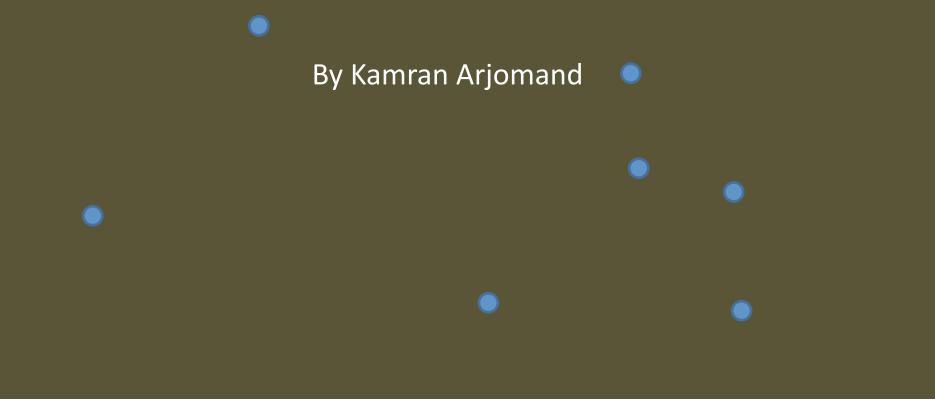
LAGRANGIAN PARTICLE TRACKING IN ISOTROPIC TURBULENT FLOW VIA HOLOGRAPHIC AND INTENSITY BASED STEREOSCOPY





Outline

I. Background

- A. Holographic Imaging
 - 1. Acquire Hologram
 - 2. Preprocessing
 - 3. Numerical Reconstruction
 - 4. Particle Extraction
 - 5. Velocity Extraction
- B. Turbulence

- A. Holographic Simulation with Gaussian Blur
- B. Single particle holographic image and intensity based image correspondence
- c. Single particle velocity calculation at given time step
- M. Additional Goals if time permits
 - A. Multiple Particle Image Correspondence
 - B. Multiple Velocity Particle Extraction
 - c. Particle Matching for a non-uniform particle field
- IV. References



Holography

- Concept of using a wave front imaging to do a three dimensional reconstruction first introduced by (Gabor, 1949)
- After introduction of the laser in the 1960's did holography really start to flourish(Collier ,1971;Vikram,1992).
- I. Film Based Holography
 - A. Intensity only reconstruction
 - B. Time consuming to reconstruct Holograms from Film
- II. Digital Holography
 - A. Easier acquisition of Data analysis (Intensity as well as complex amplitude)
 - B. Resolution restricted due to angular aperture as well as size

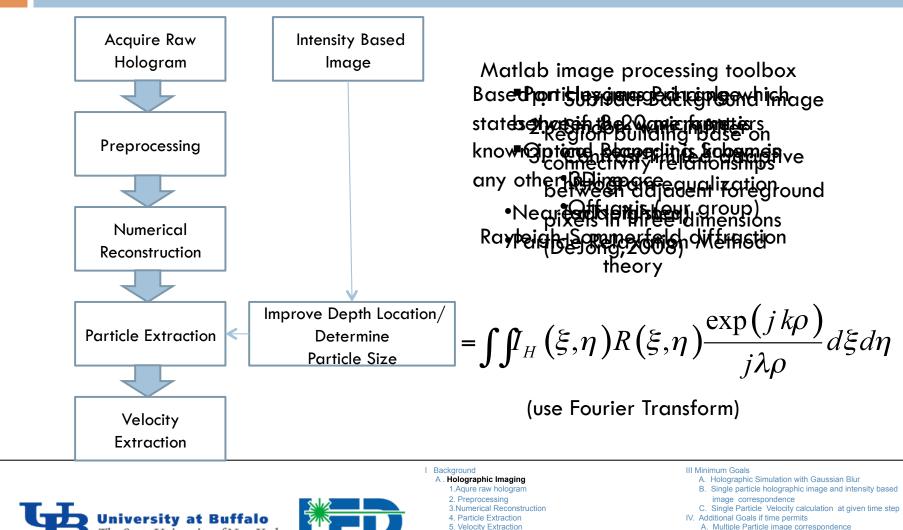




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- B. Multiple Particle matching by
- Neighbor V. References

Digital holographic Process



B. Turbulence

The State University of New York

- A. Multiple Particle image correspondence
- B. Multiple Particle matching by
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Raw Hologram



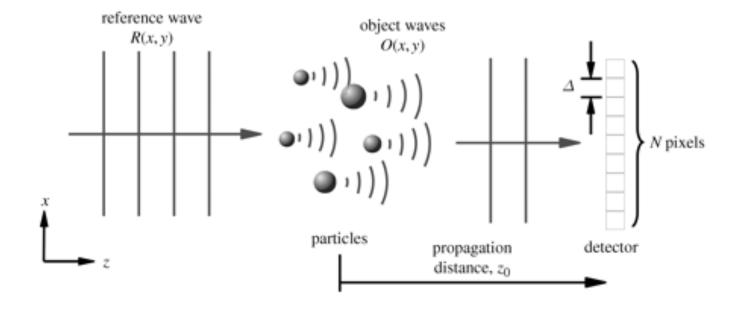




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Raw Hologram Acquisition





V. References

Angular Aperture

• angular aperture is a function of the camera pixel size, Δ , and the image size, a function of the number of pixels, *N*. Given the system parameters: ,

$$\Omega = \begin{cases} \frac{H}{2z} & if \Delta \leq \Delta_c \\ \\ \frac{\lambda}{2\Delta} & if \Delta \geq \Delta_c \end{cases}$$

Critical Pixel Size:
$$\Delta_c = \frac{\lambda z}{H} = \sqrt{\frac{\lambda z}{N}}$$

• Our CCD camera is 2650x2650 pixels with an effective pixel size of 2 micrometers with a long distance microscopic lens system

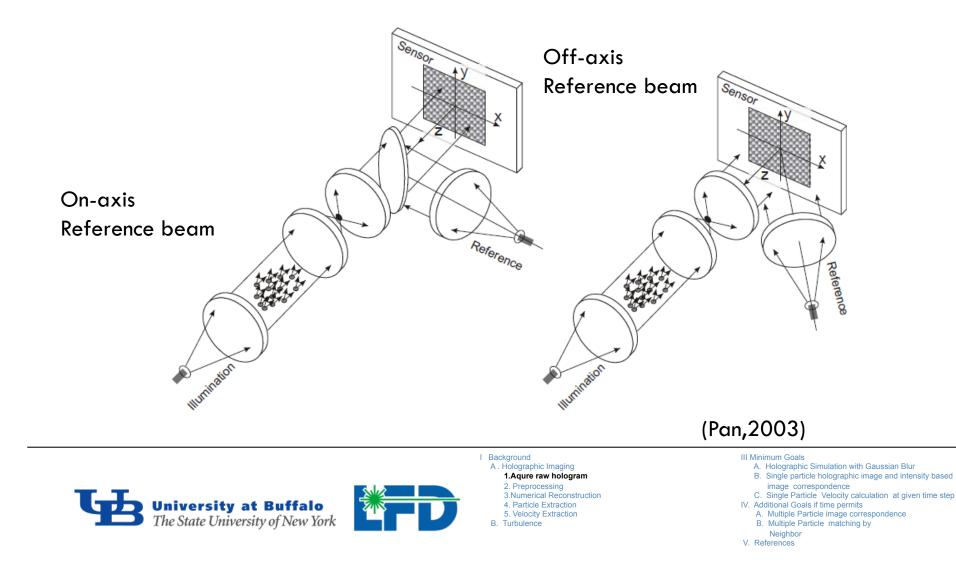




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In-Line Recording Object Beam Configurations



Advantages/Disadvantages of In-line

Advantages

- Greater Intensity Hologram
- Complex amplitude Particle Extraction
- Potential for particle size determination

Disadvantages

- Excessive Speckle Noise from particles outside of region of interest resulting in large depth resolution errors
- Low Particle Seeding Density

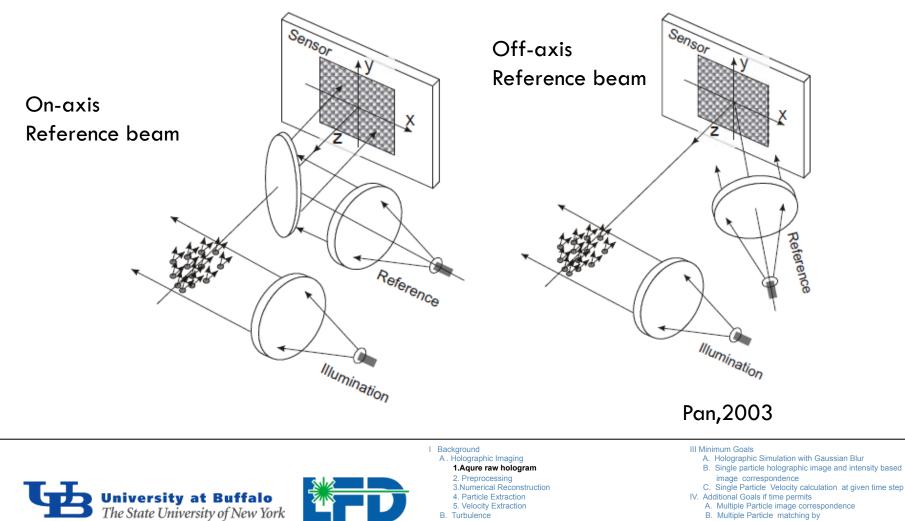




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Off-Axis Recording Object Beam Configurations



- B. Multiple Particle matching by
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Advantages/Disadvantages of Hybrid Holographic Recording

Advantages

- Speckle Noise suppression resulting from smaller imaged region
- Lower resolution requirement then off-axis reference wave configuration
- Facilities with higher particle concentrations can be imaged
- More accurate z location

Disadvantages

• No complex amplitude particle extraction methods

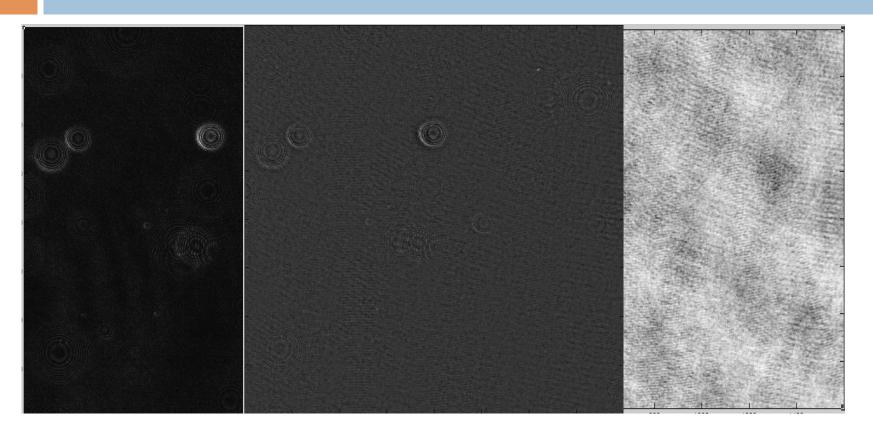




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Subtraction with Background Image



Raw Hologram

Image after



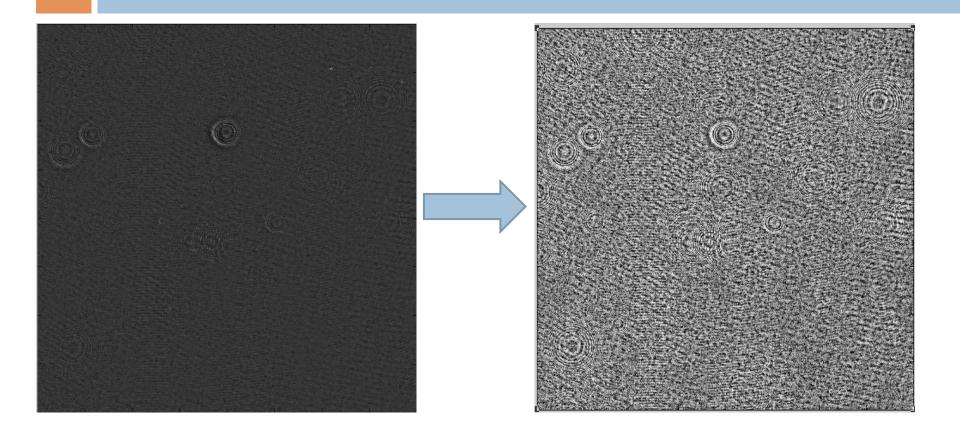


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Background Image

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Contrast-limited adaptive histogram equalization and Imfilter







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Holography with on-axis reference wave

$$I_{H} = \left| \mathbf{R} \right|^{2} + \left| \mathbf{O} \right|^{2} + 2 \left| \mathbf{R} \right| \cdot \left| \mathbf{O} \right| \cdot \cos \left(\frac{\pi r^{2}}{\lambda z_{0}} + \varphi \right)$$

- R= reference wave
- O=object wave
- Z= distance from focus plane
- r = radial coordinate in the hologram recording system
- λ = wavelength
- $\varphi = \mathsf{phase} \mathsf{shift}$





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Numerical Reconstruction (Direct Method(Takaki,1999))

$$U(x, y, z) = \int \int I_{H}(\xi, \eta) R(\xi, \eta) \frac{\exp(jk\rho)}{j\lambda\rho} d\xi d\eta$$

Fourier Transforms:

$$U(x, y, z) = \Im^{-1} \left\{ \Im \left[I_H(\xi, \eta) \cdot R(\xi, \eta) \right] \cdot \Im \left[k_z(u, v) \right] \right\}$$

Diffraction kernel

$$k_{z}(x, y, z) = \frac{1}{j\lambda} \cdot \frac{\exp(jk\sqrt{x^{2} + y^{2} + z^{2}})}{\sqrt{x^{2} + y^{2} + z^{2}}}$$
$$K_{z}(m, n) = \exp\left[-j\frac{2\pi z}{\lambda}\sqrt{1 - \left(\frac{\lambda m}{N_{x}\Delta_{x}}\right)^{2} - \left(\frac{\lambda n}{N_{y}\Delta_{y}}\right)^{2}}\right]$$

Discrete Form

Fourier Transform $M_{n}^{f} = matrix^{j} indices^{j} kz \sqrt{1 - (\lambda u)^{2} - (\lambda v)^{2}}$ $N_{x}, N_{y} = number of pixels$ $\Delta_{x}, \Delta_{y} = pixel size in x an y directions$





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Particle Extraction

Particle Extraction using Intensity(PEI)

• Only available method for side scattering due to irregular distribution of scattered wave in side scattering

The intensity based centroid of the particle $(x_{p'}y_{p'}z_{p})$ is calculated from the relationships,

 $x_p = \frac{m_{100}}{m_{000}}, y_p = \frac{m_{010}}{m_{000}}, z_p = \frac{m_{001}}{m_{000}}$

where a moment of order (p+q+r) of the intensity *I* is given by,

$$m_{pqr} = \sum_{-\infty}^{\infty} \sum_{-\infty}^{\infty} \sum_{-\infty}^{\infty} i^{p} j^{q} k^{r} I(i, j, k)$$

(DeJong,2008)



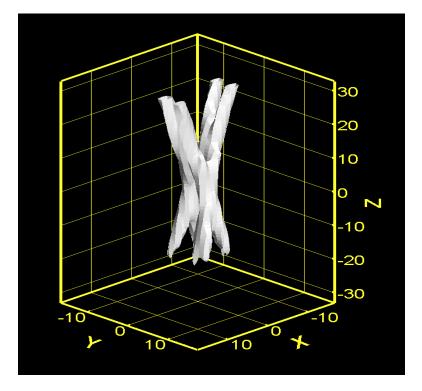


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Problems with particle centroid calculation



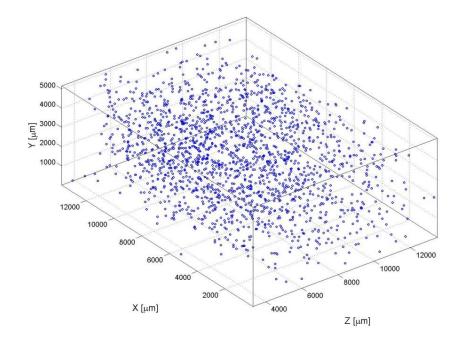




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3D Reconstructed Particle Field



(DeJong,2008)

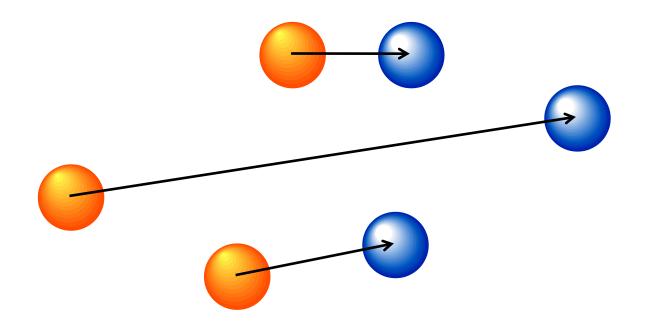


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Velocity Extraction

Nearest Neighbor(Ouellette, 2006)







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A. Multiple Particle image correspondence

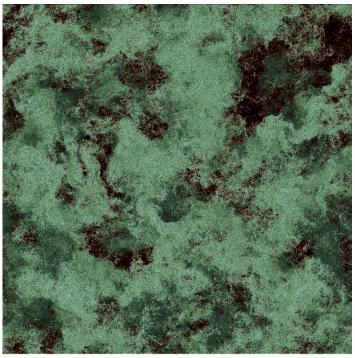
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What is Turbulence ?

- Rotational and Dissipative
- Non-linear
- Stochastic(random)
- diffusive









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Isotropic Turbulence

Singlepoint Velocity Correlations

$$\langle u^2 \rangle = \langle v^2 \rangle = \langle w^2 \rangle$$

 $\langle uv \rangle = \langle vw \rangle = \langle wu \rangle = 0$

Homogeneous Turbulence in which all the fluctuation statistics have no preferred directionality. All statistics are independent of coordinate rotations and reflections





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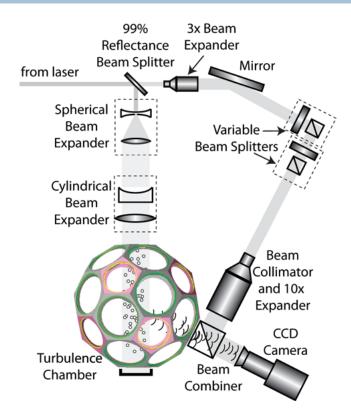
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My Research





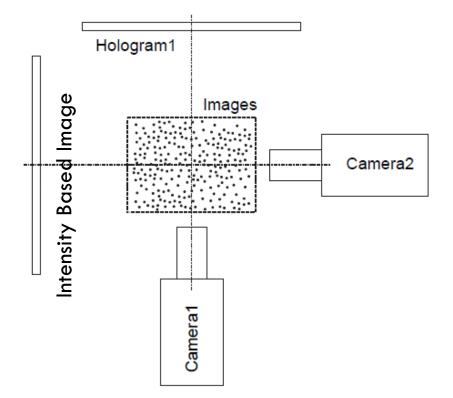


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For my experiment

(first assume perfectly orthogonal setup has been completed)



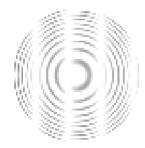




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Simulation of Holographic Particle (completed)





Synthesized Hologram Hologram after Gaussian Blurr

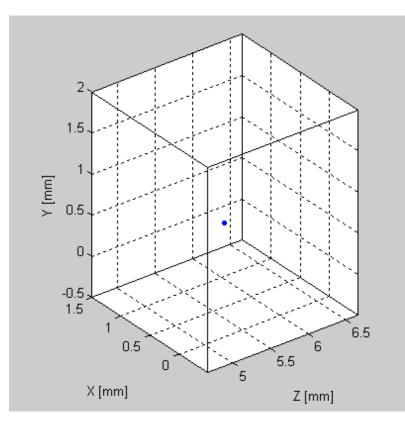




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Correspondence of Reconstructed Hologram with Intensity Based Image (currently working on)







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Other Minimum goals to be completed

- Determination of Particle Size via pixel count
- Simulate Movement of particles for a given Time Step





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Long Term Goals

- Multiple Particle Image Correspondence
- Multiple Particle Velocity Extraction
- Particle matching for a non-uniform particle field





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- V. References

References

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