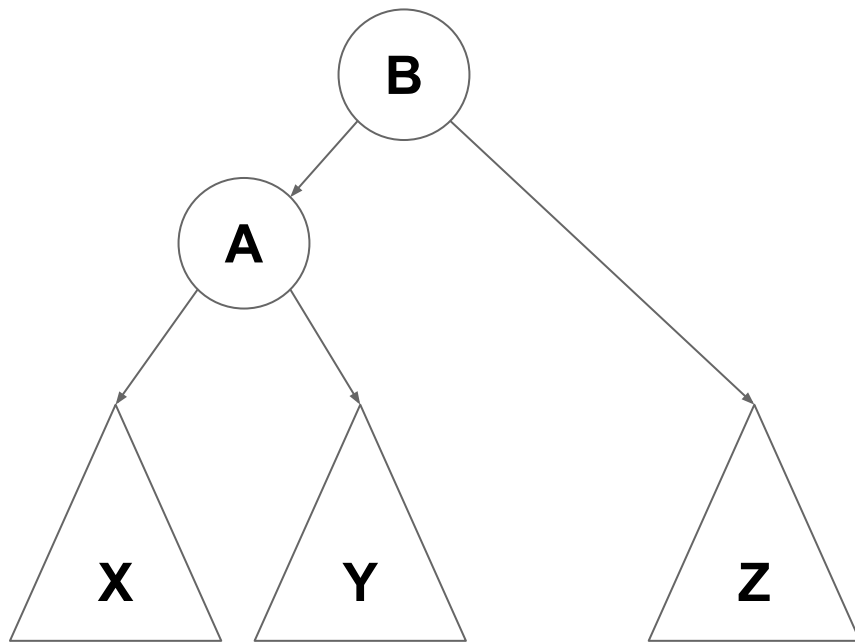
A became **B**'s left child

B's left child became **A**'s right child

Is ordering maintained? Yes!

Y used to be in the right subtree of **A**

It is still in the right subtree of **A** ✓



Rotate(A, B)

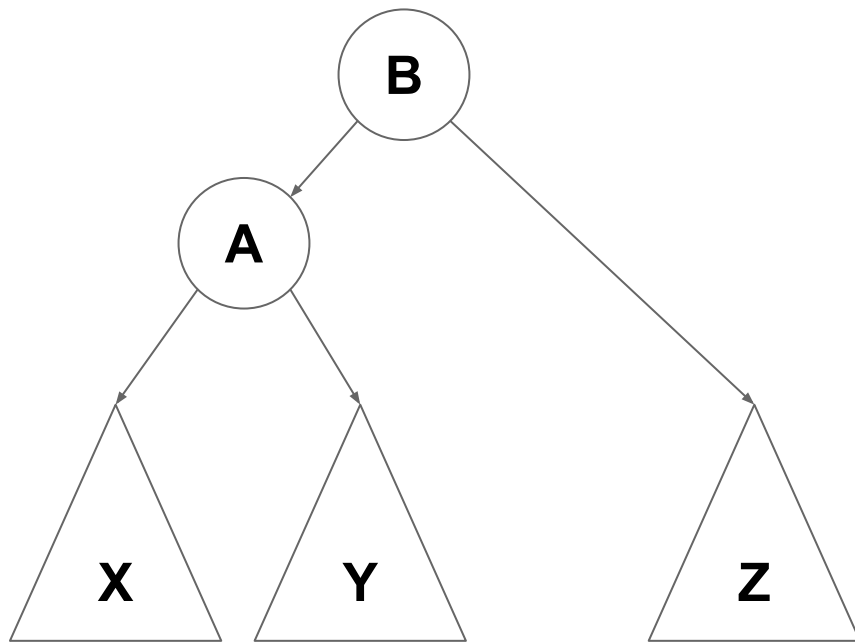
Rebalancing Trees (rotations)

A became **B**'s left child

B's left child became **A**'s right child

Is ordering maintained? Yes!

Complexity?



Rotate(A, B)

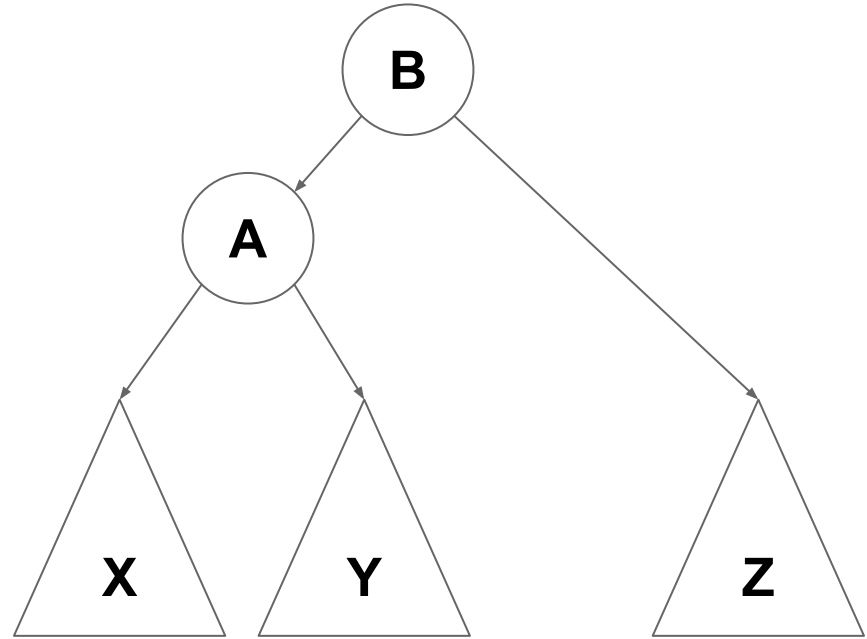
Rebalancing Trees (rotations)

A became **B**'s left child

B's left child became **A**'s right child

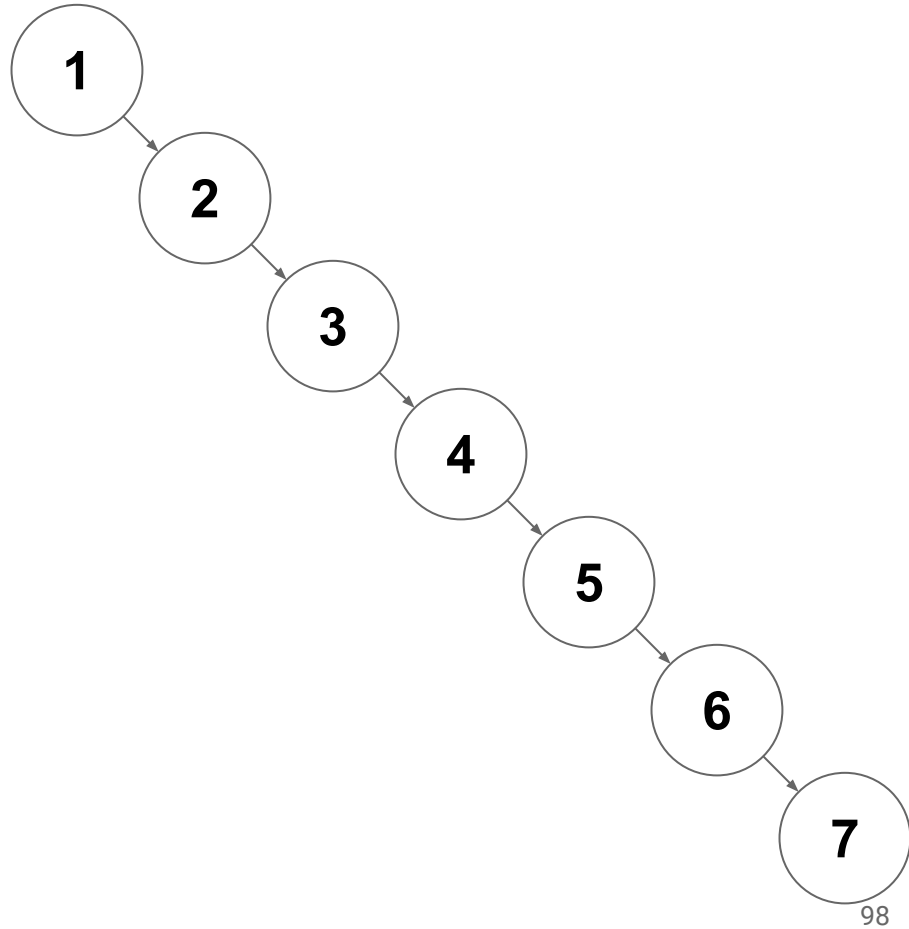
Is ordering maintained? Yes!

Complexity? $O(1)$



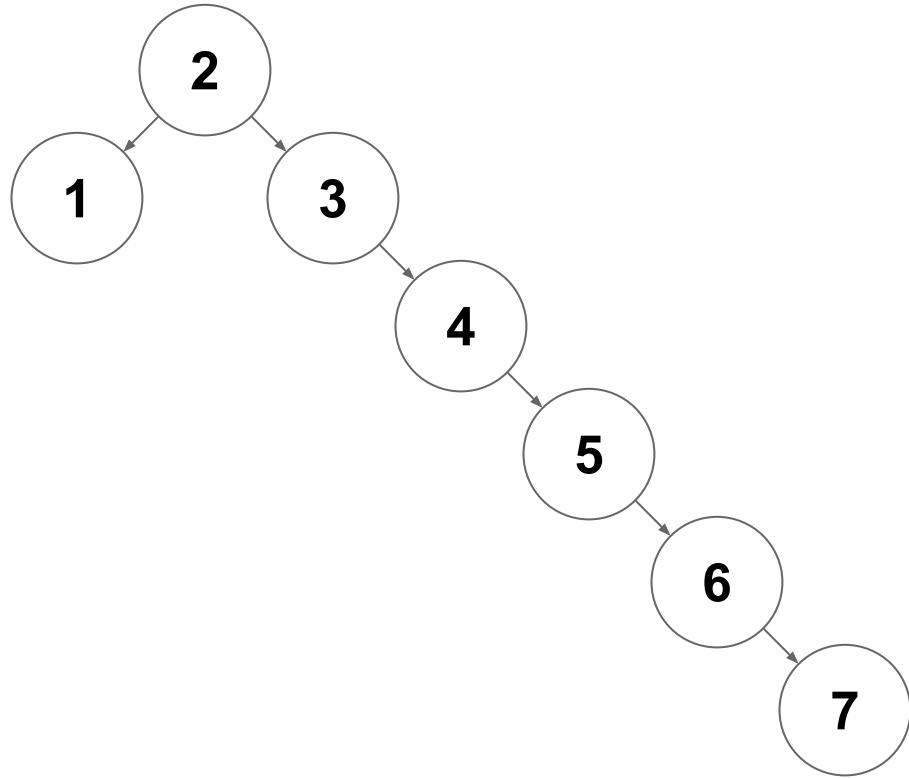
Rotate(A, B)

Rebalancing Trees



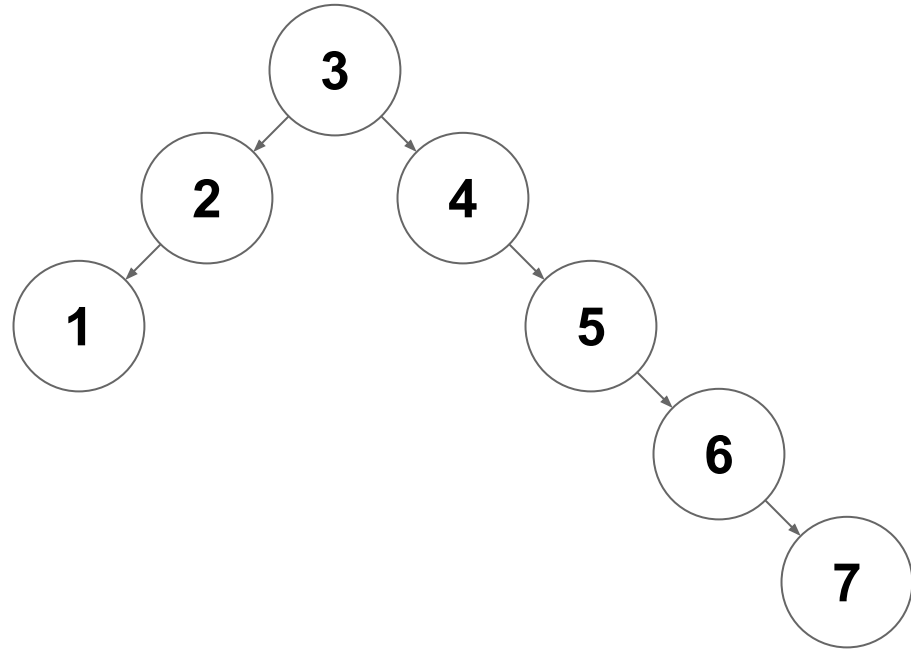
Rebalancing Trees

`Rotate(1,2)`



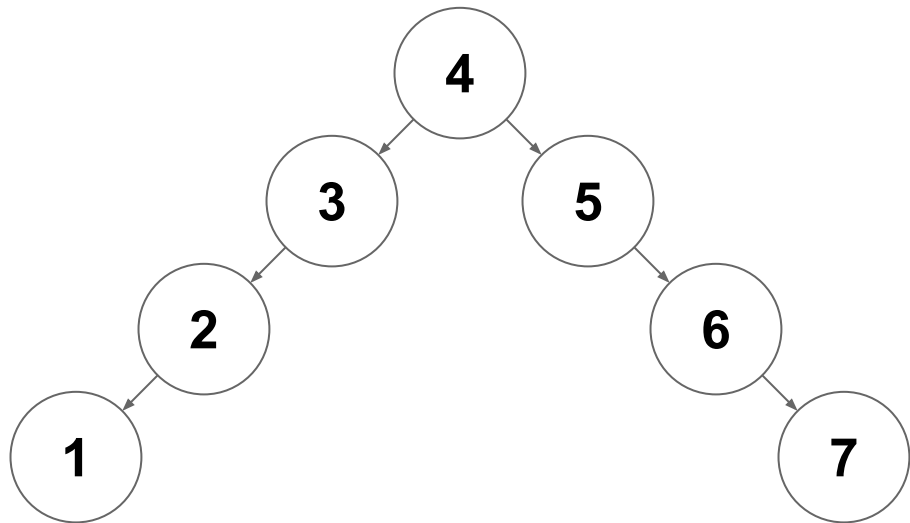
Rebalancing Trees

Rotate(2,3)



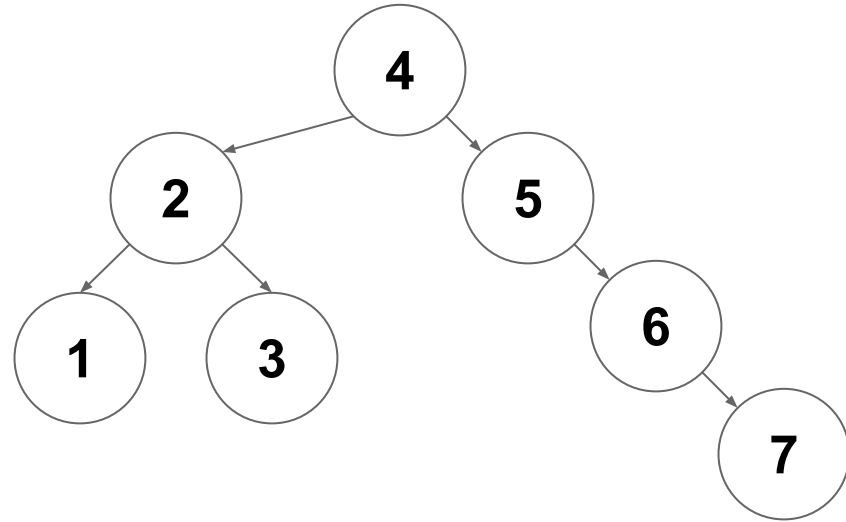
Rebalancing Trees

Rotate(3,4)



Rebalancing Trees

Rotate(3,2)



Rebalancing Trees

Rotate(5,6)

